

International Space Station Assembly Operations Book

ISS-2J/A

Mission Operations Directorate Operations Division

20 MAY 09







United Space Alliance

National Aeronautics and Space Administration

Lyndon B. Johnson Space Center Houston, Texas

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INTERNATIONAL SPACE STATION ASSEMBLY OPERATIONS BOOK ISS-2J/A

20 MAY 09

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SODF

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This document is under the configuration control of the Systems Operations Data File Control Board (SODFCB).

| | Incorporates the following: | | | | | | |
|-----|-----------------------------|-----------------|-----------------|----------------|--|--|--|
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| | Assy_Ops U1327 | Assy_Ops U1343 | Assy_Ops U1354 | | | | |

Uplinked Messages (or Approved Flight Notes) replaced by this revision, remove from Book:

None

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ACTIVATION AND CHECKOUT

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OBJECTIVE:

Monitor input current to Berthing Mechanism Electronics Package (BEP) to assess the bolting torque on the ground. The preparation task (steps 1 to 4) will be performed twice in parallel with BCDU ops in <u>1.102 ACTIVE EFBM OPS FOR JEF BERTHING</u>. The setup and current monitor task requires coordination working with EFBM operator.

LOCATIONS:

JPM1D7

DURATION:

60 minutes

10 minutes for preparation

10 minutes for setup

30 minutes for current monitor (in parallel with 1.102 ACTIVE EFBM OPS FOR JEF BERTHING)

10 minutes for closeout

CREW:

One

MATERIALS:

9V Alkaline Battery (if Battery change out required)

Telatemp temperature recorder decal

TOOLS:

Mini-Maglite (if required)

DCS 760 Camera

Scopemeter Power Adapter (SMPA)

Scopemeter and Accessories Kit:

Scopemeter P/N SEG39129678-303

Scopemeter Current Probe Kit:

Scopemeter Current Probe P/N SEG39130242-301

ISS IVA Toolbox:

Drawer 2:

5/32" Hex Head, 1/4" Drive

Ratchet, 1/4" Drive

(5-35 in-lbs) Trq Driver, 1/4" Drive

Drawer 3:

4" Common Tip Screwdriver (if Battery change out required)

REFERENCE PROCEDURE(S):

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1. ACCESS



Figure 1. JPM1D7-08 Area Hazardous Equipment Location.

WARNING

- Vacuum Vent Pneumatic Valve (VVPV) may have hot surface. Care must be taken when accessing EFBM Power cable to prevent injury.
- 2. Metal flexible hose for VVPV may have sharp edges. Care must be taken when accessing EFBM Power cable to prevent injury.

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JPM1D7 1.1 Remove Closeout Panel JPM1D7-08, fasteners (nineteen) (Ratchet, 1/4" Drive; 5/32" Hex Head, 1/4" Drive). Temporarily stow. Refer to Figure 1.



Figure 2. EFBM Power Cable Location (with Velcro).

1.2 Untie Velcro from cables. Refer to Figure 2.

2. SETUP SCOPEMETER AND CURRENT PROBE



exposure to 49 degree C

Figure 3. Telatemp Temperature Recorder Decal (before, after exposure to 49 degrees C).

2.1 Locate Telatemp decal on Scopemeter and Scopemeter Current Probe.

If decal indicates exposure to 49 degrees C (120 degrees F) or more, do not use scopemeter and inform **SSIPC**. Refer to Figure 3.



Figure 4. Scopemeter Current Probe Connected to Scopemeter INPUT A.

2.2 Scopemeter Current Probe $\rightarrow \mid \leftarrow$ INPUT A (red) on Scopemeter Refer to Figure 4.

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- Select 100mV/A on Scopemeter Current Probe using probe slide switch. Refer to Figure 5.
- 2.4 Verify Scopemeter Current Probe ON indicator illuminated (good Current Probe Battery indication).

If no light ON or dim,

Replace Scopemeter Current Probe Battery (9V Battery) by removing captive screw on back of probe (4" Common Tip Screwdriver).

3. CURRENT MONITOR PREPARATION





Figure 6. Current Monitor Configuration.

- 3.1 Grip Scopemeter Current Probe, open jaws.
 Place wire EFBM Power Cable in notch of Scopemeter Current Probe, close jaws.
 Verify Current Flow Arrow orientation is as shown in Figure 6.
- 4. CONFIGURING SCOPEMETER
 - 4.1 <u>Powering On Scopemeter</u> While holding down F5 Press and release ON/OFF.

Listen for two beeps, release F5.

4.4

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4.2 <u>Configuring Scopemeter Input A</u>

Press INPUT A. Press F5 (PROBE A MENU). Press F5 (SELECT ITEM). Use blue arrow keys to scroll down and highlight "100 mV/A." Press F5 (SELECT ITEM). Press F1 (CLOSE). Press SCOPEMETER (to return to main menu).

NOTE

Probe should not be used to measure current on more than one wire at a time.

 4.3 <u>Zeroing Scopemeter Current Probe</u> Leave jaws closed. Use thumbwheel on top of probe to zero probe. Verify on Scopemeter Display (±0.005) on "A DC" scale.

<u>Turning Off INPUT B</u> Press F1 (SCOPE). Press INPUT B. Press F2 (deselect DISPLAY INPUT B). Press SCOPEMETER (to return to main menu).

Notify EFBM operator, "Current Probe zeroing complete, Go for powering on BEP."



Figure 7. Display of Scope Record Mode (after pressing MIN MAX RECORD).





4.5 <u>Checking Out Scope Recording Function</u> Press MIN MAX RECORD.

Refer to Figure 7. Press F2 (START).

If necessary

- Press F1 (YES) to overwrite previous recording.
- Refer to Figure 8.

Verify live waveform is displayed and RUN is on the top right corner.

Wait 20 seconds for sample recording.

Press HOLD RUN (to stop the recording). Verify RUN changes to HOLD.

4.6 <u>Powering Off Current Probe And Scopemeter</u> If EFBM operator is already performing

<u>1.102 ACTIVE EFBM OPS FOR JEF BERTHING</u> (SODF: ASSY OPS: ACTIVATION AND CHECKOUT) after step 4.5, then: Go to step 4.7.

Notify EFBM operator, "Scopemeter checkout complete, Go for powering off BEP."

Select OFF on Scopemeter Current Probe using slide switch. Press ON/OFF (to powerdown Scopemeter). Disconnect Scopemeter, Scopemeter Current Probe.

If powering off Current Probe and Scopemeter complete Notify SSIPC of task completion. \gg

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- 4.7 Configuring Oscilloscope Display Press "S" on TIME button until Time Scale reads "50ms/DIV." Press "V" on RANGE button of INPUT A until INPUT A Scale reads "500mADC 100mV/A." Press INPUT A MOVE (up or down) button until baseline reading is located at first division of cell. Refer to Figure 9.
- RECORDING CURRENT ON EFBM STRUCTURAL LATCH OPS 5.

CAUTION

BEP primary current can be measured using FLUKE current probe and scopemeter, then crewmember and/or ground support members can check if BEP primary current profiles have one(two) peaks and/or sudden falling pattern as shown in Figure 10(11). If they cannot confirm these peaks, this indicates that the torque detection circuit has failed.

NOTE

- 1. It takes \sim 3:15 until the structural latch drive stops and current peaks are detected.
- 2. When the time base range is 50 ms/DIV, scopemeter memory can store 60 seconds of data for a single channel waveform. If the recording time is greater than 60 seconds, then the memory is overwritten to store the latest 60 seconds of data.
- 3. Data recording must be stopped within 20 seconds after the completion of the structural latch drive, since the expected time for the waveform of interest is approximately 15 seconds prior to the completion of the structural latch drive.
- 4. Steps 5 through 7(8) must be repeated for Structural Latch B and A (SL B and A) ops.
- 5. The success of the structural latch motion will be determined by SSIPC based on current peaks and deltas measured in step 7(8).
- 5.1 On EFBM operator, "Ready for Structural Latch B(A) extension, start the current recording."

Press F2 (START).

If necessary Press F1 (YES) to overwrite previous recording.

Verify RUN is displayed.

5.2 On EFBM operator, "Structural Latch extension complete, stop the current recording."

Within 20 seconds of completion of EFBM operations Press HOLD RUN (to stop the recording).

Verify RUN changes to HOLD.

6. VERIFYING CURRENT PEAKS

NOTE

- 1. The following cursor settings will measure the maximum current value for the reading points (two or four). The goal is to determine the delta between Reading Points 1 and 2 (or Reading Points 3 and 4). Refer to Figure 10(11).
- 2. During SL B(SL A) operations, two structural latch bolts are simultaneously driven by independent actuating motors.

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7. MEASURING CURRENT PEAKS FOR ONE PEAK

Figure 12. Waveform of One Current Peak.



Figure 13. Waveform Around Reading Point 1 (Zoomed in).

7.1 Press F4 (ZOOM out) twice. Use MOVE (left or right) button to center area of interest in display. Refer to Figure 12.

Press F3 (ZOOM in) to provide better resolution around Reading Point 1.

Refer to Figure 13.

7.2 Press F5 (select CURSOR on).

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Press F1 (MORE). Press F4 (NEXT PAGE). Use blue arrow keys to highlight "READINGS ON DISPLAY." Press F5 (SELECT ITEM). Use blue arrow keys to highlight "1." Press F5 (SELECT ITEM). Use blue arrow keys to highlight "ADD MAIN READING." Press F5 (SELECT ITEM). Use blue arrow keys to scroll down and highlight "Amax peak." Press F5 (SELECT ITEM). Press F5 (SELECT ITEM). Press F1 (CLOSE).



Figure 14. Maximum Current Value of Reading Point 1.

7.3 Use LEFT CURSOR and RIGHT CURSOR buttons to position cursors as shown in Figure 14.

 Record Amax peak:
 A [Reading Point 1] for SL B

 Record Amax peak:
 A [Reading Point 1] for SL A

7.4 Photo document Scopemeter display (DCS 760 Camera).



Figure 15. Maximum Current Value of Reading Point 2.

7.5 Use LEFT CURSOR and RIGHT CURSOR buttons to position cursors as shown in Figure 14.

Record Amax peak: ______ A [Reading Point 2] for SL B Record Amax peak: ______ A [Reading Point 2] for SL A

7.6 Photo document Scopemeter display (DCS 760 Camera).

<u>NOTE</u> Refer to <u>step 7.3</u> for [Reading Point 1] and refer to <u>step 7.5</u> for [Reading Point 2].

- 7.7 Inform **SSIPC** of the recorded current peaks ([Reading Point 1], [Reading Point 2]).
- 7.8 Repeat <u>steps 5</u> through <u>7(8)</u> for Structural Latch A.
- 7.9 Go to <u>step 9</u>.



8. MEASURING CURRENT PEAKS FOR TWO PEAKS





Figure 17. Waveform Around Reading Point 1 (Zoomed in).

 8.1 Press F4 (ZOOM out) twice. Use MOVE (left or right) button to center area of interest in display. Refer to Figure 16.

Press F3 (ZOOM in) to provide better resolution around Reading Point 1.

Refer to Figure 17.

8.2 Press F5 (select CURSOR on).

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Press F1 (MORE). Press F4 (NEXT PAGE). Use blue arrow keys to highlight "READINGS ON DISPLAY." Press F5 (SELECT ITEM). Use blue arrow keys to highlight "1." Press F5 (SELECT ITEM). Use blue arrow keys to highlight "ADD MAIN READING." Press F5 (SELECT ITEM). Use blue arrow keys to scroll down and highlight "Amax peak." Press F5 (SELECT ITEM). Press F5 (SELECT ITEM). Press F1 (CLOSE).



Figure 18. Maximum Current Value of Reading Point 1.

8.3 Use LEFT CURSOR and RIGHT CURSOR buttons to position cursors as shown in Figure 18.

 Record Amax peak:
 _______ A [Reading Point 1] for SL B

 Record Amax peak:
 ______ A [Reading Point 1] for SL A

8.4 Photo document Scopemeter display (DCS 760 Camera).



Figure 19. Maximum Current Value of Reading Point 2.

8.5 Use LEFT CURSOR and RIGHT CURSOR buttons to position cursors as shown in Figure 19.

 Record Amax peak:
 _______ A [Reading Point 2] for SL B

 Record Amax peak:
 ______ A [Reading Point 2] for SL A

8.6 Photo document Scopemeter display (DCS 760 Camera).

<u>NOTE</u>

Refer to <u>step 8.3</u> for [Reading Point 1] and refer to <u>step 8.5</u> for [Reading Point 2].

8.7 Inform **SSIPC** of the recorded current peaks ([Reading Point 1], [Reading Point 2]).

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Figure 20. Waveform of Reading Points 3 and 4.

 8.8 Use MOVE (left or right) button to show the waveform of Reading Points 3 and 4.
 Use LEFT CURSOR and RIGHT CURSOR buttons to position cursors as shown in Figure 20.

Record Amax peak: _____ A [Reading Point 3] for SL B Record Amax peak: _____ A [Reading Point 3] for SL A

8.9 Photo document Scopemeter display (DCS 760 Camera).



Figure 21. Maximum Current Value of Reading Point 4.

8.10 Use LEFT CURSOR and RIGHT CURSOR buttons to position cursors as shown in Figure 21.

 Record Amax peak:
 A [Reading Point 4] for SL B

 Record Amax peak:
 A [Reading Point 4] for SL A

8.11 Photo document Scopemeter display (DCS 760 Camera).

NOTE

Refer to <u>step 8.8</u> for [Reading Point 3] and refer to <u>step 8.10</u> for [Reading Point 4].

8.12 Inform **SSIPC** of the recorded current peaks ([Reading Point 3], [Reading Point 4]).

Repeat steps 5 through 7(8) for Structural Latch A.

- 9. CLEANUP
 - 9.1 Select OFF on Scopemeter Current Probe using slide switch.
 - 9.2 Press ON/OFF (to powerdown Scopemeter).
 - 9.3 Disconnect Scopemeter, Scopemeter Current Probe.
 - 9.4 Remove Scopemeter Current Probe from EFBM Power Cable.
 - 9.5 Tie cables include EFBM Power Cable with Velcro. Refer to Figure 2.
- 10. CLOSEOUT
 - 10.1 Tighten, torque fasteners (one per corner, total four) at each corner of Closeout Panel (JPM1D7-08), to 27 in-lbs [Ratchet, 1/4" Drive; 5/32" Hex Head, 1/4" Drive; (5-35 in-lbs) Trq Driver, 1/4" Drive].
 - 10.2 Notify **SSIPC** of task completion. Stow tools, equipment.

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OBJECTIVE:

Perform the Active Exposed Facility Berthing Mechanism (EFBM) operation for JEM Exposed Facility (JEF) berthing. Perform capture, bolting and connect umbilicals of the JEM Exposed Facility (JEF) following translation into Ready to Latch (RTL) position by the SSRMS. EFBM capture latches are driven through a multistage capture sequence, then all four structural latches are engaged into their respective nut mechanism, then all eighteen umbilicals are connected into their connectors.

LOCATION:

JPM1F4 (WS Rack)

JPM1D7 (JEM AL)

DURATION:

1 hour 30 minutes (not including steps 7 and 8).

20 minutes for Preparation (steps $\underline{1}$ to $\underline{5}$)

5 minutes for Capture Latch deploy (step $\underline{6}$)

5 minutes for Deactivating as required (step 7)

5 minutes for Activating as required (step 8)

10 minutes for Capture (steps $\underline{9}$ to $\underline{10}$)

30 minutes for Structural Latch extension (steps 11 to 14)

5 minutes for Umbilcals extension (step 15)

20 minutes for closing (steps <u>16</u> to <u>20</u>)

CREW:

One

REFERENCE PROCEDURE:

2.610 PICKLIST ROUTING

MATERIALS:

6" x 6" Ziplock Bag, "BCDU Caps"

ISS IVA Toolbox:

Drawer 2:

Ratchet, 1/4" Drive

5/16" Socket, 1/4" Drive

Drawer 5:

Static Wrist Tether

1.102 ACTIVE EFBM OPS FOR JEF BERTHING

(ASSY OPS/2JA/FIN/HC)

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Figure 1. Active EFBM Configuration (Initial Configuration).
| | NOTE | | | | |
|---------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--|--|--|--|
| 1. No ma AC | Jotation "(AOS/M)" indicates that AOS during execution of step is nandatory. If currently LOS, or expecting LOS prior to completion of an AOS/M step, wait for next AOS to perform. | | | | |
| 2. Cr | ewmember can use RMS Mon1(2) for secondary view as needed. | | | | |
| 3. Cr do th€ | ewmember may not use two CCPs simultaneously because the VCU es not have a capability to receive two Camera-control commands at e same time. | | | | |
| 4. WI se | hen configuring Video System on SLT(RLT), Monitor should be lected first, then Camera. | | | | |
| 5. Fo ch sta at: | or all non-JEM related Cameras, the pan, tilt and zoom must be ecked on PCS. MCC-H can direct you to the appropriate PCS Camera atus Reader display to obtain telemetry. These displays can be found | | | | |
| | C&T: Video Status Reader Video Status Reader | | | | |
| 6. Fo ch W | r all JEM related Cameras, the pan, tilt and zoom values must be ecked on RLT or RMS monitors. These values are not displayed on S monitors or SLT. | | | | |
| 7. Sti se | ructural Latches 1(3) and 2(4) are operated when SL A(SL B) switch is lected. | | | | |
| 8. In 4 (| order to route USOS Cameras, <u>2.610 PICKLIST ROUTING</u> , steps 1 to SODF: C&T: NOMINAL: 2.6 VIDEO) can be referenced. | | | | |
| CONI PACK | NECTING BCDU TO BERTHING MECHANISM ELECTRONICS (AGE (BEP) | | | | |
| 1.1 | If EVA is in progress Notify EVA crew not to enter the keep-out zone around Active EFBM. | | | | |
| 1.2 | JEM: JPM: EPS: Main: PDB a2 JPM EPS PDB a2 Verify RPC1 (BEP) – Open | | | | |
| 1.3 | Don Static Wrist Tether. Attach clip to unpainted, unanodized metal surface. | | | | |
| | WARNING | | | | |
| | The following Active EFBM operation from step 1.4 to 18.2 may cause shearing/pinching hazard to EVA crew if the crew is around Active EFBM. | | | | |
| | | | | | |

BCDU I/F FOR BM(J011B) on JPM 1/P7-106 ←|→ Tethered Protective Сар

SLT

JPM1D7

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P011B on Jumper Cable (80AS51500-213) →|← BCDU I/F FOR BM (J011B) on JPM 1/P7-106

- 1.5 Doff Static Wrist Tether.

JEM Laptop Table

Figure 2. JEM Laptop Table Configuration.

- 1.6 Detach SLT from JEM Laptop Table.
- 1.7 Temporarily attach SLT for use in steps <u>4</u> and <u>16</u>.
- 1.8 Transfer and attach JEM Laptop Table to Seat Track on the left lower side of WS Rack. Refer to Figure 2.
- 1.9 Attach BCDU on JEM Laptop Table, Velcro.
- 2. <u>ACTIVATING WS CCP AND WS MON1</u> WS Mon sw POWER \rightarrow ON (Verify Lt - Illuminated Green)
- WS CCP pb PANEL POWER → ON (Verify Lt Illuminated Green)

Verify VCU a, b ENABLE Lt – Illuminated Green

3. CONFIGURING VIDEO SYSTEM

WARNING

Entering the keep-out zone of TVC/PTU moving envelope would lead to pinching and shearing of EVA crews.

3.1 If EVA is in progress Notify EVA crew not to enter the keep-out zone around TVC/PTU EXT A and F.

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3.2 Configure Cameras as required.

| WS Mon1 | RMS Mon1 | RMS Mon2 | |
|----------------------------|------------------------|-----------------------|--|
| 09: P1 Lower Outboard | EXT F (-73, -40.5; Z = | EXT A (73, -40.5; Z = | |
| (+150, +11; Z = 4.9 cm) | 1.9) | 1.9) | |





Figure 4 - EFBM Init Config

EXT F (-73, -40.5; Z = 1.9).

Figure 5 - EFBM Init Config EXT A (73, -40.5; Z = 1.9).

CAUTION

Active EFBM operations with a large MLI cover installed would lead to Active EFBM failure.

- 3.3 Verify Active EFBM large MLI cover (one) is removed.
- 4. <u>POWERING ON BEP TO ACTIVATE EFBM</u>

CAUTION

BEP shall be deactivated before continuous activation time of BEP reaches three hours to avoid reaching the high temperature limit.

- SLT
- 4.1 On Scopemeter operator, "Go for Powering On BEP.":
- 4.2 JEM Verify JEM MODE – Robotics_operation(Standard)
- 4.3 JEM: JPM: EPS: Main: PDB a2: RPC1 JPM EPS PDB a2 RPC1 Cmd cmd RPC Close Ovrd Execute
- 4.4 JEM: JPM: EPS: Main: PDB a2 JPM EPS PDB a2 Verify RPC1 (BEP) – Close

Record RPC1 Close Time: GMT ______ ____:____:____:

4.5

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BCDU

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Verify the following status:

PWR – On INTLK – On

'STRUCTURAL LATCH'

DISCONNECT 1 - On DISCONNECT 2 - On DISCONNECT 3 - On DISCONNECT 4 - On

'MODE'

CONNECT - On

'ACTUATOR STATUS'

READY - On

5. <u>TESTING LEDS</u> Toggle LED TEST switch.

Verify All LEDs - On

6. PERFORMING CAPTURE LATCHES DEPLOY

6.1 'ACTUATOR SELECT' Toggle CAPT switch.

Verify CAPT – On

6.2 'ACTUATOR STATUS' Verify READY – On

NOTE

It takes \sim 67 seconds to complete the Capture Latches motion in step 6.4.

- 6.3 Record the duration using stopwatch between RUN On (step <u>6.4</u>) and READY – On (step <u>6.5</u>): ______ seconds
- 6.4 'ACTUATOR STATUS' Toggle START switch.

WS Mon Verify RUN – On Verify Capture Latches begin deploying.

BCDU 6.5 'ACTUATOR STATUS' Verify READY – On Verify RUN – Off

- 6.6 'ACTUATOR SELECT" Verify CAPT – Off
- 6.7 'CAPTURE LATCH' Verify OPEN 1 – On Verify OPEN 2 – On Verify OPEN 3 – On Verify OPEN 4 – On
- 6.8 Give SSRMS operator GO, "Capture Latches open has been completed, Go for JEF unberth."
- 7. DEACTIVATING BEP AS REQUIRED

| | | CAUTION | | | |
|------|----|----------------|---------------------------------------------------------------------------------------------------------------------------|--|--|
| | | BEP three | shall be deactivated before continuous activation time of BEP reaches hours to avoid reaching the high temperature limit. | | |
| | | lf the step | Berthing operation is expected to be complete within three hours, go to $\underline{9}$. | | |
| SLT | | 7.1 | JEM: JPM: EPS: Main: PDB a2: RPC1 JPM EPS PDB a2 RPC1 Cmd cmd RPC Open Execute | | |
| | | 7.2 | JEM: JPM: EPS: Main: PDB a2 JPM EPS PDB a2 Verify RPC1 (BEP) – Open | | |
| BCDU | | 7.3 | Verify PWR – Off | | |
| | | | Record RPC1 Open Time: GMT:: | | |
| | 8. | POW | ERING ON BEP TO ACTIVATE EFBM AS REQUIRED | | |
| | | 8.1 | On SSRMS operator GO for EFBM activation. | | |
| SLT | | 8.2 | JEM Verify JEM MODE – Robotics_operation(Standard) | | |
| | | 8.3 | JEM: JPM: EPS: Main: PDB a2: RPC1 JPM EPS PDB a2 RPC1 Cmd cmd RPC Close Ovrd Execute | | |
| | | 8.4 | JEM: JPM: EPS: Main: PDB a2 JPM EPS PDB a2 Verify RPC1 (BEP) – Close | | |
| | | | Record RPC1 Close Time: GMT : : | | |

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BCDU

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8.5 Verify the following status:

PWR – On INTLK – On

'CAPTURE LATCH'

Verify OPEN 1 – On Verify OPEN 2 – On Verify OPEN 3 – On Verify OPEN 4 – On

'MODE'

CONNECT - On

'ACTUATOR STATUS'

READY - On

Give SSRMS operator GO for maneuver to Ready To Latch (RTL).

- 9. PERFORMING FIRST STAGE CAPTURE (AOS/M)
 - 9.1 On SSRMS operator GO, "Maneuver to RTL complete, SSRMS is limped, Carriage of SSRMS LEE is partially derigidized, Go for capture latch closing."
 - 9.2 If BEP is reactivated in step 7 and 8 Toggle INTLK switch.

Verify INTLK – Off

'MODE'

Verify CONNECT – On

9.3 'ACTUATOR SELECT' Toggle CAPT switch.

Verify CAPT – On

9.4 'ACTUATOR STATUS' Verify READY – On

NOTE

It takes \sim 8 seconds to complete the Capture Latches motion in step 9.6.

9.5 Record the duration using stopwatch between RUN – On (step <u>9.6</u>) and READY – On (step <u>9.7</u>): _______ seconds 9.6 'ACTUATOR STATUS' Toggle START switch.

Verify RUN – On Verify Capture Latches begin retracting to soft capture position.

BDCU

WS Mon

- 9.7 'ACTUATOR STATUS' Verify READY – On Verify RUN – Off
 - 9.8 'ACTUATOR SELECT' Verify CAPT – Off
 - 9.9 'CAPTURE LATCH' Verify SOFT CAPTURE 1 – On Verify SOFT CAPTURE 2 – On Verify SOFT CAPTURE 3 – On Verify SOFT CAPTURE 4 – On

10. PERFORMING SECOND STAGE CAPTURE (AOS/M)

10.1 'ACTUATOR SELECT' Toggle CAPT switch.

Verify CAPT – On

10.2 'ACTUATOR STATUS' Verify READY – On

NOTE

It takes ${\sim}60$ seconds to complete the Capture Latches motion in step 10.4.

- 10.3 Record the duration using stopwatch between RUN On (step <u>10.4</u>) and READY – On (step <u>10.5</u>): ______ seconds
- 10.4 'ACTUATOR STATUS' Toggle START switch.

WS Mon

Verify RUN – On Verify Capture Latches begin retracting to close position.

- BDCU 10.5 'ACTUATOR STATUS' Verify READY – On Verify RUN – Off
 - 10.6 'ACTUATOR SELECT' Verify CAPT – Off
 - 10.7 'CAPTURE LATCH'

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Verify CLOSE 1 – On Verify CLOSE 2 – On Verify CLOSE 3 – On Verify CLOSE 4 – On

11. PERFORMING STRUCTURAL LATCH 1, 2 EXTENSION

11.1 'ACTUATOR SELECT' Toggle SL A switch.

Verify SL A – On

11.2 'ACTUATOR STATUS' Verify READY – On

NOTE

- 1. It takes \sim 3:35 to complete the Structural Latches motion in step <u>11.4</u>.
- 2. The timing on which CONNECT 1 or 2 turns on first is unknown due to the initial misaligment between the passive half and the active half of EFBM.
- 11.3 Record the duration using stopwatch between RUN On (step <u>11.4</u>) and CONNECT – On (step <u>11.5</u>)

CONNECT 1: ______ seconds CONNECT 2: ______ seconds

11.4 'ACTUATOR STATUS' Toggle START switch.

Verify RUN – On

- 11.5 'STRUCTURAL LATCH' Verify CONNECT 1 – On Verify CONNECT 2 – On
- 11.6 'ACTUATOR STATUS' Verify READY – On Verify RUN – Off
- 11.7 'ACTUATOR SELECT' Verify SL A – Off
- 11.8 Notify **SSIPC** of the recorded duration (CONNECT 1, 2). Refer to step <u>11.3</u>.
- 12. PERFORMING STRUCTURAL LATCH 3, 4 EXTENSION

<u>NOTE</u> Current measurement with scopemeter is performed in parallel with this step.

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12.1 'ACTUATOR SELECT' Toggle SL B switch.

Verify SL B – On

- 12.2 'ACTUATOR STATUS' Verify READY – On
- 12.3 Notify Scopemeter operator, "Ready for Structural Latch B extension, start the current recording."
- NOTE 1. It takes \sim 3:10 to complete the Structural Latches motion in the step 12.5. 2. In step 12.4, the timing of LED indication is that CONNECT 4 turns on first and then after 6 seconds (nominal) CONNECT 3 turns on. 3. In step 12.6, Scopemeter operator needs "Stop recording" call just after LED verification because the memory of Scopemeter can only store the data for one minute. Record the duration using stopwatch between RUN - On (step 12.5) 12.4 and CONNECT - On (step 12.6) CONNECT 4: ______ seconds [T4] CONNECT 3: ______ seconds [T3] 12.5 'ACTUATOR STATUS' Toggle START switch. Verify RUN – On 12.6 'STRUCTURAL LATCH' Verify CONNECT 4 - On Verify CONNECT 3 - On

Notify Scopemeter operator, "Structural Latch B extension complete, stop the current recording."

- 12.7 'ACTUATOR STATUS' Verify READY – On Verify RUN – Off
- 12.8 'ACTUATOR SELECT' Verify SL B – Off
- 12.9 Verify LED On timing [T4] within 186.5 ± 4 seconds. Verify LED On timing [T3] within 192.5 ± 4 seconds. Verify LED On timing ([T3] - [T4]) within 6 ± 2 seconds.
- 12.10 Notify **SSIPC** of the recorded duration (CONNECT 3 [T3], 4 [T4]). Refer to step <u>12.4</u>.

13. PERFORMING STRUCTURAL LATCH 1, 2 RETRACTION

- 13.1 If BEP is reactivated in step 7 and 8 Verify INTLK – Off Go to step <u>13.3</u>.
- 13.2 Toggle INTLK switch.

Verify INTLK – Off

13.3 'MODE' Toggle MODE switch.

Verify DISCONNECT – On

13.4 'ACTUATOR SELECT' Toggle SL A switch.

Verify SL A – On

13.5 'ACTUATOR STATUS' Verify READY – On

<u>NOTE</u>

- 1. It takes \sim 3:15 to complete the Structural Latches motion in the step 13.7.
- 2. In step <u>13.6</u>, the timing of LED indication is that DISCONNECT 1 turns on first and then after 2 seconds (nominal) DISCONNECT 2 turns on.
- 3. If unexpected indication of Disconnect LEDs is encountered, crew should perform the star block in step 13.8.
- 13.6 Record the duration using stopwatch between RUN On (step <u>13.7</u>) and DISCONNECTs – On (step <u>13.8</u>). DISCONNECT 1: _______seconds
 - DISCONNECT 2: _____ seconds
- 13.7 'ACTUATOR STATUS' Toggle START switch.

Verify RUN – On

13.8 'STRUCTURAL LATCH' Verify DISCONNECT 1 – On Verify DISCONNECT 2 – On

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If DISCONNECT 2 turns on first Toggle STOP switch. Verify STOP – On ✓SSIPC If DISCONNECT 2 remains off for 4 seconds after DISCONNECT 1 turns on Toggle STOP switch. Verify STOP – On ✓SSIPC

- 13.9 'ACTUATOR STATUS' Verify READY – On Verify RUN – Off
- 13.10 'ACTUATOR SELECT' Verify SL A – Off
- 14. PERFORMING STRUCTURAL LATCH 1, 2 RE-EXTENSION

<u>NOTE</u>

Current measurement with scopemeter is performed in parallel with this step.

14.1 'MODE' Toggle MODE switch.

Verify CONNECT - On

14.2 'ACTUATOR SELECT' Toggle SL A switch.

Verify SL A – On

- 14.3 'ACTUATOR STATUS' Verify READY – On
- 14.4 Notify Scopemeter operator, "Ready for Structural Latch A Reextension, start the current recording."

14.5

14.6

14.8

NOTE 1. It takes \sim 3:15 to complete the Structural Latches motion in step 14.6. 2. In step 14.5, the timing of LED indication is that CONNECT 1 turns on first and then after 2 seconds (nominal) CONNECT 2 turns on. 3. In step 14.7, Scopemeter Operator needs "Stop recording" call just after LED verification because the memory of Scopemeter can only store the data for one minute. Record the duration using stopwatch between RUN – On (step 14.6) and CONNECT - On (step 14.7) CONNECT 1: ______ seconds [T1] CONNECT 2: ______ seconds [T2] 'ACTUATOR STATUS' Toggle START switch. Verify RUN - On 14.7 'STRUCTURAL LATCH' Verify CONNECT 1 – On Verify CONNECT 2 – On Notify Scopemeter operator, "Structural Latch A extension completed, stop the current recording." 'ACTUATOR STATUS' Verify READY – On

14.9 'ACTUATOR SELECT' Verify SL A – Off

Verify RUN – Off

- 14.10 Verify LED On timing [T1] within 194 ± 4 seconds. Verify LED On timing [T2] within 196 ± 4 seconds. Verify LED On timing ([T2] - [T1]) within 2 ± 2 seconds.
- 14.11 Notify SSIPC of the recorded duration (CONNECT 1 [T1], 2 [T2]). Refer to step 14.5.

15. PERFORMING UMBILICALS EXTENSION

15.1 'ACTUATOR SELECT' Toggle UMB switch.

Verify UMB – On

15.2 'ACTUATOR STATUS' Verify READY – On

15.3

15.4

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| It takes \sim 61 seconds to complete the umbilicals motion in step 15.4. |
|-------------------------------------------------------------------------------------------------------------------------|
| Record the duration using stopwatch between RUN – On (step <u>15.4</u>) and READY – On (step <u>15.5</u>): seconds |
| 'ACTUATOR STATUS' Toggle START switch. |
| Verify RUN – On |

NOTE

15.5 'ACTUATOR STATUS' Verify READY - On Verify RUN – Off

- 15.6 'ACTUATOR SELECT' Verify UMB – Off
- 15.7 'UMBILICAL' Verify CONNECT 1 – On Verify CONNECT 2 - On
- 16. DEACTIVATING BEP

WARNING

The following steps 16 and 17.2 must be performed in order to prevent inadvertent release of the JEF and shearing/pinching hazard to EVA crew due to inadvertent motion of Active EFBM.

SLT

- 16.1 JEM: JPM: EPS: Main: PDB a2: RPC1 JPM EPS PDB a2 RPC1 Cmd cmd RPC Open Execute
- 16.2 JEM: JPM: EPS: Main: PDB a2 JPM EPS PDB a2 Verify RPC1 (BEP) – Open

Record RPC1 Open Time: GMT ______ ___:___:____:

BCDU 16.3 Verify PWR – Off

17. SAFING

- JPM1D7 17.1 Don Static Wrist Tether. Attach clip to unpainted, unanodized metal surface.
 - P011B on Jumper Cable (80AS51500-213) ←|→ BCDU I/F FOR BM 17.2 (J011B) on JPM 1/P7-106

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- 17.3 P011B on Jumper Cable (80AS51500-213) →|← Protective Cap BCDU I/F FOR BM (J011B) on JPM 1/P7-106 →|← Protective Cap
- 17.4 Doff Static Wrist Tether.
- 17.5 If EVA in progress Notify EVA crew that Keep-out zone around Active EFBM is removed.
- 17.6 Give SSRMS operator GO, "Active EFBM berthing operations complete, Go for ungrapple JEF."
- 18. BCDU STORAGE
- JPM1F4 18.1 Don Static Wrist Tether. Attach clip to unpainted, unanodized metal surface.
 - 18.2 P006B on Jumper Cable (80AS51500-213) $\leftarrow | \rightarrow J1$ on BCDU
 - 18.3 P006B on Jumper Cable (80AS51500-213) →|← Protective cover J1 on BCDU →|← Protective Cap
 - 18.4 Detach the BCDU bonding jumper from bonding point on WS Rack (Ratchet, 1/4" Drive; 5/16" Socket, 1/4" Drive).
 - 18.5 Doff Static Wrist Tether.
 - 18.6 Detach BCDU from WS Rack.
 - 18.7 Temporarily stow.
- 19. DEACTIVATING WS CCP AND WS MON1
- WS CCP sw CAMERA COMMAND \rightarrow OFF

pb PANEL POWER → OFF (Verify Lt – Not Illuminated)

- WS Mon sw POWER \rightarrow OFF (Verify Lt Not Illuminated)
 - 20. CLOSEOUT
 - 20.1 Notify SSIPC, "Active EFBM operations complete."
 - 20.2 Stow all tools, equipment and hardware.

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OBJECTIVE:

This procedure is used to setup G1 Camcorder near JEM Airlock and Work Station rack for taking video of the Scopemeter during EFBM Current Monitor, and for taking video of the BCDU during Active EFBM Ops for JEF Berthing.

LOCATION:

JPM1D7, JPM1F7 (Around JEM Airlock) for G1 Camcorder

JPM1D5 (EPS2 Rack) for MPC and MPC DC Power Supply

DURATION

25 minutes

5 minutes for preparation

10 minutes for G1 Camcorder and MPC setting (Step 1)

5 minutes for G1 Camcorder setup, operation (Step 2)

5 minutes for G1 Camcorder and MPC Deactivation (Step 3)

CREW:

One

MATERIALS:

Ziplock Bag

TOOLS:

G1 Camcorder P/N XH G1

G1 Camcorder Fixture P/N MPC-011

ISS IVA Toolbox:

Drawer 2:

3/16" Hex Head, 1/4" Drive

Driver Handle, 1/4" Drive

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Figure 1. MPC, Multi-Protocol DC Power Supply, IPU and G1 Camcorder Configuration.



Figure 2. G1 Camcorder Installation Location (Candidate).

1. G1 CAMCORDER AND MPC SETTING

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1.1 <u>G1 Camcorder Placement</u>

| | | NOTE | | | |
|---------------------------|-----|-------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--|--|
| | | 1. Equipment configuration is shown in Figure 1. | | | |
| | | 2. MPC and MPC DC Power Supply are set on JPM1D5 EPS2 Rack. | | | |
| JPM1D7 | | 1.1.1 | Attach G1 Camcorder Fixture to seat tracks around JEM Airlock to face Scopemeter referring to Figure 2. | | |
| | | 1.1.2 | If Multi-use Bracket Adapter 1/4-20 is attached to G1 | | |
| | | | Remove Multi-use Bracket Adapter 1/4-20 (Driver Handle, 1/4" Drive; 3/16" Hex Head, 1/4" Drive). Stow Multi-use Bracket Adapter 1/4-20 in Ziplock Bag. | | |
| | | 1.1.3 | Attach G1 Camcorder onto G1 Camcorder Fixture. | | |
| MPC DC Power Supply | | 1.1.4 | ✓sw 8.4V PWR 1 – OFF | | |
| G1 Camcorder | | | ✓POWER Dial – OFF | | |
| | | 1.1.5 | G1 Camcorder Combination Cable Connection P22 → ← HDV/DV terminal on G1 Camcorder P21 → ← G1 Camcorder (the Battery installation portion on G1 Camcorder back side) | | |
| | 1.2 | MPC P | owering On | | |
| UOP | | 1.2.1 | If POWER OUT - RESET illuminated pb POWER OUT → Press | | |
| | | | ✓POWER OUT – ENABLE illuminated ✓FAULT/TEST – OK illuminated | | |
| | | | WARNING | | |
| | | | Do not touch the back surface (Velcro side) of Multi- Protocol Converter DC Power Supply to prevent touch temperature hazard due to fan failure. Front side and switches can be touched. | | |
| MPC DC Power Supply | | 1.2.2 | sw 16V PWR \rightarrow ON | | |
| | | | ✓16V PWR LED – illuminated (green) | | |
| | | 1.2.3 | sw 8.4V PWR 1 → ON | | |

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√8.4V PWR 1 LED – illuminated (green)

MPC $1.2.4 \text{ sw Power} \rightarrow \text{ON}$

✓3V LED – illuminated (green)
 ✓5V LED – illuminated (green)

NOTE

Once MPC downlink has been initiated, downlink cannot be terminated without **SSIPC** GO due to system limitations.

2. <u>G1 CAMCORDER SETUP AND OPERATION</u>

2.1 Camcorder Body Settings

G1 Camcorder

- 2.1.1 Remove Lens Cap.
 - 2.1.2 POWER Dial →
 - ✓Viewfinder (LCD) ● (Pause)
 - 2.1.3 ✓Standby Lever STANDBY
 - 2.1.4 ✓" ◆XLR" is not displayed in Viewfinder
- 2.2 √Viewfinder (LCD) HDV 60i displayed

If HDV 60i is not displayed, then

pb MENU \rightarrow Press sel SELECT/SET \blacktriangleright SIGNAL SETUP - press sel SELECT/SET \triangleright SIGNAL STD - press sel SELECT/SET \triangleright HD - press sel SELECT/SET \triangleright YES - press pb MENU \rightarrow Press sel SELECT/SET \triangleright SIGNAL SETUP - press sel SELECT/SET \triangleright FRAME RATE - press sel SELECT/SET \triangleright 60i - press sel SELECT/SET \triangleright 7ES - press pb MENU \rightarrow Press

MPC 2.3 <u>MPC LED Check</u> √TAXI LED – illuminated (green)

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✓HDV LED – illuminated (green)

2.4 Lens Settings

G1 Camcorder 2.4.1 ✓ND FILTER – OFF

- 2.4.2 ✓POSITION PRESET OFF
- 2.4.3 Notify **SSIPC** that MPC and G1 Camcorder are ready for downlink.

3. G1 CAMCORDER AND MPC DEACTIVATION

| | | | NOTE | | |
|---------------------------|----|-----------------------------|------------------------------------------------------------------------------------------------------------|--|--|
| | | SSI to S | PC gives go after video data is successfully downlinked and transferred SIPC, which takes about 5 minutes. | | |
| | | 3.1 | On SSIPC GO | | |
| | | | Attach Lens Cap. | | |
| | | | POWER Dial \rightarrow OFF | | |
| MPC | | 3.2 | sw POWER \rightarrow OFF | | |
| | | | ✓All LEDs are not illuminated | | |
| MPC DC Power Supply | | 3.3 | sw 8.4V PWR 1 → OFF | | |
| | | | ✓8.4V PWR 1 LED – not illuminated | | |
| | | 3.4 | sw 16V PWR \rightarrow OFF | | |
| | | | ✓16V PWR LED – not illuminated | | |
| UOP | | 3.5 | If other equipment is not used on the same UOP pb POWER OUT → Press | | |
| | | | ✓POWER OUT – RESET (illuminated) ✓FAULT/TEST – not illuminated | | |
| | 4. | <u>CLO</u> Notif Stow | <u>SE OUT</u> y SSIPC that Deactivation is complete. / tools. | | |

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1.201 JEF ACTIVATION FLOW CHART

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1.201 JEF ACTIVATION FLOW CHART

(ASSY OPS/2JA/FIN 1/MULTI J)

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Parameters 1. EDUs

| [Y] | [Z] |
|-------|-------------|
| EDU a | PDB a RPC3 |
| EDU b | PDB b RPC20 |

OBJECTIVE:

Perform JEF EFU Capture Latch Ops for JLE berthing to EFU10(9). This procedure can be used for JEF EFU10 and EFU9 by replacing parameters with the EFU to be operated. Steps 7 to 10 are normally performed by crew and the others by **SSIPC**.

LOCATION:

JPM1A6

DURATION:

50 minutes

10 minutes for EFU Ops preparation (steps 1 to 3)

5 minutes for EDU activation and EFU select (step 4)

15 minutes for EFU Capture Latch open (steps 5 to 6)

15 minutes for EFU Capture Latch close (steps 7 to 10)

5 minutes for EFU deactivation and JEF Ops mode transition (steps 11 to 12)

CREW:

One

<u>NOTE</u>

- 1. EDU activation, EFU Capture Latch open and EDU deactivation are normally performed by **SSIPC**.
- 2. Notation "(AOS/M)" indicates that AOS during execution of step is mandatory. If currently LOS, or expecting LOS prior to completion of an AOS/M step, wait for next AOS to perform.
- 3. This procedure can be used for EFU10 and EFU9 by replacing the name of the port being operated.



Figure 1. EFU Cmd Buttons.



- 1. When Select Cmd is selected in Figure 1, JEF Mech EFU10(9) Select Cmd window opens for EFU selection.
- When Action Cmd is selected in Figure 1, JEF Mech EFU10(9) Action Cmd window opens for execution of Softdock, Release, or Capture Command.
- 3. When Action Cmd is executed, JEF Mech EFU10(9) Action Cmd window will be automatically closed. Therefore re-open of this window is required to issue the Stop command for EFU unexpected motion.
- 4. If EFU arms have unexpected motion (Example, latching arm motion in the unexpected direction), the following star block will be performed to terminate EFU motion.

| (ASSY OPS/2 | JA/FIN 1/MULTI J/HC) Page 3 of 10 pages |
|-------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| SLT | If unexpected motion of EFU arms is observed, Perform the following steps to terminate EFU motion: JEF: Mech: PLX: EFU10(9) (Refer to Table 1) JEF Mech EFU 10(9) Stat |
| | * sel Action - Cmd (Refer to Figure 1) * JEF Mech EFU 10(9) Action Cmd |
| | <pre>* cmd Stop Execute * * JEF Mech EFU 10(9) Stat</pre> |
| | * Verify Abort – Aborted |
| | 1. VERIFYING EDU AND EFU MOTOR TEMP |

- ✓SSIPC that the temperature of the EDU and the designated EFU Motor is in normal range
- 2. <u>CONFIGURING VIDEO SYSTEM</u> Use best available view (JPM, JEMRMS, ISS Truss, SSRMS, etc.). Pan/tilt/zoom Camera, as required, to observe the EFU.
- 3. JEF OPS MODE TRANSITION BEFORE EFU CLOSE
 - 3.1 <u>Verifying JEM Mode</u> JEM

Verify JEM Mode – Robotics Operation

3.2 Transitioning JEF Ops Mode To PL Exchange JEF: EPS JEF EPS

Verify JEF Ops Mode – PL_Ops_Enable

sel JEF Ops Mode

JEF Sel Ops Mode Cmd

cmd P/L Exchange Execute

JEF EPS

Verify JEF Ops Mode – P/L Exchange

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WARNING

ESC, HCE, EDU health status must be Normal to detect the inadvertent PL release.

- 4. POWERING ON EDU
 - 4.1 <u>Verifying ESC and HCE Health Status</u> JEF: CDH JEF CDH

If ESC a(b) is Blue,

sel ESC a(b)

JEF CDH ESC a(b) Stat

Verify Health Status – Normal

JEF: TCS: PTCS a

If HCE a is Blue,

JEF: TCS: PTCS a: HCE a: FWC

Verify Health Status - Normal

JEF: TCS: PTCS b

If HCE b is Blue,

JEF: TCS: PTCS b: HCE b: FWC

Verify Health Status – Normal

4.2 Closing PDB RPC

Remind EVA crew of the keep-out zone around the EFU.

WARNING

If EVA crew needs to get inside the designated EFU keep-out zone, the EFU must be deactivated to avoid shearing/pinching.

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| NOTE | | | | |
|-------------------------------------|-------------|--|--|--|
| SSIPC designates which EDU is used. | | | | |
| Table 1. Parameters for EDUs | | | | |
| EDUs | EDU RPCs | | | |
| [Y] | [Z] | | | |
| EDU a | PDB a RPC3 | | | |
| EDU b | PDB b RPC20 | | | |

JEF: Mech: PLX: EDU

JEF Mech EDU Stat

'**[Y]**' (Refer to Table 2)

sel PDB RPC Posn - Cmd

JEF EPS [Z] Cmd

cmd RPC Close Execute

JEF Mech EDU Stat

'[Y]'

Verify PDB RPC Posn – Closed

- 4.3 <u>Verifying EDU Status</u> Verify Health Status – Normal Verify BIT Status – Valid Verify BIT Result – Normal
- 4.4 <u>Selecting EFU</u> JEF: Mech: PLX: EFU 10(9) JEF Mech EFU 10(9) Stat

sel Select - Cmd (Refer to Figure 1)

JEF Mech EFU 10(9) Select Cmd

cmd Select Execute

JEF Mech EFU 10(9) Stat

Verify Health – Normal Verify Select – Selected

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5. VERIFYING BERTHING STAT FOR EFU OPEN OPS (AS REQUIRED)

WARNING

Capture1 and 2 must be Off to verify that P/L is not berthed at the selected EFU.

Verify Full Open – Off Verify Softdock – Off Verify Full Close – On Verify Capture1 – Off Verify Capture2 – Off

- 6. PERFORMING EFU CAPTURE LATCH OPEN (AS REQUIRED)
 - 6.1 Performing Softdock From Close

EFU motion from close to softdock takes ~5:35 to complete.

JEF Mech EFU10(9) Stat

sel Action - Cmd (Refer to Figure 1)

JEF Mech EFU10(9) Action Cmd

cmd Softdock Execute

JEF Mech EFU10(9) Stat

Verify Full Open – Off Verify Softdock – On Verify Full Close – Off

6.2 <u>Performing Open</u>

<u>NOTE</u>

EFU motion from softdock to open takes ~2:56 to complete.

JEF Mech EFU10(9) Stat

sel Action – Cmd (Refer to Figure 1)

JEF Mech EFU10(9) Action Cmd

cmd Release Execute

JEF Mech EFU10(9) Stat

Verify Full Open – On Verify Softdock – Off

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7. <u>VERIFYING BERTHING STAT FOR EFU CLOSE OPS</u> JEF: Mech: PLX: EFU10(9) JEF Mech EFU10(9) Stat

Verify Full Open – On Verify Softdock – Off Verify Full Close – Off Verify Capture1 – Off Verify Capture2 – Off

8. ENABLING MECHANISM AUTOSAFING SOFTWARE

On SSRMS operator GO, "Mnvr to RTL complete. SSRMS is Limped and carriage of LEE is partially derigidized. GO for EFU 10(9) Capture Latch Close".

WARNING

To prevent structural failure of SSRMS, JEF and JLE in case of SSRMS Brakes-On, the Mechanism Autosafing software in CCS must be enabled prior to initiating capture commands.

NOTE

Node 2 Nadir CBM PCS display is being utilized to navigate to the Mechanism Autosafing Displays.

sel Node 2: S&M

Node 2:S&M 'Nadir CBM'

sel Node 2 Nadir CBM

Node 2 Nadir CBM

'CBM Status'

sel Mechanism Autosafing

Mechanism Autosafing

'Autosafing PPL Version IDs - Safing Cmds'

Verify Primary C&C: 7018(7019) Verify Backup C&C: 7018(7019)

'Autosafing PPL Version IDs - Safing Default'

Verify Backup C&C: 7002

'Enable'

cmd Enable Execute

PCS

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Verify Mechanism Autosafing – Enabled

9. PERFORMING EFU CAPTURE LATCH CLOSE

9.1 Performing Softdock From Open (AOS/M)

<u>NOTE</u>

EFU motion from open to softdock takes ~2:37 to complete.

SLT

JEF: Mech: PLX: EFU10(9) JEF Mech EFU10(9) Stat

sel Action - Cmd (Refer to Figure 1)

JEF Mech EFU10(9) Action Cmd

cmd Softdock Execute

JEF Mech EFU10(9) Stat

Verify Full Open – Off Verify Softdock – On Verify Full Close – Off

9.2 <u>Performing Close (AOS/M)</u>

WARNING

- 1. The following conditions shall be met to ensure the successful payload mating.
 - (1) Full Close On
 - (2) Capture1 On
 - (3) Capture2 On
- 2. If Full Close is Off, the Full Close status on the redundant EDU shall be confirmed as an additional indication.
- 3. If Capture 1(2) is off, the timing of Full close-on shall be verified as an additional indication. EFU health status can be used as an alternate status for this timing confirmation because this is a summary status including Time-over error and Under-limit error of Full Close status.

NOTE

EFU motion from softdock to close takes ~5:54 to complete.

JEF Mech EFU10(9) Stat

sel Action - Cmd (Refer to Figure 1)

JEF Mech EFU10(9) Action Cmd

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cmd Capture Execute

JEF Mech EFU10(9) Stat Verify Full Close – On Verify Capture1 – On Verify Capture2 – On If one of Full Close, Capture1 and 2 statuses is not true, If Full Close is Off, * If EDU a is used, * Perform step 11 for EDU a deactivation, then: Perform step 4.2 for EDU b activation, then: If EDU b is used, Perform step 11 for EDU b deactivation, then: Perform step 4.2 for EDU a activation, then: JEF: Mech: PLX: EFU10(9) * * JEF Mech EFU10(9) Stat * * Verify Full Close - On * * * Go to step 10. * * If Capture1(2) is Off, * JEF Mech EFU10(9) Stat Verify Health - Normal Go to step 10.

10. INHIBITING MECHANISM AUTOSAFING SOFTWARE

Mechanism Autosafing

cmd Arm Execute

Verify Arm – ✓

cmd Inhibit Execute

Verify Mechanism Autosafing – Inhibited

PCS

(ASSY OPS/2JA/FIN 1/MULTI J/HC) Page 10 of 10 pages

Notify SSIPC, "Go for activating JLE, JLE has been berthed at EFU10(9)."

11. POWERING OFF EDU

On SSIPC GO, proceed to powering off EDU.

WARNING

EDU shall be deactivated to prevent inadvertent PL release.

SLT

JEF: Mech: PLX: EDU JEF Mech EDU Stat '[Y]' (Refer to Table 2)

sel PDB RPC Posn - Cmd

JEF EPS [Z] Cmd

cmd RPC Open Execute

JEF Mech EDU Stat

'[Y]'

Verify PDB RPC Posn – Open

If EVA crew is in the vicinity of designated EFU,

Notify EVA crew the designated EFU has been powered off, so the keepout zone around the EFU has been removed.

12. JEF OPS MODE TRANSITION AFTER EFU CLOSE

JEF: EPS

JEF EPS

Verify JEF Ops Mode – P/L Exchange

sel JEF Ops Mode

JEF Sel Ops Mode Cmd

cmd PL_Ops_Enable Execute

JEF EPS

Verify JEF Ops Mode – PL_Ops_Enable

(ASSY OPS/2JA/FIN/HC)

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| EFU in Use [X1] | SPBs [P1] | SPB RPCs [Q1] | PDBs [R1] | PDB RPCs [S1] | |
|-----------------|-----------|---------------|-----------|---------------|--|
| [X1] | [P1] | [Q1] | [R1] | [S1] | |
| EFU10 | SPB a | RPC6 | PDB b | RPC34 | |
| EFU9 | SPB b | RPC11 | PDB a | RPC17 | |

Parameters 1. Parameters for JEF EFUs

Parameters 2. Parameters for EDUs

| EDUs [Y1] | EDU RPCs [Z1] |
|-----------|---------------|
| [Y1] | [Z1] |
| EDU a | PDB a RPC3 |
| EDU b | PDB b RPC20 |

OBJECTIVE:

Perform JEF EFU Capture Latch Open for SSRMS unberthing JLE from EFU10(9). This procedure can be used for JEF EFU10 and EFU9 by replacing parameters with the EFU is operated. Steps <u>5</u> to <u>6</u> are normally performed by crew and the others by **SSIPC**.

LOCATION:

JPM1A6

DURATION:

55 minutes

10 minutes for EFU preparation and activation (steps 1 to 4)

5 minutes for Preparation for JLE unberthing (step 5)

15 minutes for EFU Capture Latch open (step 6)

15 minutes for EFU Capture Latch close (step 7)

5 minutes for EFU deactivation (steps <u>8</u>)

5 minutes for JEF Ops mode transition (step 9)

CREW:

One

NOTE

- 1. EDU activation, EFU Capture Latch close and EDU deactivation are normally performed by **SSIPC**.
- 2. Notation "(AOS/M)" indicates that AOS during execution of step is mandatory. If currently LOS, or expecting LOS prior to completion of an AOS/M step, wait for next AOS to perform.
- 3. This procedure can be used for EFU10 and EFU9 by replacing [X1] with the name of the port being operated (example, EFU10). Different RPCs are also operated for different ports. Table 1 is used throughout the procedure to indicate which RPCs and SPBs should be operated to perform various steps.

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| EFU in Use [X1] | SPBs [P1] | SPB RPCs [Q1] | PDBs [R1] | PDB RPCs [S1] |
|--------------------|-----------|------------------|-----------|------------------|
| EFU10 | SPB a | RPC6 | PDB b | RPC34 |
| EFU9 | SPB b | RPC11 | PDB a | RPC17 |





SLT

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If unexpected motion of EFU arms is observed Perform the following steps to terminate EFU motion. JEF: Mech: PLX: [X1] (Refer to Table 1.) JEF Mech [X1] Stat sel Abort - Cmd (Refer to Figure 1.) * JEF Mech [X1] Action Cmd * * * cmd Stop Execute * * JEF Mech [X1] Stat * * * Verify Abort – Aborted *

1. VERIFYING EDU AND EFU MOTOR TEMP

✓SSIPC that the temperature of the EDU and the designated EFU Motor is in nominal range

- <u>CONFIGURING VIDEO SYSTEM</u> Use best available view (JPM, JEMRMS, ISS Truss, SSRMS, etc.). Pan/tilt/zoom Camera, as required, to observe the EFU.
- 3. JEF OPS MODE TRANSITION BEFORE EFU CAPTURE
 - 3.1 Verifying JEM Mode JEM

Verify JEM Mode – Robotics Operation

3.2 <u>Transitioning JEF Ops Mode to PL Exchange</u> JEF: EPS JEF EPS

Verify JEF Ops Mode – PL_Ops_Enable

sel JEF Ops Mode

JEF Sel Ops Mode Cmd

cmd P/L Exchange Execute

JEF EPS

Verify JEF Ops Mode – P/L Exchange

4. <u>POWERING ON EDU</u>

4.1 Closing PDB RPC

Remind EVA crew of the keep-out zone around the EFU.

| WARNING |
|---------------------------------------------------------------------------------------------------------------------------|
| If EVA crew needs to get inside the designated EFU keep-out zone, the EFU must be deactivated to avoid shearing/pinching. |

NOTE

SSIPC designates either of EDU a or EDU b is used.

Table 2. Parameters for EDUs

| EDUs [Y1] | EDU RPCs [Z1] |
|-----------|---------------|
| EDU a | PDB a RPC3 |
| EDU b | PDB b RPC20 |

JEF: Mech: PLX: EDU

JEF Mech EDU Stat

'[Y1]' (Refer to Table 2.)

sel PDB RPC Posn - Cmd

JEF EPS [Z1] Cmd

cmd RPC Close Execute

JEF Mech EDU Stat

'[Y1]'

Verify PDB RPC Posn – Closed

- 4.2 <u>Verifying EDU Status</u> Verify Health Status – Normal Verify BIT Status – Valid Verify BIT Result – Normal
- 4.3 <u>Verifying Berthing Status</u> JEF: Mech: PLX: **[X1]** JEF Mech **[X1]** Stat

Verify Full Open – Off Verify Softdock – Off Verify Full Close – On Verify Capture1 – On Verify Capture2 – On
<u>VERIFYING SSRMS PREREQUISITES FOR EFU CAPTURE</u>
 On SSRMS operator, "GO for [X1] Capture Latch Open, JLE has been grappled."</u>

On **SSIPC** GO for EFU Capture Latch Open:

PCS MSS: SSRMS SSRMS

SLT

Verify all joints - Limped

MSS: SSRMS: Tip LEE

Verify 'Snare' Close, Capture (two) – blue Verify 'Carriage' Retract – blue

6. PERFORMING EFU CAPTURE LATCH OPEN

6.1 <u>Selecting EFU (AOS/M)</u> JEF: Mech: PLX: **[X1]** JEF Mech **[X1]** Stat

sel Select - Cmd (Refer to Figure 1.)

JEF Mech [X1] Select Cmd

cmd Select Execute

JEF Mech [X1] Stat

Verify Health – Normal Verify Select – Selected

6.2 Performing Softdock from Close (AOS/M)

NOTE

EFU motion from close to softdock takes ~5:35 to complete.

JEF Mech [X1] Stat

sel Softdock - Cmd (Refer to Figure 1.)

JEF Mech [X1] Action Cmd

cmd Softdock Ovrd Execute

JEF Mech [X1] Stat

Verify Full Open – Off Verify Softdock – On

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Verify Full Close – Off Verify Capture1 – Off Verify Capture2 – Off

6.3 Performing Open (AOS/M)

<u>NOTE</u>

EFU motion from softdock to open takes ~2:56 to complete.

JEF Mech [X1] Stat

sel Full Open – Cmd (Refer to Figure 1.)

JEF Mech [X1] Action Cmd

cmd Release Ovrd Execute

JEF Mech [X1] Stat

Verify Full Open – On Verify Softdock – Off

Notify SSRMS operator, "Go to unberth JLE, EFU arms have been opened."

- 7. <u>PERFORMING EFU CAPTURE LATCH CLOSE</u> On SSIPC GO, proceed to step 7.1.
 - 7.1 Performing Softdock from Open

NOTE

EFU motion from open to softdock takes ~2:37 to complete.

JEF Mech [X1] Stat

sel Softdock – Cmd (Refer to Figure 1.)

JEF Mech [X1] Action Cmd

cmd Softdock Execute

JEF Mech [X1] Stat

Verify Full Open – Off Verify Softdock – On Verify Full Close – Off

7.2 Performing Close

 $\frac{\text{NOTE}}{\text{EFU motion from softdock to close takes} \sim 5:54 \text{ to complete.}}$

1.302 EFU10(9) OPS FOR JLE UNBERTHING - SLT/PCS

(ASSY OPS/2JA/FIN/HC)

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JEF Mech [X1] Stat

sel Full Close - Cmd (Refer to Figure 1.)

JEF Mech [X1] Action Cmd

cmd Capture Execute

JEF Mech [X1] Stat

Verify Full Close – On

8. <u>POWERING OFF EDU</u> JEF: Mech: PLX: EDU JEF Mech EDU Stat '**[Y1]**' (Refer to Table 2.)

sel PDB RPC Posn - Cmd

JEF EPS [Z1] Cmd

cmd RPC Open Execute

JEF Mech EDU Stat

Verify PDB RPC Posn – Open

If EVA crew is in the vicinity of designated EFU

Notify EVA crew the designated EFU has been powered off, so the keepout zone around the EFU has been removed.

9. JEF OPS MODE TRANSITION AFTER EFU CAPTURE

JEF: EPS

Verify JEF Ops Mode – P/L Exchange

sel JEF Ops Mode

JEF Sel Ops Mode Cmd

cmd PL_Ops_Enable Execute

JEF EPS

Verify JEF Ops Mode – PL_Ops_Enable

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2.100 JPM TO JEF 1553 JUMPER RECONFIGURATION

(ASSY OPS/2J/A/FIN)

Page 1 of 5 pages

OBJECTIVE:

After JEF is berthed to JPM, JEM SLBus 2, PLBus 2, and Local Bus JEM are connected to JEF.

LOCATION:

JPM1F7

JPM1A7

DURATION:

60 minutes

10 minutes for Preparation

15 minutes for JEM SLBus 2 Ch b, PLBus 2 Ch a and Local Bus JEM Ch a jumper

20 minutes for JEM SLBus 2 Ch a, PLBus 2 Ch b and Local Bus JEM Ch b jumper

15 minutes for Closeout

CREW:

One

TOOLS:

Digital Camera

ISS IVA Toolbox:

Drawer 2:

5/32" Hex Head, 1/4" Drive

Ratchet, 1/4" Drive

(10-50 in-lbs) Trq Wrench, 1/4" Drive

Drawer 3:

Inspection Mirror

Drawer 5:

Static Wrist Tether

2.100 JPM TO JEF 1553 JUMPER RECONFIGURATION (ASSY OPS/2J/A/FIN) Page 2 of 5 pages

JPM Port Endcone Connector Plate behind JPM1F7-10 P1672 J1672 JEM PLBus 2 Ch a EFBM Local Bus JEM Ch a (Fwd From Node 2 Local Bus JEM Ch a (Rtn) JEM SLBus 2 Ch a J1672A \supset Terminator P2672 J2672 JEM SLBus 2 Ch b JEM PLBus 2 Ch b Local Bus JEM Ch b (Fwd) EFBM From Node 2 Local Bus JEM Ch b (Rtn) J2672A Terminator Connector Plate behind JPM1A7-10

Figure 1. JEM SLBus 2, PLBus 2 and Local Bus JEM Jumpers Connection.



Figure 2. JPM1A7-10 and JPM1F7-10 Closeout Panel.

2.100 JPM TO JEF 1553 JUMPER RECONFIGURATION

(ASSY OPS/2J/A/FIN)

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Figure 3. Connector Plate behind JPM1F7-10.



Figure 4. Connectors Plate behind JPM1A7-10.

NOTE

- 1. **SSIPC** and **MCC-H** switch 1553B bus channel (a or b) to avoid 1553B bus FDIR initiation prior to each jumper reconfiguration.
- 2. SSIPC and MCC-H checkout JEM SLBus 2, PLBus 2 and Local Bus JEM communication status after each jumper reconfiguration.
- 3. Inspection Mirror may be needed to confirm connector labels.

2.100 JPM TO JEF 1553 JUMPER RECONFIGURATION

(ASSY OPS/2J/A/FIN)

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1. <u>RECONFIGURING JEM SLBUS 2 CH B, PLBUS 2 CH A AND LOCAL BUS</u> JEM CH A JUMPER (P1672)

JPM1F7

- 1.1 Remove Closeout Panel (JPM1F7-10), fasteners (seven) (Ratchet, 1/4" Drive; 5/32" Hex Head, 1/4" Drive).
 Temporarily stow.
 Refer to Figure 2.
 - 1.2 Don Static Wrist Tether. Secure to an unpainted, unanodized metal surface.
 - 1.3 On **SSIPC** GO P1672 $\leftarrow \mid \rightarrow$ J1672A Protective Cap $\leftarrow \mid \rightarrow$ J1672 Protective Cap $\rightarrow \mid \leftarrow$ J1672A P1672 $\rightarrow \mid \leftarrow$ J1672 Refer to Figure 3.
 - 1.4 Doff Static Wrist Tether.
 - 1.5 Notify **SSIPC** of JEM SLBus 2 Ch b, PLBus 2 Ch a and Local Bus JEM Ch a jumper reconfiguration completion.
- 2. <u>RECONFIGURING JEM SLBUS 2 CH A, PLBUS 2 CH B AND LOCAL BUS</u> JEM CH B JUMPER (P2672)

JPM1A7

- 2.1 Remove Closeout Panel (JPM1A7-10), fasteners (eighteen) (Ratchet, 1/4" Drive; 5/32" Hex Head, 1/4" Drive).
 Temporarily stow.
 Refer to Figure 2.
 - 2.2 Don Static Wrist Tether. Secure to an unpainted, unanodized metal surface.
 - 2.3 On **SSIPC** GO P2672 ←|→ J2672A Protective Cap ←|→ J2672 Protective Cap →|← J2672A P2672 →|← J2672 Refer to Figure 4.
 - 2.4 Doff Static Wrist Tether.
 - 2.5 Notify **SSIPC** of JEM SLBus 2 Ch a, PLBus 2 Ch b and Local Bus JEM Ch b jumper reconfiguration completion.
- 3. <u>CLOSEOUT</u>
 - 3.1 On **SSIPC** GO Check for FOD within 1 m.
 - 3.2 Photo document all newly configured hardware (Digital Camera).
 - 3.3 Install Closeout Panel (JPM1A7-10).

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|--------------------|-----|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--|
| | | Tighten, torque fasteners at each corner of Closeout Panel (one per corner, total four) to 27 in-lbs [Ratchet, 1/4" Drive; 5/32" Hex Head, 1/4" Drive; (10-50 in-lbs) Trq Wrench, 1/4" Drive]. | |
| JPM1F7 | 3.4 | Check for FOD within 1 m. | |
| | 3.5 | Photo document all newly configured hardware (Digital Camera). | |

- 3.6 Install Closeout Panel (JPM1F7-10). Tighten, torque fasteners at each corner of Closeout Panel (one per corner, total four) to 27 in-lbs [Ratchet, 1/4" Drive; 5/32" Hex Head, 1/4" Drive; (10-50 in-lbs) Trq Wrench, 1/4" Drive].
- 3.7 Notify **SSIPC** of task completion. Stow tools.

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A&C CONTINGENCY

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OBJECTIVE:

Install EFBM Contingency Sensor Cable between Exposed Facility Berthing Mechanism (EFBM) and Berthing Mechanism Electronics Package (BEP) in order to intentionally open the circuit for a failed limit switch by cutting the corresponding signal line.

LOCATIONS:

JPM1D7

DURATION:

1 hour 25 minutes

10 minutes for Preparation

20 minutes for Cutting limit switch line (step 1)

25 minutes for Installing EFBM Contingency Sensor Cable (steps 2 and 3)

15 minutes for Checkout (steps 4 and 5)

15 minutes for Closeout (step 6)

CREW:

One

PARTS:

EFBM Contingency Sensor Cable P/N USE0923-101

MATERIALS:

Kapton Tape

TOOLS:

Digital Camera

Pocket Knife

Mini-Maglite (if required)

ISS IVA Toolbox:

Drawer 2:

5/32" Hex Head, 1/4" Drive

Ratchet, 1/4" Drive

(10-50 in-lbs) Trq Wrench, 1/4" Drive

Drawer 4:

Wire Cutters

Drawer 5:

Static Wrist Tether

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1. <u>CUTTING LIMIT SWITCH SIGNAL LINE ON EFBM CONTINGENCY</u> <u>SENSOR CABLE</u>

NOTE

Signal lines are marked both "BLU RF" and "WHT RF" on each line such as "CL1 BLU RF" and "CL1 WHT RF". "BLU RF" and "WHT RF" are left out in this procedure.



Figure 1. Marking on Limit Switch Signal Lines.

| Label (Marking) | Function (Limit Switch Signal Line for) | Check |
|-----------------|-----------------------------------------|-------|
| CL1 | Capture Latch 1 | |
| CL2 | Capture Latch 2 | |
| CL3 | Capture Latch 3 | |
| CL4 | Capture Latch 4 | |
| SL1 | Structure Latch 1 | |
| SL2 | Structure Latch 2 | |
| SL3 | Structure Latch 3 | |
| SL4 | Structure Latch 4 | |
| UMB1 | Umbilical Latch 1 | |
| UMB2 | Umbilical Latch 2 | |

| Table T. Limit Switch Lines Information |
|-----------------------------------------|
|-----------------------------------------|

- 1.1 ✓SSIPC which limit switch signal line on Table 1 should be cut Record in Table 1.
- 1.2 Cut the selected line (Wire Cutters).

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Figure 2. Cross Section of the Cut Line.



Figure 3. Peeled Outer Insulation and Shields.

<u>NOTE</u>

Step 1.3 will be performed to avoid contact between Signal lines and Shields.

- 1.3 Treatment for Cut Line Near Connector P4 (Bent End)
 - 1.3.1 Cut Outer Insulation and Shields 10 mm (0.5 inch) along the dotted lines (pink colored) shown in Figures 2 and 3 (Wire Cutters, Pocket Knife).

Peel back Outer Insulation and Shields.

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Wrap around the peeled Outer Insulation and Shields (Kapton Tape).

- 1.3.2 Cover the ends of signal line (metal wires) (two) separately, isolating each from any other metal wires (Kapton Tape).
- 1.4 <u>Treatment for Cut Line Near Connector J004B (Straight End)</u> Cover the end of the cut line (Kapton Tape).
- 1.5 Repeat <u>steps 1.3</u> and <u>1.4</u> for the remaining cut lines.
- 1.6 Photo document the EFBM Contingency Sensor Cable (Digital Camera).
- 2. ACCESS TO BEP UNDER JEM AIRLOCK
 - 2.1 <u>Safing for Access to BEP</u> ✓**SSIPC**, BEP is deactivated and allow BEP to cool for 80 minutes

CAUTION

Care must be taken not to damage thin harnesses routed on JPM structure. Examples of thin harnesses are shown in Figures 2 and 3.

Some fasteners on Closeout Panel are hidden by Beta Cloth Closeout

JEM Airlock



Figure 4. Closeout Panel JPM1D7-07 to Access BEP.

JPM1D7

2.2 Partially remove Beta Cloth Closeout attached to Closeout Panel JPM1D7-07 at side of JEM Airlock, Velcro. Refer to Figure 4.

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- 2.3 Remove Closeout Panel JPM1D7-07, fasteners (nineteen) (Ratchet, 1/4" Drive; 5/32" Hex Head, 1/4" Drive).
 Temporarily stow.
 Refer to Figure 4.
- 2.4 Partially remove FDS Partition, Velcro.
- 3. INSTALLING EFBM CONTINGENCY SENSOR CABLE



Figure 5. J4 Connector on BEP.

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EFBM Contingency Sensor Cable

Figure 6. Image of EFBM Contingency Sensor Cable Insertion.

- 3.1 Don Static Wrist Tether. Attach clip to unpainted, unanodized metal structure.
- 3.2 Wire harness (P004B) $\leftarrow | \rightarrow J4$ on BEP Refer to Figures 5 and 6.
- 3.3 EFBM Contingency Sensor Cable J004B to Wire harness P004B (straight end) →|← Wire harness (P004B)
- 3.4 EFBM Contingency Sensor Cable P4 to BEP J4 (bent end) →|← J4 on BEP
- 3.5 Doff Static Wrist Tether.
- 3.6 Photo document the connection of EFBM Contingency Sensor Cable (Digital Camera).
- 3.7 ISS **↓** SSIPC EFBM Contingency Sensor Cable connection is completed.
- 4. VERIFYING BCDU STATUS

| 4.1 | Powering On BEP |
|-----|------------------------------|
| | JPM: EPS: Main: PDB a2: RPC1 |
| | JPM EPS PDB a2 RPC1 Cmd |

cmd RPC Close Ovrd Execute

JPM EPS PDB a2

Verify RPC1 (BEP) - Close

BCDU 4.2 <u>Verifying BCDU LED</u> Verify the following status:

PWR - On

SLT

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INTLK – On

'MODE'

CONNECT - On

'ACTUATOR STATUS'

READY - On

- 4.3 ISS ↓ **SSIPC** LED status
- 4.4 **✓SSIPC** the expected other LED status after failed limit switch recovery.
- 4.5 Photo document BCDU overview and LED status (Digital Camera).
- 4.6 **✓SSIPC**, BEP deactivation is required

If BEP deactivation is required,

JEM: JPM: EPS: Main: PDB a2: RPC1 JPM EPS PDB a2 RPC1 Cmd

cmd RPC Open Execute

JEM: JPM: EPS: Main: PDB a2

Verify RPC1 (BEP) – Open

- 5. <u>CLOSE OUT</u>
 - 5.1 Check for FOD within 1m around BEP.
 - 5.2 Attach FDS Partition, Velcro.
- JPM1D7 5.3 Tighten, torque fasteners (four) at each corner of Closeout Panel JPM1D7-07, to 27 in-lbs [Ratchet, 1/4" Drive; 5/32" Hex Head, 1/4" Drive; (10-50 in-lbs) Trq Wrench, 1/4" Drive]. Refer to Figure 4.
 - 5.4 Attach Beta Cloth Closeout onto Closeout Panel JPM1D7-07, Velcro. Refer to Figure 4.
 - 5.5 Notify **SSIPC** of task completion. Stow all tools. Update IMS.

SLT

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OBJECTIVE:

Connect power cables from UOP to Exposed Facility Berthing Mechanism (EFBM) Berthing Mechanism Electronics Package (BEP) to provide contingency power.

LOCATIONS:

JPM

DURATION:

40 minutes for Contingency Power Supply

10 minutes for Preparation

10 minutes for Cable assembly and connection to UOP (steps 1 and 2)

5 minutes for Removing Closeout Panel (step 3)

5 minutes for Connecting cable to BEP Interface Panel (step 4)

5 minutes for EFBM Checkout (step 5)

5 minutes for Current Probe Relocation (step 6)

35 minutes for Closeout after completion of EFBM Ops (step 7)

5 minutes for Preparation

20 minutes for Cable disconnections

10 minutes for Closeout

CREW:

One

PARTS:

MKAK Power Cable 1 P/N 80A89021-101

EFBM Contingency Power Cable P/N 80A89028-101

Protective Cap P/N 660-024M17N

TOOLS:

Digital Camera

Mini-Maglite (if required)

ISS IVA Toolbox:

Drawer 2:

5/32" Hex Head, 1/4" Drive

Ratchet, 1/4" Drive

(10-50 in-lbs) Trq Wrench, 1/4" Drive

Drawer 5:

Static Wrist Tether

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2.4 Doff Static Wrist Tether.

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3. ACCESSING INTERFACE PANEL

Figure 2. JPM1D7-08 Area Hazardous Equipment Location.

WARNING Metal flexible hose for VVPV may have sharp edges. When accessing EFBM Power cable to prevent injury, care must be taken.

JPM1D7 3.1 If

1 If required,

19 MAY 09

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Remove Closeout Panel JPM1D7-08, fasteners (one per a corner, total four) (Ratchet, 1/4" Drive; 5/32" Hex Head).

Secure to nearby rack front.

Refer to Figure 2.



Figure 3. Interface Panel - Looking From Fwd to Aft.

- 3.2 Partially remove FDS Partition, Velcro. Refer to Figure 3.
- 4. <u>CONNECTING EFBM CONTINGENCY POWER CABLE TO BEP POWER</u> <u>CABLE</u>
 - 4.1 Remove Scopemeter and Current Probe from W1009 cable. Temporarily stow.
 - 4.2 <u>Verifying No Power to BEP</u> ✓SSIPC, PDB a2 RPC 1 (BEP) opened.
 - 4.3 Don Static Wrist Tether. Attach clip to unpainted, unanodized metal structure.
 - 4.4 W1009 P1581 ← |→ PDB I/F FOR BM (J007B) on Interface Panel Protective Cap (P/N 660-024M17N) → |← W1009 P1581 Refer to Figure 3.
 - 4.5 Tethered Protective Cap ←|→ EFBM Contingency Power Cable P13 TO JPM J007B

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EFBM Contingency Power Cable P13 TO JPM J007B →|← PDB I/F FOR BM (J007B) on Interface Panel

4.6 Doff Static Wrist Tether.

WARNING If the crew is around Active EFBM, the following EFBM checkout from step 5 may cause shearing/pinching hazard to EVA crew.

5. EFBM CHECKOUT

| JPM1D7 | 5.1 | If BCDU is not connected to BEP, |
|--------|-----|-------------------------------------------------------------------------------------------------------------------------|
| | | 5.1.1 If EVA is in progress, |
| | | Notify EVA crew not to enter the keep-out zone around Active EFBM. |
| | | 5.1.2 Don Static Wrist Tether. Attach clip to unpainted, unanodized metal surface. |
| | | 5.1.3 Tethered Protective Cap ← → P011B on Jumper Cable (80AS51500-213) |
| | | Tethered Protective Cap ← → BCDU I/F FOR BM(J011B) on JPM 1/P7-106 |
| | | P011B on Jumper Cable (80AS51500-213) → ← BCDU I/F FOR BM (J011B) on JPM 1/P7-106 |
| | | 5.1.4 Doff Static Wrist Tether. |
| UOP | 5.2 | Powering On BEP POWER OUT → Press ✓POWER OUT – ENABLE (illuminated green) ✓FAULT/TEST – OK (illuminated green) |
| BCDU | 5.3 | <u>Verifying BCDU Status</u> Verify the following status |
| | | PWR – On INTLK – On |
| | | 'MODE' |
| | | CONNECT – On |
| | | 'ACTUATOR STATUS' |
| | | READY – On |

5.4 ISS U SSIPC BCDU LED status

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5.5 **✓SSIPC**, BEP deactivation is required

UOP

If BEP deactivation is required,

pb POWER OUT → Press (Press pushbutton to release)

Verify POWER OUT – RESET (illuminated) Verify FAULT/TEST – not illuminated

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6. <u>RELOCATING SCOPEMETER CURRENT PROBE TO EFBM</u> <u>CONTINGENCY POWER CABLE</u>







Grip Scopemeter Current Probe, open jaws.

Place wire EFBM Contingency Power Cable in notch of Scopemeter Current Probe, close jaws.

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Verify Current Flow Arrow orientation is as shown in Figure 4.

- 7. CLOSEOUT AFTER COMPLETION OF EFBM OPS
 - 7.1 Remove Scopemeter and Current Probe. Temporarily stow.
 - 7.2 <u>Verifying No Power Applied to Original Power Cable W1009 for BEP</u> ✓SSIPC, PDB a2 RPC 1 (BEP) opened

UOP

- 7.3 Checking No Power Applied to J3, J4 Of UOP
 ✓POWER OUT RESET illuminated
 ✓FAULT/TEST not illuminated
- 7.4 Don Static Wrist Tether. Attach clip to unpainted, unanodized metal structure.
- 7.5 Disconnecting MKAK Power Cable 1 From UOP
 P1 TO UOP ←|→ UOP
 Tethered Protective Cap →|← P1 TO UOP
 Tethered Protective Cap →|← J3(J4) on UOP

JPM1D7

- 7.6 <u>Disconnecting EFBM Contingency Power Cable</u>
 EFBM Contingency Power Cable P13 TO JPM J007B ← |→ PDB I/F
 FOR BM (J007B) on Interface Panel
- 7.7 <u>Reconnecting Original Power Cable W1009 to BEP</u> Protective Cap ←|→ W1009 P1581 Temporarily stow Protective Cap.

W1009 P1581 →|← PDB I/F FOR BM (J007B) on Interface Panel

- 7.8 Doff Static Wrist Tether.
- 7.9 Install FDS Partition, Velcro. Refer to Figure 3.
- 7.10 Check for FOD within 1m. Photo-document all newly installed hardware (Digital Camera).
- 7.11 <u>Installing Closeout Panel</u>
 Tighten, torque fasteners (four) at each corner of Closeout Panel
 JPM1D7-08, to 27 in-lbs [Ratchet, 1/4" Drive; 5/32" Hex Head; (10-50 in-lbs) Trg Wrench].

Refer to Figure 2.

7.12 <u>Folding Cables For Stowing</u> Demate EFBM Contingency Power Cable from MKAK Power Cable 1.

Mate Tethered Protective Caps to EFBM Contingency Power Cable and MKAK Power Cable 1.

Coil cables about 40 cm diameters, Velcro straps.

7.13 Notify **SSIPC**, closeout is complete. Stow all tools and equipment.

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OBJECTIVE:

Activate JEF PDB a and b, ESC a, HCE a by SLT. This procedure is a backup procedure to be executed by crew in case **SSIPC** is unable to perform <u>1.503 JEF ACTIVATION - SSIPC</u>. The goal of this procedure is to start temp control with HCE a and provide TVC and PTU heater power so that JEF can be kept alive.

DURATION:

60 minutes

CREW:

One

- NOTE 1. JEF PDB a, ESC a and HCE a powering on temperature is higher than -35 °C. If temperatures are lower than -35 °C, the JEF activation heater should be activated, and wait until temperatures indicates higher than -35 °C. 2. Temperature above can not be monitored at SLT; therefore, **SSIPC** will determine if activation heater will need to be turned on or not. 1. VERIFYING JEF PDB a, ESC a AND HCE a TEMPERATURES ✓SSIPC if JEF activation heater is needed If **SSIPC** request to power on the JEF activation heater, JPM: EPS: Main: PDB a1: RPC7 JPM EPS PDB a1 RPC7 Cmd cmd RPC Close Execute * JPM EPS PDB a1 Verify RPC7 – Cl * * Notify SSIPC JEF activation heater power on was completed. * * Wait until SSIPC GO. 2. VERIFYING JEF MODE STATUS JEM Verify JEF Mode – Manual POWERING ON JEF PDB a AND JEF PDB b 3.
 - 3.1 <u>Powering On JEF PDB a</u> JPM: EPS: Main: PDU a1: JEF PDB a: FWC JEF EPS PDB a FWC Stat 'PDU RPC Position'

SLT

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sel Cmd

JPM EPS PDU a1 RPC1 Cmd

cmd 25A-RPC Close Execute

JEF EPS PDB a FWC Stat

Verify PDU RPC Position – 25A Close

If JEF activation heater was activated in step 1, omit step 3.2.

3.2 <u>Powering On JEF PDB b</u> JPM: EPS: Main: PDU b1: JEF PDB b: FWC JEF EPS PDB b FWC Stat 'PDU RPC Position'

sel Cmd

JPM EPS PDU b1 RPC1 Cmd

cmd 25A-RPC Close Execute

JEF EPS PDB b FWC Stat

Verify RPC Position – 25A Close

4. ACTIVATING ESC a

NOTE

After ESC a power on command is issued, it takes approximately 6 minutes to verify ESC a Power On BIT status in step 4.1, and approximately 9 minutes for JEF PDB a status in step 4.2.

4.1 <u>Powering On ESC a</u> JEF: CDH: SLBus2: ESC a JEF CDH ESC a Stat 'PDB RPC Position'

sel Cmd

JEF EPS PDB a RPC1 Cmd

cmd RPC Close Execute

JEF CDH ESC a Stat

Verify PDB RPC Position – Close Verify JCP/ESC Comm Status – OK Verify BIT Status – Valid Verify BIT Result – Normal

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Verify Health Status – Normal

JEF: CDH JEF CDH

Verify JEF Ops Mode – Standby

4.2 <u>Verifying JEF PDB a Status</u> JEF: EPS: PDB a: FWC JEF EPS PDB a FWC Stat

> Verify BIT Status – Valid Verify BIT Result – Normal Verify Health Status – Normal

4.3 <u>Verifying JEF PDB b Status</u> If JEF PDB b was not activated in step 3.2, JEF: EPS: PDB b: FWC JEF EPS PDB b FWC Stat

> Verify BIT Status – Valid Verify BIT Result – Normal Verify Health Status – Normal

If JEF PDB b was not activated in step 3.2, JEF: EPS: PDB b: FWC JEF EPS PDB b FWC Stat

Verify BIT Status – Valid Verify BIT Result – Failure Verify Health Status – Failure

- 5. ACTIVATING HCE a
 - 5.1 <u>Transitioning JEF Ops Mode to Preservation</u> JEF: TCS: JEF Ops Mode JEF Sel Ops Mode Cmd

cmd JEF Preservation Execute

JEF TCS

Verify JEF Ops Mode – Preservation

NOTE

After HCE a power on command is issued, HCE a Power On BIT takes approximately 1 minute in step 5.3.

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5.2 <u>Powering On HCE a</u> JEF: TCS: PTCS a: HCE a: FWC JEF TCS HCE a FWC Stat 'PDB RPC Position'

sel Cmd

JEF EPS PDB a RPC8 Cmd

cmd RPC Close Execute

JEF TCS HCE a FWC Stat

Verify PDB RPC Position – Close

- 5.3 <u>Verifying HCE a Power On BIT Status</u> Verify BIT Status – Valid Verify BIT Result – Normal Verify Health Status – Normal
- 5.4 <u>Starting HCE a Heater Control</u> JEF: TCS: PTCS a: HCE a: FWC JEF TCS HCE a FWC Stat 'Sys Htr Cntl Status'

.

sel Cmd

JEF TCS HCE a Sys Htr Cmd

cmd Auto Execute

JEF TCS HCE a FWC Stat

Verify Sys Htr Cntl Status - Auto

JEF: TCS: PTCS a: HCE a

JEF TCS HCE a

- Verify RPC1 Cl Verify RPC2 – Cl Verify RPC3 – Cl Verify RPC4 – Cl Verify RPC5 – Cl Verify RPC6 – Cl
- 5.5 <u>Verifying HCE a Heater Control Status</u> Verify SW4 – Auto Verify SW5 – Auto Verify SW6 – Auto Verify SW12 – Auto Verify SW13 – Auto

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Verify SW15 – Auto Verify SW16 – Auto Verify SW1 – Auto Verify SW3 – Auto Verify SW31 – Control Off Verify SW2 – Auto Verify SW7 – Auto Verify SW8 – Auto Verify SW9 – Auto Verify SW10 – Auto Verify SW11 – Auto Verify SW14 – Auto

NOTE

HCE a does not provide heater power to the external TVCs and PTUs, which are not yet moved to the on-orbit positions.

6. <u>SHUTTING OFF TVC AND PTU HEATER AT ON-ORBIT LOCATION</u>

6.1 <u>Shutting Off TVC and PTU EF A Heater</u> JEF: TCS: PTCS a: TVC/PTU A: Cmd JEF TCS HCE a Sw9 Cmd

cmd Control Off Execute

JEF TCS PTCSa TVCPTU A Htr Stat

Verify Control Status – Off Verify HCE Switch Position – Open

6.2 <u>Shutting Off TVC and PTU EF F Heater</u> JEF: TCS: PTCS a: TVC/PTU F: Cmd JEF TCS HCE a Sw11 Cmd

cmd Control Off Execute

JEF TCS PTCSa TVCPTU F Htr Stat

Verify Control Status – Off Verify HCE Switch Position – Open

If JEF PDB b was activated in step 3.2, omit step 7, 8.

7. <u>POWERING OFF JEF ACTIVATION HEATER</u> JPM: EPS: Main: PDB a1: RPC7 JPM EPS PDB a1 RPC7 Cmd

cmd RPC Open Execute

JPM EPS PDB a1

Verify RPC 7 – Op

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8. POWERING ON JEF PDB b

<u>NOTE</u> Wait until JEF PDB b warm up by HCE a heater is completed.

8.1 <u>Powering On JEF PDB b</u> On SSIPC GO

> JPM: EPS: Main: PDU b1: JEF PDB b: FWC JEF EPS PDB b FWC Stat 'PDU RPC Position'

sel Cmd

JPM EPS PDU b1 RPC1 Cmd

cmd 25A-RPC Close Execute

JEF EPS PDB b FWC Stat

Verify RPC Position – 25A Close

8.2 <u>Start Sampling JEF PDB b</u> JEF: CDH: SLBus 2: ESC a JEF CDH ESC a Stat 'ESC/JEF PDB b Comm Status'

sel Cmd

JEF CDH ESC JEF PDB b Comm Cmd

cmd Start Communication Execute

JEF: EPS: PDB b: FWC

Verify BIT Status – Valid Verify BIT Result – Normal Verify Health Status – Normal

9. ACTIVATING TVC AND PTU EF F, A HEATER IN LAUNCH LOCATION

NOTE

Heater power is supplied through LTAB with ISS2 Mode Plug to the external TVCs and PTUs, which remain in their launch positions.

JEF: EPS: PDB b: RPC26 JEF EPS PDB b RPC26 Cmd

cmd RPC Close Execute
3.104 JEF ACTIVATION TO KEEP ALIVE - SLT

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JEF EPS PDB b

Verify RPC26 – Cl

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OBJECTIVE:

Reconfigure ICS Jumpers for communicating with Inter-orbit Communication System - Exposed Facility (ICS-EF) at backup port, Exposed Facility Unit (EFU) #5.

LOCATION:

JPM1O4 (ICS Rack)

DURATION:

30 minutes

CREW:

One

PARTS:

Ziplock Bag labeled "ICS 1553 I/F Cable"

ICS 1553 I/F Cable 5A P/N: S4899A B/N: ICS1555AN

ICS 1553 I/F Cable 5B P/N: S4901A B/N: ICS1555BN

TOOLS:

Digital Camera

ISS IVA Toolbox:

Drawer 5:

Static Wrist Tether

- 1. PREPARATION
 - 1.1 **✓SSIPC** to verify ICS-PM is deactivated
 - 1.2 Verify Name and Barcode number on IMS label: ICS 1553 I/F Cable 5A, B/N: ICS1555AN ICS 1553 I/F Cable 5B, B/N: ICS1555BN
 - 1.3 <u>Removing Rack UIP Closeout</u>

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Figure 1. Rack UIP Closeout "ICS Rack Lower Closeout".

JPM1O4

Open the rack side of ICS Rack Lower Closeout, Snap fasteners (two), Velcro. Refer to Figure 1.

- 1.4 Don Static Wrist Tether. Secure to unpainted, unanodized metal surface.
- 2. EXCHANGING 1553 I/F CABLE 7A, 7B WITH 5A, 5B

<u>NOTE</u> Figure 2 and Tables 1, 2 should be referred to in <u>step 2</u>.

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Figure 2. Connection of ICS 1553 Cables on ICS Rack UIP and Z-Panel.

| Cable Label | Label on Connector | Label on Connector |
|--------------|--------------------|--------------------|
| | to Rack UIP | to Z-Panel |
| ICS 1553 I/F | P273 | P173 |
| Cable 7A | TO CONNECTOR PANEL | TO UTILITY PANEL |
| | J203 | J3 |
| ICS 1553 I/F | P274 | P174 |
| Cable 7B | TO CONNECTOR PANEL | TO UTILITY PANEL |
| | J204 | J4 |

Table 1. 1553B Cables for EFU #7 (to be removed)

Table 2. 1553B Cables for EFU #5 (to be installed)

| 10. | Table 2. Tood Cables for $E = 0 \# 0$ (to be installed) | | | | |
|--------------|---------------------------------------------------------|--------------------|--|--|--|
| Cable Label | Label on Connector | Label on Connector | | | |
| | to Rack UIP | to Z-Panel | | | |
| ICS 1553 I/F | P253 | P153 | | | |
| Cable 5A | TO CONNECTOR PANEL | TO UTILITY PANEL | | | |
| | J203 | J3 | | | |
| ICS 1553 I/F | P254 | P154 | | | |
| Cable 5B | TO CONNECTOR PANEL | TO UTILITY PANEL | | | |
| | J204 | J4 | | | |

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- 2.1 Removing ICS 1553 I/F Cable 7A P273 $\leftarrow | \rightarrow$ J203 on Rack UIP P173 $\leftarrow | \rightarrow$ J3 on Z-Panel
- 2.2 Installing ICS 1553 I/F Cable 5A Pink plastic caps (two) ←|→ ICS 1553 I/F Cable 5A P253 →|← J203 on Rack UIP P153 →|← J3 on Z-Panel
- 2.3 Mate pink plastic caps (two) removed from ICS 1553 I/F Cable 5A to ICS 1553 I/F Cable 7A. Stow ICS 1553 I/F Cable 7A in Ziplock Bag labeled "ICS 1553 I/F Cable".
- 2.4 Removing ICS 1553 I/F Cable 7B P274 $\leftarrow \mid \rightarrow$ J204 on Rack UIP P174 $\leftarrow \mid \rightarrow$ J4 on Z-Panel
- 2.5 Installing ICS 1553 I/F Cable 5B
 Pink plastic caps (two) ←|→ ICS 1553 I/F Cable 5B
 P254 →|← J204 on Rack UIP
 P154 →|← J4 on Z-Panel
- 2.6 Mate pink plastic caps (two) removed from ICS 1553 I/F Cable 5B to ICS 1553 I/F Cable 7B.
 Stow ICS 1553 I/F Cable 7B in Ziplock Bag labeled "ICS 1553 I/F Cable".
- 3. EXCHANGING CONNECTION BETWEEN J251 AND J504

CAUTION Do not touch coaxial contact pins of P251 and P504 connectors.



Figure 3. J251 and J504 Connectors on ICS Rack UIP.

| Cable Function | Label on Connector | From | | То |
|----------------|--------------------|------|----------|------|
| | to Rack UIP | | | |
| | P251 | J251 | → | J504 |
| | TO CONNECTOR PANEL | | | |
| ICS-PM/ICS-EF | J251 | | | |
| Data line | P504 | J504 | → | J251 |
| | TO CONNECTOR PANEL | | | |
| | J504 | | | |

| Table 3. IC | CS-PM/ICS-EF | Data Cable | Connection | Exchange |
|-------------|--------------|------------|------------|----------|
| | | | | |

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P251 ←| \rightarrow J251 on Rack UIP P504 ←| \rightarrow J504 on Rack UIP

P504 →|← J251 on Rack UIP P251 →|← J504 on Rack UIP Refer to Figure 3 and Table 3.

- 4. CLOSE OUT
 - 4.1 Doff Static Wrist Tether.
 - 4.2 Check for FOD within 1 m radius.
 - 4.3 Photo document new jumper connection on Rack UIP and Z-Panel (Digital Camera).
 - 4.4 Close ICS Rack Lower Closeout, Snap fasteners (two), Velcro. Refer to Figure 1.
 - 4.5 Notify **SSIPC** of task completion. Update IMS with stowage location of hardware.

PAYLOADS

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TOP



HOOK VELCRO

MIDDECK STATUS CHECK (ASSY OPS/2JA/FIN) Page 1 of 4 pages

OBJECTIVE:

In step 1, perform a status check on the Glacier System. In step 2 verify the Advanced Biological Research System LED Status on the front panel. In step 3, verify the Protein Crystallization Diagnostics Facility (PCDF) Process Unit LED status on the front panel. In addition, the front fan grid PCDF Process Unit will be checked and cleaned of any debris.

<u>TOOLS</u>

Gray Tape (for cleaning)

- MA16J/L 1. <u>GLACIER STATUS CHECK</u> 1.1 √cb POWER – Close (It on)
 - $1.2 \sqrt{\text{sw BATTERY} \text{ON (It on)}}$
 - 1.3 √Display 'HOME'

- * If Display '**Error Pending**'
- Perform GLACIER ERROR MESSAGE, all (SODF: ASSY
- * OPS: PAYLOADS), then:

- * If '**HOME**' not shown:

<u>NOTE</u> After door openings, CURR TEMP may be out of range ramping toward set point.

- 1.4. If ascent Glacier S/N tbd $\sqrt{\text{Display} \text{'CURR TEMP:'}}$ is +4.0°C ± 5.0°C.
- 1.5 If descent Glacier S/N tbd $\sqrt{\text{Display} \text{'CURR TEMP:'}}$ is -95°C ± 5.0°C.
- 1.6. Log from Glacier front panel '**GPS**', '**CURR TEMP**' in Table 1 Glacier Log.
- 1.7 $\sqrt{MCC-H}$ of data recorded in Table 1 and any off-nominal conditions.

ASSY OPS-1a/2JA/A







MIDDECK STATUS CHECK (ASSY OPS/2JA/FIN) Pa

Page 2 of 4 pages

| Table | 1. | Glacier | Log |
|-------|----|---------|-----|
|-------|----|---------|-----|

| GPS | CURR TEMP | GPS | CURR TEMP |
|-----|-----------|-----|-----------|
| /: | °C | | °C |
| /: | °C | /: | °C |
| /: | °C | /: | °C |
| /: | °C | /: | °C |
| /: | °C | /: | °C |
| /: | °C | /: | °C |
| /: | °C | /: | °C |
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| /: | °C | /: | °C |
| /: | °C | /: | °C |
| /: | °C | /: | °C |
| /: | °C | /: | °C |

ASSY OPS-1b/2JA/A

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HOOK VELCRO

HOOK VELCRO

MIDDECK STATUS CHECK

(ASSY OPS/2JA/FIN) Page 3 of 4 pages

MF28E 2. ABRS STATUS CHECK 2.1 √STATUS It – green ***** If STATUS It - amber * On MCC-H GO: * * sw PWR \rightarrow OFF * $cb \ CB1 \rightarrow Open$ * Wait 30 seconds * $cb \; CB1 \rightarrow Closed$ * sw PWR \rightarrow ON * √STATUS It – green *** 2.2 $\sqrt{MCC-H}$ of status.

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ASSY OPS-1c/2JA/A

TOP





MIDDECK STATUS CHECK

(ASSY OPS/2JA/FIN) Page 4 of 4 pages

- MA16F 3. PCDF-PROCESS UNIT STATUS CHECK
 - 3.1 √EDR PWR ON It on
 - 3.2 √POWER ON It on
 - 3.3 √CONTR FAILURE It off
 - 3.4 √NOMINAL PROCESS TEMP It on
 - $3.5\sqrt{\text{STAND}}$ ALONE MODE It on

* If any of the above are not in the expected state

* Perform PCDF PROCESS UNIT OFF NOM RECOVERY

- (MDDK), all (SODF: ASSY OPS: PAYLOADS), then:
- 3.6 Verify by inspection that the PUE1 Fan (located on front center of PCDF-PU) is running.

 \sqrt{Fan} inlet and clean if required

- 3.7 Record MET: _____/ ____ and status in Table 2 PCDF Log.
- 3.8 $\sqrt{MCC-H}$ of MET and status.

| MET | STATUS |
|-----|--------|
| /: | |
| !: | |
| !: | |
| /: | |
| /: | |
| /: | |
| /: | |
| /: | |
| /: | |

Table 2. PCDF Log.

ASSY OPS-1d/2JA/A

PCDF PROCESS UNIT TRANSFER ISS TO MDDK

(ASSY OPS/2JA/FIN)

Page 1 of 3 pages

OBJECTIVE:

Transfer Protein Crystallization Diagnostics Facility (PCDF) Process Unit from Columbus to the Shuttle Middeck. This activity prepares the middeck locker to receive the payload. This activity will be performed immediately following the ESA PODF procedure which powers off, demates cables and removes PCDF Process Unit from European Drawer Rack (EDR) Locker. This activity transfers the payload to Shuttle Middeck, installs it into a middeck locker and powers it to a survival state.

LOCATION:

Removed: EDR - COL1F1

Installed: MA16F

TOOLS:

3/32" Hex Head, 1/4" Drive

1/4" Driver Handle

DURATION:

30 minutes

MA16F 1. PREP MIDDECK LOCKER

- 1.1 Verify locker empty.
- 1.2 Verify shim mounted on inside of locker door.
- 1.3 Remove ISS Internal Rear Closeout using thumb latches (two).
- 1.4 Close locker door.
- 1.5 Remove panels (three) from locker door front by rotating stud fasteners 1/4 turn CCW using 3/32" Hex Head, 1/4" Drive and 1/4" Driver Handle.
- 1.6 **✓MCC-H** middeck locker ready to receive PCDF-Process Unit.

CAUTION

To prevent loss of science, power interrupt time should not exceed 100 minutes.

COL1F1 2. PCDF PROCESS UNIT TRANSFER AND INSTALLATION INTO MDDK

- 2.1 Transfer PCDF Process Unit to Middeck.
- MA16F 2.2 Open locker door latch (two) and insert into locker.
 - 2.3 Stow slings on left and right sides of the PCDF Process Unit per Figure 1.



Figure 1. Stowing Slings

2.4 Fold Nomex wings (two) and close the Velcro per Figure 2.



Figure 2. Closing Nomex Wings and Velcro

- 2.5 Close and lock locker door latch (two).
- 3. PCDF PROCESS UNIT POWER ON
- MO13Q 3.1 ✓sw DC UTIL PWR MNB OFF
- O15:C 3.2 ✓cb MNB UTIL PWR F1/MO13Q open
- MA16F 3.3 √sw POWER OFF
 - 3.4 DC JUMPER (tbd)→|←POWER J01
- O15:C 3.5 ✓ cb MNB UTIL PWR F1/MO13Q close
- MO13Q 3.6 sw DC UTIL PWR MNB \rightarrow ON
- MA16F 3.7 sw POWER \rightarrow ON
 - 3.8 Record Power On time (GMT): _____ (___/__:___)
 - 4. VERIFY PCDF PROCESS UNIT STATUS
 - 4.1 Wait ~ 30 seconds (for system initialization)
 - 4.2 ✓EDR POWER ON It on
 - 4.3 ✓POWER ON It on
 - 4.4 ✓CONTR FAILURE It off

| 4.5 | ✓ STAND ALONE MODE It – on |
|-------------|---------------------------------------------------------------------------------------------------------------------------------------------------|
| * * * * * * | If any of the above are not in the expected state Perform <u>PCDF PROCESS UNIT OFF NOM RECOVERY</u> , all (SODF: ASSY OPS: PAYLOADS), then: |
| *** 4.6 | Record status of NOMINAL PROCESS TEMP It: |
| 4.7 | Notify MCC-H: |

Installation of PCDF Prcess Unit is complete Provide Power On time from above (step 3.8). Provide NOMINAL PROCESS TEMP It status (step 4.6). This Page Intentionally Blank

OBJECTIVE:

To correct off-nominal configurations of Protein Crystallization Diagnostics Facility (PCDF) Process Unit while operated in the middeck. These major steps are independent and are not intended to be performed in sequence.

| | 1. If POWER ON LT-OFF or CONTR FAILURE LT-ON |
|-------|----------------------------------------------------------------------------------------------|
| | then CYCLE PROCESS UNIT POWER |
| MA16F | 1.1 sw POWER \rightarrow OFF |
| | sw POWER \rightarrow ON |
| | 1.2 Wait one minute. |
| | 1.3 Perform <u>MIDDECK STATUS CHECK</u> , steps 3.1 to 3.5 (SODF: ASSY OPS: PAYLOADS), then: |
| | 1.4 ✓MCC-H with status. |
| | 2. If EDR POWER ON LT - OFF, then: |
| MO13Q | 2.1 Verify sw DC UTIL PWR MNB – ON |
| O15:C | 2.2 Verify cb MNB UTIL PWR F1/MO13Q – cl |
| | 2.3 Cycle all sources of Process Unit Power |
| MA16F | 2.3.1 sw POWER \rightarrow OFF |
| MO13Q | sw DC UTIL PWR MNB \rightarrow OFF |
| | On MCC-H GO |
| O15:C | cb MNB UTIL PWR F1/MO13Q \rightarrow Open |
| | 2.3.2 cb MNB UTIL PWR F1/MO13Q \rightarrow Close |
| MO13Q | sw DC UTIL PWR MNB \rightarrow ON |
| MA16F | sw POWER \rightarrow ON |
| | Wait one minute. |
| | Perform <u>MIDDECK STATUS CHECK</u> , steps 3.1 to 3.5 (SODF: ASSY OPS: PAYLOADS), then: |

✓ MCC-H with status.

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(ASSY OPS/2JA/FIN 1/MULTI P)

Page 1 of 5 pages

OBJECTIVE:

This procedure removes ISS Locker (two) from the shuttle middeck. The lockers are transferred to the EXPRESS-6 Rack and exchanged with the Descent Glacier. The Descent Glacier unit is transferred to the middeck, powered to a survival state and installed. This procedure is performed in parallel with the Glacier Swap-ISS Procedure.

PARTS:

Velcro Strap

Gray Tape

TOOLS:

High Torque Locker Tool (Volume H, taped to wall)

STS IFM Toolbox:

1/4" Socket, 1/4" Drive

Ratchet, 1/4" Drive

(40-200 in-lbs) Trq Wrench, 1/4" Drive

<u>NOTE</u>

ISS crew will simultaneously prepare Descent Glacier unit to expedite powered transfer activity and ensure Glacier power interrupt time does not exceed 120 minute limit.

- 1. √Transfer path clear between EXPRESS-6 Rack and middeck.
- 2. <u>REMOVING LOCKERS FROM MIDDECK</u>



2.1 Untether DC POWER CABLE 20 AMP from Port Wall above MF28E.



Figure 1. ISS Locker Installation in Middeck.

2.2 Unfasten Locker fasteners (four) from Adapter Plate (High Torque Locker Tool; 1/4" Socket, 1/4" Drive; Ratchet, 1/4" Drive).

Remove locker and temporary stow.

GLACIER SWAP-SHUTTLE (ASSY OPS/2JA/FIN 1/MULTI P)

MF28G 2.3 Unfasten Locker fasteners (four) from Adapter Plate (High Torque Locker Tool; 1/4" Socket, 1/4" Drive; Ratchet, 1/4" Drive).

Remove locker and temporary stow.

MF28E 2.4 Unfasten Adapter Plate fasteners (four) from VPMP (High Torque Locker Tool; 1/4" Socket, 1/4" Drive; Ratchet, 1/4" Drive).

Temporary stow Adapter Plate.

- MF28G 2.5 Unfasten Adapter Plate fasteners (four) from VPMP (High Torque Locker Tool; 1/4" Socket, 1/4" Drive; Ratchet, 1/4" Drive). Temporary stow Adapter Plate.
 - 2.6 Notify ISS crew that middeck location is ready.
- LAB1O4 3. Transfer ISS Locker (two) and Adapter Plate (two) to EXPRESS-6 Rack.
 - 4. Exchange Glacier unit for ISS Locker (two) and Adapter Plate (two) with ISS crewmember.
- MF28E/G 5. Transfer Descent Glacier to Middeck location and slide into position.
 - 6. GLACIER POWER ON IN ORBITER MIDDECK
- ML86B 6.1 \checkmark cb MNB MAR 1 \rightarrow Open
- MF28E/G 6.2 ✓cb POWER Open ✓sw BATTERY – ON
 - 6.3 Verify and complete DC POWER CABLE 20AMP connections:

ENT PAYLOAD DC PWR → |← POWER (J1)

ML86B 6.4 cb MNB MAR $1 \rightarrow$ Close

| | | NOTE |
|---------|-----|------------------------------------------------------------------------------------------------------------------|
| | | Glacier initialization could take up to 3 minutes. Initialization is complete once Line 1 reads ' HOME '. |
| MF28E/G | 6.5 | cb POWER \rightarrow Close (It on) |
| | | Record Power On Time: (GMT) |

✓sw BATTERY – ON (It on)

(ASSY OPS/2JA/FIN 1/MULTI P)

If POWER It off

*

Perform <u>GLACIER FAIL TO REPOWER</u> (SODF: ASSY OPS:

PAYLOADS), then:

WARNING

Glacier requires four fasteners torqued to 75 in-lbs to be properly fastened onto VPMP for structural and safety purposes.



Figure 2. Glacier Configuration.

7. GLACIER SETUP OR INSTALLATION IN ORBITER MIDDECK

- 7.1 Fasten Glacier fasteners (four) into Middeck locker VPMP mounted on wire tray using following pattern: upper left, lower right, upper right, lower left and torque to 75 in-lbs [High Torque Locker Tool; 1/4" Socket, 1/4" Drive; (40-200 in-lbs) Trq Wrench, 1/4" Drive].
- 7.2 Tether DC POWER CABLE 20 AMP to top of Glacier using Velcro Strap and Gray Tape.

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| 7.3 | Disconnect Glacier IVA Handle from Glacier and temporarily stow. |
|-------------|------------------------------------------------------------------------------------------------------------------------------|
| 7.4 | Verify front door is closed. |
| 7.5 | ✓Display (Line 1) ' HOME ' |
| * * * * * * | If display - ' **Error Pending** ' Perform <u>GLACIER ERROR MESSAGE</u> , all (SODF: ASSY OPS: PAYLOADS), then: |
| * * * * | If ' HOME ' not shown Perform <u>GLACIER LCD BLANK</u> , all (SODF: ASSY OPS: |

- | PAYLOADS), then:
- 7.6 From front panel display

Record CURR TEMP: _____

Record SET POINT: _____

Record GPS time: _____

7.7 Stow IVA Handle per Stow Note

If all powered transfers are complete

Stow tools.

If all powered transfers are not complete

Temporarily stow all tools.

7.8 Notify **MCC-H** of Glacier transfer to middeck completion.

Report time from <u>step 6.5</u> and temperature, set point and GPS from <u>step 7.6</u>.

<u>Ground should update IMS for the following parts:</u> ISS Locker (MF28E) TO: LAB1O4_G1 ISS Locker (MF28G) TO: LAB1O4_J1 Adapter Plate (two) TO: per Transfer List Glacier TO: Middeck This Page Intentionally Blank

GLACIER SWAP-ISS (ASSY OPS/2JA/FIN 1/MULTI P)

Page 1 of 6 pages

OBJECTIVE:

This procedure configures the Glacier in EXPRESS-6 Rack for descent by removing the unit from the EXPRESS Rack, powering off the unit, disconnecting the EXPRESS resources (power, data, and cooling water), and locking the Cryocooler Launch Locks. The Descent Glacier is then exchanged with ISS Lockers (two). The ISS Lockers are installed in EXPRESS -6 Rack. This procedure is performed in parallel with the Glacier Swap-STS Procedure.

MATERIALS:

Dry Wipes

Gray Tape

PARTS:

Glacier IVA Handle B/C CBSE-F10075-1 (reference Stow Note)

Volume Compensators B/C GLCR1000J, GLCR1001J (reference Stow Note)

TOOLS:

High Torque Locker Tool

ISS IVA Toolbox:

3/16" Hex Head, 1/4" Drive

Driver Handle, 1/4" Drive

1/4" Socket, 1/4" Drive

Ratchet, 1/4" Drive

1/4" Drive; (5-35 in-lbs) Trq Driver, 1/4" Drive

<u>NOTE</u>

Shuttle crew will simultaneously remove lockers in middeck to expedite powered transfer activity to ensure Glacier power interrupt time does not exceed the 120 minute limit.

LAB1O4 (Glacier)

- 1. Verify front door locking flap is in LOCKED position.
 - 2. Connect Glacier IVA Handle diagonally to front face of Descent Glacier at locations marked IVA Receptacle (two of four).



Figure 1. Glacier Configuration.

- 3. Unfasten Glacier from EXPRESS Rack Backplate (four) (High Torque Locker Tool; 1/4" Socket, 1/4" Drive; Ratchet, 1/4" Drive).
- 4. Notify shuttle crew that ISS Glacier is ready for shutdown.
- 5. <u>GLACIER SHUTDOWN</u>

LAB1O4 (Glacier)

5.1 ✓Display (Line 1) – 'HOME'

| | ************************************** |
|-----|------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| | If display -'**Error Pending**' Perform <u>3.003 GLACIER MANUAL ERROR MESSAGE</u>, all (PODF: GLACIER: MALFUNCTION), then: |
| | * If ' HOME ' not shown * |
| 5.2 | Record front panel display GPS time: |
| 5.3 | pb Left (MENU) \rightarrow Press (one time) |
| | The following messages appear: 'MAIN MENU' 'QUICK STATUS 1/5' |
| 5.4 | pb Left (NEXT) \rightarrow Press (four times) |
| | The following messages appear: 'MAIN MENU' 'SHUTDOWN 5/5' |
| 5.5 | pb Center (SELECT) → Press (one time) |
| | The following messages appear: 'SHUTDOWN' 'SHUTDOWN 1/2' |
| 5.6 | pb Center (SELECT) → Press (one time) |
| | The following messages appear: 'Confirm Shutdown' 'SHUTDOWN' |
| 5.7 | pb Left (APPLY) \rightarrow Press (one time) |
| | The following messages appear: 'Glacier' 'System' 'Shutting Down' 'Please wait' |
| 5.8 | ✓Display shows the following messages 'Glacier' 'Shutdown Complete' 'TURN POWER OFF' |
| 5.9 | Wait 5 seconds. |

| | | NOTE | | | | |
|-----------|----|--------------------------------------------------------------|------------------------------------------------------------------------------------------|--|--|--|
| | | 1. Power down begins when Glacier POWER cb is open. | | | | |
| | | 2. Power light can take up to 2 minutes to fully extinguish. | | | | |
| | | 3. BA | TTERY sw is left on to power data logger during transfer. | | | |
| | | 5.10 | cb POWER → Open | | | |
| | | | Record Power Off Time: (GMT) | | | |
| LAB1O4_F1 | | 5.11 | sw LOCKER-3 POWER → OFF ✓LOCKER-3 POWER Lt – Off | | | |
| | 6. | RESOURCE DISCONNECTS FROM GLACIER UNIT | | | | |
| Glacier | | 6.1 | EXPRESS Rack Power Cable (24")← → POWER J1 | | | |
| | | 6.2 | EXPRESS Rack Data Cable (24")← → DATA J2 | | | |
| | | 6.3 | Glacier Water Supply Line ← → WATER SUPPLY Glacier Water Return Line ← → WATER RETURN | | | |
| | | | Verify no leakage at connectors. | | | |
| | | | * If leakage is present | | | |
| | | | * Clean up with Dry Wipes. | | | |
| | | | ************************************ | | | |
| | | 6.4 | Tether cables and water lines out of the way. | | | |
| | 7. | Carefu | ully slide the Glacier unit out of the locker position to access the rear of nit. | | | |
| | • | | decomposite the second state of a state of the second state (Disited Compose) | | | |

- 8. Photo document the rear intake and exhaust vents (Digital Camera).
- 9. Clean the Glacier rear intake and exhaust vents with Gray Tape. Refer to Figure 2.

(ASSY OPS/2JA/FIN 1/MULTI P)

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Figure 2. Cryocooler Launch Locks and Vents on Rear of Glacier.

- Push in and rotate clockwise cryocooler launch locks (four) at rear of Glacier until locking pin is engaged (LOCK) (3/16" Hex Head, 1/4" Drive; Driver Handle, 1/4" Drive). Refer to Figure 2.
- 11. Exchange Glacier unit for ISS Locker (two) and Adapter Plate (two) with shuttle crewmember. Temporary stow Adapter Plates (two).
- 12. INSTALLING LOCKERS
- LAB1O4_G 12.1 Slide MF28E locker into EXPRESS-6 Rack Locker 3 location.

Tighten, torque fasteners (four) on each Locker to 30 in-lbs [High Torque Locker Tool; 1/4" Socket, 1/4" Drive; (5-35 in-lbs) Trq Driver, 1/4" Drive] in a diagonal pattern.

LAB104_J1 12.2 Slide MF28G locker into EXPRESS-6 Rack Locker 4 location.

Tighten, torque fasteners (four) on each Locker to 30 in-lbs [High Torque Locker Tool; 1/4" Socket, 1/4" Drive; (5-35 in-lbs) Trq Driver, 1/4" Drive] in a diagonal pattern.

13. REMOVING RESOURCE CONNECTIONS

- LAB1O4_F1 13.1 EXPRESS Rack Power Cable (24")←|→ LOCKER-3 POWER J1
 - 13.2 EXPRESS Rack Data Cable (24")←|→ LOCKER-3 DATA J2
 - 13.3 Glacier Water Return Line ←|→ COOLANT WATER RETURN Glacier Water Supply Line ←|→ COOLANT WATER SUPPLY
 - 13.4 Connect Volume Compensator to each Water Line

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Glacier Water Return Line (small connector, Preece)→|← Volume Compensator

Glacier Water Supply Line (small connector, Preece)→|← Volume Compensator

14. Stow:

Power and Data cables per Stow Note

Water Lines with Volume Compensators per Stow Note

Adapter Plate (two) per Transfer List

All IVA Tools if payload transfers are complete.

15. Notify **MCC-H** Glacier Swap-ISS is complete. Report power-off time from <u>step 5.10</u>.

Ground should update IMS for the following parts:

ISS Locker TO: LAB1O4_G1

ISS Locker TO: LAB1O4_J1

EXPRESS Rack Power Cable (24") TO: per Stow Note

EXPRESS Rack Data Cable (24") TO: per Stow Note

Glacier Water Return Line with Volume Compensator TO: per Stow Note

Glacier Water Supply Line with Volume Compensator TO: per Stow Note

Adapter Plate (two) TO: per Transfer List

Glacier TO: Middeck

GLACIER CONFIGURATION FOR DESCENT

(ASSY OPS/2JA/FIN)

Page 1 of 2 pages

OBJECTIVE:

The following steps will perform a configuration for descent of Glacier Systems.

TOOLS

3/16" Hex Head, 1/4" Drive

- 4" Ext, 1/4" Drive
- (40 200 in-lbs) Trq Wrench, 1/4" Drive
- Glacier 1. ✓cb POWER Close (It on)
 - 2. ✓sw BATTERY ON (It on)



Figure 1. Glacier Configuration

3. ✓Glacier door is closed.

**

*

*

Page 2 of 2 pages

If Outer Door does not close

Press on top left corner or bottom left corner of door to assist with closure.

4. ✓Door Latch – Locked (Finger latches fully spread apart and locking flap positioned between finger latches.)

WARNING

Glacier Door Captive Locks (two) must be torqued to 75 in-lbs to prevent door from opening during launch and return.

Fasten Glacier Door Captive Locks (two), torgue to 75 in-lbs using 3/16" Hex 5. Head, 1/4" Drive, 4" Ext, 1/4" Drive, (40 to 200 in.-lbs.) Trq Wrench 1/4" Drive. See Figure 1 Glacier Configuration.

6. Notify MCC-H Glacier Config for Descent is complete.

STOW tools as required, to original locations:

GLACIER PREPARATION FOR SAMPLE TRANSFER

(ASSY OPS/2JA/FIN)

Page 1 of 2 pages

OBJECTIVE:

The following steps will perform a status check on the Glacier System and prepare the hardware for sample transfer.

<u>TOOLS</u>

3/16" Hex Head, 3/8" Drive

4" Extension, 3/8" Drive

Ratchet, 3/8" Drive

MA16F/G (Glacier)
1. ✓cb POWER – Close (It on)
2. ✓sw BATTERY – ON (It on)
3. ✓Display – 'HOME'
* If Display - '**Error Pending**'
* Perform GLACIER ERROR MESSAGE, then:
* If 'HOME' not shown:
* If 'HOME' not shown:
* pb Right (EXIT) → push until 'HOME' appears

- 4. ✓Display 'CURR TEMP:' is -95.0°C ± 5.0°C.
- 5. Log from Glacier front panel 'GPS', 'CURR TEMP' in Glacier Log Table 1. Table 1. Glacier Log

| GPS | CURR TEMP | GPS | CURR TEMP |
|-----|-----------|-----|-----------|
| :: | °C | :: | °C |
| :: | °C | :: | °C |
| :: | °C | :: | °C |
| :: | °C | :: | °C |
| ·:: | °C | :: | °C |

6. If first time opening Glacier door since launch,

Unlock Glacier Door Captive Locks (two) using 3/16" Hex Head, 3/8" Drive; 4" Extension, 3/8" Drive; Ratchet, 3/8" Drive. See Figure 1 Glacier Configuration. GLACIER PREPARATION FOR SAMPLE TRANSFER(ASSY OPS/2JA/FIN)Page 2 of 2 pages



Figure 1. Glacier Configuration

7. Notify **MCC-H** of data recorded in Table 1 and any off-nominal conditions.
GLACIER POWER UP

(ASSY OPS/2JA/FIN)

Page 1 of 2 pages

OBJECTIVE:

The following steps will activate Glacier Systems.

On MCC-H GO

- ML86B 1. cb MNB MAR $1 \rightarrow$ Open
- Glacier 2. ✓cb POWER Open (It off)
 - 3. ✓sw BATTERY OFF (It off)
 - 4. ✓SHUTTLE PAYLOAD DC PWR CABLE → |← POWER J1
- ML85E 5. ✓SHUTTLE PAYLOAD DC PWR CABLE → |← DC 20 AMP J11
- ML86B 6. cb MNB MAR 1 \rightarrow Close

NOTE

System initialization may take up to 3 minutes. Initialization complete once Line 1 of front panel display reads '**HOME**'.

- Glacier 7.
 - 7. cb POWER \rightarrow Close (It on)
 - 8. sw BATTERY \rightarrow ON (It on)

<u>NOTE</u>

The **HOME** menu will be slightly different based upon the current Temperature Control Mode (**SET POINT**, **IDLE**, or **MANUAL**) of the Glacier.

9. ✓Display '**HOME**'

*

- If 'HOME' not shown,
 - Perform GLACIER FAIL TO REPOWER then:

- If Display '**Error Pending**'
 - Perform GLACIER ERROR MESSAGE, then:

10. Log from Glacier front panel:

GPS: _____:____:____:____

CURR TEMP: _____. °C

11. Notify **MCC-H** of Power Up complete and data recorded in Step 10.

GLACIER REBOOT

(ASSY OPS/2JA/FIN)

OBJECTIVE:

The following steps will perform a reboot of Glacier Systems.

| Glacier | 1. | ✓Display ' HOME ' |
|---------|----|---------------------------------------------------------------------------------------------------------------------|
| | | * If 'HOME' not shown: |
| | | <pre>pb Right (EXIT) → Press until 'HOME' appears</pre> |
| | | ~ ************************************ |
| | 2. | Log from Glacier front panel: |
| | | GPS::: |
| | | CURR TEMP:°C |
| | 3. | pb Left (MENU) \rightarrow Press (one time), following appears: |
| | | 'MAIN MENU' 'QUICK STATUS 1/5' |
| | 4. | pb Left (NEXT) \rightarrow Press (four times), following appears: |
| | | 'MAIN MENU' 'SHUTDOWN 5/5' |
| | 5. | pb Center (SELECT) \rightarrow Press (one time), following appears: |
| | | 'SHUTDOWN' 'SHUTDOWN 1/2' |
| | 6. | pb Left (NEXT) → Press (one time), following appears: 'SHUTDOWN' 'REBOOT 2/2' |
| | 7. | pb Center (SELECT) → Press (one time), following appears: 'Confirm Shutdown' 'REBOOT' |
| | 8. | pb Left (APPLY) → Press (one time), following appears: 'Glacier' 'System' 'Shutting Down' 'Please wait' |
| | 9. | Verify Display— 'Glacier' 'System' 'Rebooting' 'Please wait' |

NOTE System initialization may take up to 3 minutes. Initialization is complete once Line 1 of front panel display reads '**HOME**'.

10. ✓ Display '**HOME**'

| * | |
|-------------|-----------------------------------------------|
| * * * | If 'HOME' not shown: |
| * * * | √мсс-н |
| ** | *************************************** |
| ** | *************************************** |
| * | If Display - '**Errror Pending**' I |
| * * * | Perform GLACIER ERROR MESSAGE, then: |
| ** | *************************************** |

11. Notify MCC-H of recorded data in step 2.

OBJECTIVE:

The following steps will perform a shutdown of Glacier Systems. Commanded shutdowns prevent loss of data and system errors and are the desired nominal method of shutdown.

| | | CAUTION |
|---------|----|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| | | Due to possible loss of experiment payload(s), Glacier should not be shutdown for more than 120 minutes, unless necessary for Orbiter contingency operations. |
| Glacier | 1. | <pre>✓Display 'HOME' If Display - '**Error Pending**' Perform GLACIER ERROR MESSAGE, then: If 'HOME' not shown: pb Right (EXIT) → push until 'HOME' appears</pre> |
| | 2. | Log Glacier front panel: GPS:::: |
| | 3. | CURR TEMP:°C pb Left (MENU) \rightarrow Press (one time), following appears: |
| | | 'MAIN MENU' 'QUICK STATUS 1/5' |
| | 4. | pb Left (NEXT) \rightarrow Press (four times), following appears: |
| | | 'MAIN MENU' 'SHUTDOWN 5/5' |
| | 5. | pb Center (SELECT) → Press (one time), following appears: 'SHUTDOWN' 'SHUTDOWN 1/2' |
| | 6. | pb Center (SELECT) → Press (one time), following appears: 'Confirm Shutdown' 'SHUTDOWN' |
| | 7. | pb Left (APPLY) \rightarrow Press (one time), following appears: |

Page 2 of 2 pages

- 'Glacier' 'System' 'Shutting Down' 'Please wait...'
- Verify—
 'Glacier'
 'Shutdown Complete'
 'TURN POWER OFF'
- 9. Wait 5 seconds before proceeding.
- 10. sw BATTERY \rightarrow OFF (It off)

<u>NOTE</u>

Power light can take up to 2 minutes to fully extinguish. OK to proceed without waiting.

- 11. cb POWER \rightarrow Open (It off)
- ML86B 12. cb MNB MAR $1 \rightarrow$ Open
 - 13. Notify MCC-H of recorded data and time in step 2.



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| GLACIER | GLACIER ERROR MESSAGE (ASSY OPS/2JA/FIN 1/MULTI P) Page 8 of 17 pages | |
|---------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--|
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GLACIER ERROR MESSAGE

(ASSY OPS/2JA/FIN 1/MULTI P) Page 15 of 17 pages









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GLACIER FAIL TO HOLD SET POINT(ASSY OPS/2JA/FIN)Page 1 of 9 pages

OBJECTIVE:

This procedure is required when the Glacier fails to hold set point. It performs a check of some critical parameters then directs the manual reconfiguration of some key controls as required.

| Glacier | 1. | RECORD DATA |
|---------|----|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| | | ************************************** |
| | | * If Display-' **Error Pending** ' |
| | | * Perform <u>GLACIER ERROR MESSAGE</u> (SODF: ASSY OPS: * PAYLOADS: GLACIER), then: |
| | | * ************************************* |
| | | 1.1 √Display – ' HOME ' |
| | | ************************************** |
| | | * If 'HOME' not shown: |
| | | * * pb Right (EXIT) → push until 'HOME' appears |
| | | ************************************ |
| | | 1.2 Record from front panel start 'CURR TEMP', 'SET POINT', 'GPS' in <u>TABLE 3 GLACIER DIAGNOSTIC LOG FILE</u> (SODF: ASSY OPS: PAYLOADS: GLACIER) |
| | 2. | CHECK STATUS OF KEY PARAMETERS |
| | | 2.1 pb Left (MENU) → push (one time), following appears: 'MAIN MENU' 'QUICK STATUS 1/5' |
| | | 2.2 pb Center (SELECT) → push (one time), following appears: 'QUICK STATUS' 'Cold Head 1A 1/16' |
| | | NOTE |
| | | 1. The center pushbutton (NEXT) moves to next status display. |
| | | 2. The left pushbutton (PREV) moves to previous status display. |
| | | 2.3 Record Cold Head 1A, Cold Head 1B, Cold Head 2A, Cold Head 2B, and CircFan Speed in <u>TABLE 3 GLACIER DIAGNOSTIC LOG FILE</u> (SODF: ASSY OPS: PAYLOADS: GLACIER) |
| | | 2.4 pb Center (NEXT) \rightarrow push until all data has been recorded. |
| | | 2.5 pb Right (EXIT) \rightarrow push until 'HOME ' |
| | | 2.6 \checkmark MCC-H to report log values from Table 3 and get direction. |
| | | 2.7 Record any ground supplied data in <u>TABLE 2 GLACIER RESET LOG</u> <u>FILE</u> (SODF: ASSY OPS: PAYLOADS: GLACIER) |

3. SET TEMPERATURE CONTROL MODE TO IDLE

- 3.1 pb Left (MENU) → push (one time), following appears:
 'MAIN MENU'
 'QUICK STATUS 1/5'
- 3.2 pb Left (NEXT) → push (three times), following appears: 'MAIN MENU' 'SETUP 4/5'
- 3.3 pb Center (SELECT) → push (one time), following appears: 'SETUP' 'Temp Control 1/3'
- 3.4 pb Center (SELECT) → push (one time), following appears: 'Temp Control' 'Set Point Temp 1/18'
- 3.5 pb Left (NEXT) → push (one time), following appears: 'Temp Control' 'Control Mode 2/18'

NOTE

- 1. There are 3 options for setting the Control Mode (IDLE, SET POINT and MANUAL).
- 2. The left pushbutton (NEXT) changes the Mode, the center pushbutton (APPLY) selects the mode and the right pushbutton (CANCEL) returns to the previous mode.
- 3.6 pb Center (SELECT) → Press (one time), following appears: 'Control Mode' 'XXXX'
- 3.7 pb Left (NEXT) → press as required to select desired Temperature Control Mode to IDLE
- 3.8 pb Center (APPLY) \rightarrow push (one time)
- 3.9 ✓Confirm New Control Mode = IDLE
- 3.10 pb Left (APPLY) → Press (one time), following appears: 'Temp Control' 'Control Mode 2/18'
- 3.11 √Control Mode = IDLE
- 3.12 pb Right (EXIT) → Press until 'HOME' appears
- 4. <u>SET SETPOINT TEMP</u>
 - 4.1 pb Left (MENU) → push (one time) following appears:
 'MAIN MENU'
 'QUICK STATUS 1/5'

- 4.2 pb Left (NEXT) → push (three times) following appears:
 'MAIN MENU'
 'SETUP 4/5'
- 4.3 pb Center (SELECT) → push (one time) following appears:
 'SETUP'
 'Temp Control 1/3'
- 4.4 pb Center (SELECT) → push (one time) following appears:
 'Temp Control'
 'Set Point Temp 1/18'
- 4.5 pb Center (SELECT) → push (one time) following appears: 'Set Point Temp'

'XXXX.X °C' '-160.0 to +004.0'

NOTE

- 1. The left pushbutton (CURSOR) moves cursor between New Set Point Temp fields. The default cursor position will be blinking.
- 2. The center pushbutton (PLUS) increases New Set Point Temp selected digit field value by 1.
- 4.6 Enter desired Set Point temperature per MCC-H.
- 4.7 pb Right (DONE) \rightarrow push (one time)
- 4.8 ✓Confirm New Set Point = desired Set Point
- 4.9 pb Left (APPLY) → Press (one time), following appears:
 'Temp Control'
 'Set Point Temp 1/18'
- 4.10 ✓ Set Point Temp = desired Set Point
- 4.11 pb Right (EXIT) \rightarrow push until '**HOME**' appears
- 5. <u>SET TEMP CONTROL SENSORS</u>
 - 5.1 pb Left (MENU) → push (one time) following appears: 'MAIN MENU' 'QUICK STATUS 1/5'
 - 5.2 pb Left (NEXT) → push (three times) following appears: 'MAIN MENU' 'SETUP 4/5'
 - 5.3 pb Center (SELECT) → push (one time) following appears: 'SETUP' 'Temp Control 1/3'
 - 5.4 pb Center (SELECT) \rightarrow push (one time) following appears: **'Temp Control'**

'Set Point Temp 1/18'

- 5.5 pb Left (NEXT) → push (two times) following appears: 'Temp Control' 'Control Sensors 3/18'
- 5.6 pb Center (SELECT) → push (one time) following appears 'Control Sensors' 'INNER OUTLET INLET'

| NOTE |
|------|
|------|

- 1. The left pushbutton (CURSOR) moves cursor between Control Sensor fields. The default cursor position will be blinking.
- 2. The center pushbutton (PLUS) changes the values of the Control Sensor fields from 0 to 1 or vice versa.
- 5.7 Enter desired combination of Temp Control Sensors per MCC-H.
- 5.8 pb Right (DONE) \rightarrow push (one time)
- 5.9 ✓Confirm New Control Sensors = desired Control Sensors
- 5.10 pb Left (APPLY) → Press (one time), following appears: 'Temp Control' 'Control Sensors 3/18'
- 5.11 ✓Control Sensors = desired Control Sensors
- 5.12 pb Right (EXIT) → Press until '**HOME**' appears
- 6. <u>SET TEMPERATURE CONTROL BANDWIDTH</u>
 - 6.1 pb Left (MENU) → push (one time) following appears:
 'MAIN MENU'
 'QUICK STATUS 1/5'
 - 6.2 pb Left (NEXT) → push (three times) following appears:
 'MAIN MENU'
 'SETUP 4/5'
 - 6.3 pb Center (SELECT) → push (one time) following appears: 'SETUP' 'Temp Control 1/3'
 - 6.4 pb Center (SELECT) → push (one time) following appears: 'Temp Control' 'Set Point Temp 1/18'
 - 6.5 pb Left (NEXT) → push (four times) following appears: 'Temp Control' 'Bandwidth 5/18' 'XX.X°C'
 - 6.6 pb Center (SELECT) \rightarrow push (one time) following appears:

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'Bandwidth' 'XX.X°C' '00.1 TO 25.5'

NOTE

- 1. The left pushbutton (CURSOR) moves cursor between Bandwidth fields. The default cursor position will be blinking.
- 2. The center pushbutton (PLUS) increases Temperature Control Bandwidth selected digit field value by 1.
- 6.7 Enter desired Temperature Control Bandwidth per MCC-H
- 6.8 pb Right (DONE) \rightarrow push (one time)
- 6.9 ✓Confirm New Bandwidth = desired Bandwidth
- 6.10 pb Left (APPLY) \rightarrow Press (one time), following appears:

'Temp Control' 'Bandwidth 5/18'

- 6.11 \checkmark Bandwidth = desired Bandwidth
- 6.12 pb Right (EXIT) → Press until 'HOME' appears

7. <u>SET PRIMARY COOLER</u>

- 7.1 pb Left (MENU) → push (one time) following appears:
 'MAIN MENU'
 'QUICK STATUS 1/5'
- 7.2 pb Left (NEXT) → push (three times) following appears: 'MAIN MENU' 'SETUP 4/5'
- 7.3 pb Center (SELECT) → push (one time) following appears: 'SETUP' 'Temp Control 1/3'
- 7.4 pb Center (SELECT) → push (one time) following appears: 'Temp Control' 'Set Point Temp 1/18'
- 7.5 pb Left (NEXT) → push (five times) following appears:
 'Temp Control'
 'Primary Cooler 6/18'
 'COOLER X'
- 7.6 pb Center (SELECT) → push (one time) following appears: 'Primary Cooler' 'COOLER X'

NOTE

- 1. There are 2 options for Primary Cooler (COOLER 1 and COOLER 2).
- 2. The left pushbutton (NEXT) changes the Primary Cooler to either COOLER 1 or COOLER 2, the center pushbutton (APPLY) selects the presently displayed Primary Cooler and the right pushbutton (CANCEL) returns to the previous display.
- 7.7 pb Left (NEXT) → push as required to select desired Primary Cooler per MCC-H
- 7.8 pb Center (APPLY) \rightarrow push (one time)
- 7.9 ✓ Confirm New Primary Cooler = desired Cooler
- pb Left (APPLY) → Press (one time), following appears: 7.10 'Temp Control' 'Primary Cooler 6/18'
- 7.11 √Primary Cooler = desired Cooler
- 7.12 pb Right (EXIT) → Press until 'HOME' appears
- 8. SET MAXIMUM POWER DRAW SETTING
 - 8.1 pb Left (MENU) \rightarrow push (one time) following appears: 'MAIN MENU' 'QUICK STATUS 1/5'
 - pb Left (NEXT) \rightarrow push (three times) following appears: 'MAIN MENU' 8.2 'SETUP 4/5'
 - 8.3 pb Center (SELECT) \rightarrow push (one time) following appears: 'SETUP' 'Temp Control 1/3'
 - pb Center (SELECT) \rightarrow push (one time) following appears: 'Temp Control' 8.4 'Set Point Temp 1/18'
 - pb Left (NEXT) \rightarrow push (twelve times) following appears: 'Temp Control' 8.5 'Max Power Draw 13/18' 'XXX W'
 - 8.6 pb Center (SELECT) \rightarrow push (one time) following appears: 'Max Power Draw' 'XXX W' '000 to 420'

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<u>NOTE</u>

- 1. The left pushbutton (CURSOR) moves the cursor between Maximum Power Draw fields. The default cursor position will be blinking.
- 2. The center pushbutton (PLUS) increases the Maximum Power Draw selected digit field value by 1.
- 8.7 Enter desired Maximum Power Draw per MCC-H.
- 8.8 pb Right (DONE) \rightarrow push (one time)
- 8.9 ✓Confirm New Max Power = desired Max Power Draw
- 8.10 pb Left (APPLY) → Press (one time), following appears: 'Temp Control' 'Max Power Draw 13/18'
- 8.11 ✓Max Power Draw = desired Max Power Draw
- 8.12 pb Right (EXIT) \rightarrow push until 'HOME' appears

9. <u>SET OVER CURRENT</u>

- 9.1 pb Left (MENU) → push (one time) following appears:
 'MAIN MENU'
 'QUICK STATUS 1/5'
- 9.2 pb Left (NEXT) → push (three times) following appears:
 'MAIN MENU'
 'SETUP 4/5'
- 9.3 pb Center (SELECT) → push (one time) following appears: 'SETUP' 'Temp Control 1/3'
- 9.4 pb Center (SELECT) → push (one time) following appears: 'Temp Control' 'Set Point Temp 1/18'
- 9.5 pb Left (NEXT) → push (thirteen times) following appears:
 'Temp Control'
 'Over Current 14/18'
 'XX.X A'
- 9.6 pb Center (SELECT) → push (one time) following appears:
 'Over Current'
 'XX.X W'
 '00.0 to 30.0'

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<u>NOTE</u>

- 1. The left pushbutton (CURSOR) moves the cursor between Over Current fields. The default cursor position will be blinking.
- 2. The center pushbutton (PLUS) increases the Maximum Power Draw selected digit field value by 1.
- 9.7 Enter desired Over Current Limit per MCC-H.
- 9.8 pb Right (DONE) \rightarrow push (one time)
- 9.9 ✓Confirm New Over Current = desired Over Current
- 9.10 pb Left (APPLY) → push (one time), following appears: 'Temp Control' 'Over Current 14/18'
- 9.11 ✓Over Current = desired Over Current
- 9.12 pb Right (EXIT) → Press until '**HOME**' appears

10. SET TEMPERATURE CONTROL MODE

- 10.1 pb Left (MENU) → push (one time) following appears: 'MAIN MENU' 'QUICK STATUS 1/5'
- 10.2 pb Left (NEXT) → push (three times) following appears: 'MAIN MENU' 'SETUP 4/5'
- 10.3 pb Center (SELECT) → push (one time) following appears: 'SETUP' 'Temp Control 1/3'
- 10.4 pb Center (SELECT) → push (one time) following appears: 'Temp Control' 'Set Point Temp 1/18'
- 10.5 pb Left (NEXT) → push (one time) following appears: 'Temp Control' 'Control Mode 2/18'
- 10.6 pb Center (SELECT) → push (one time), following appears: 'Control Mode' 'XXXX'

<u>NOTE</u>

- 1. There are 3 options for setting the Control Mode (IDLE, SET POINT and MANUAL).
- The left pushbutton (NEXT) changes the Mode, the center pushbutton (APPLY) selects the mode and the right pushbutton (CANCEL) returns to the previous mode.

- 10.7 pb Left (NEXT) \rightarrow push as required to selected desired Temperature Control Mode per **MCC-H**.
- 10.8 pb Center (APPLY) \rightarrow push one time
- 10.9 ✓Confirm New Control Mode = desired Control Mode
- 10.10 pb Left (APPLY) → push (one time), following appears: 'Temp Control' 'Control Mode 2/18'
- 10.11 ✓ Control Mode = desired Control Mode
- 10.12 pb Right (EXIT) \rightarrow push until '**HOME**' appears.
- 11. CHECK GLACIER STATUS
 - 11.1 ✓ cb POWER Close (It on)
 - 11.2 √sw BATTERY ON (It on)

11.3 ✓Display – 'HOME' If Display-'**Error Pending**' Perform <u>GLACIER ERROR MESSAGE</u> (SODF: ASSY OPS: PAYLOADS: GLACIER), then: If 'HOME' not shown: pb Right (EXIT) → push until 'HOME' appears

- 11.4 ✓Display 'CURR TEMP: XXXX.X °C' ±5.0°C or ramping toward expected temperature.
- 12. <u>RECORD END DATA</u>
 - 12.1 Record from front panel end 'CURR TEMP', 'SETPOINT', 'GPS' in TABLE 3 GLACIER DIAGNOSTIC LOG FILE (SODF: ASSY OPS: PAYLOADS: GLACIER)
 - 12.2 Notify **MCC-H** of logged values in <u>TABLE 3 GLACIER DIAGNOSTIC</u> <u>LOG FILE</u> (SODF: ASSY OPS: PAYLOADS: GLACIER)

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GLACIER MANUAL RECONFIGURE

(ASSY OPS/2JA/FIN)

Page 1 of 21 pages

OBJECTIVE:

This procedure will perform a manual reconfigure of the Glacier System using the front panel and display buttons.

- - 2. Record front panel display 'CURR TEMP', 'SET POINT', and 'GPS' and any ground supplied data in TABLE 2 GLACIER RESET LOG FILE.
 - 3. SET CONTROL MODE TO IDLE
 - 3.1 pb Left (MENU) → Press (one time), following appears: 'MAIN MENU' 'QUICK STATUS 1/5'
 - 3.2 pb Left (NEXT) → Press (three times), following appears: 'MAIN MENU' 'SETUP 4/5'
 - 3.3 pb Center (SELECT) → Press (one time), following appears: 'SETUP' 'Temp Control 1/3'
 - 3.4 pb Center (SELECT) → Press (one time), following appears: 'Temp Control' 'Set Point Temp 1/18'
 - 3.5 pb Left (NEXT) \rightarrow Press (one time), following appears: 'Temp Control' 'Control Mode 2/18'
 - 3.6 pb Center (SELECT) → Press (one time), following appears: 'Control Mode' 'XXXX'

- 1. There are 3 options for setting the Control Mode (IDLE, SET POINT, and MANUAL).
- The left pushbutton (NEXT) changes the Mode, the center pushbutton (APPLY) selects the Mode, and the right pushbutton (CANCEL) returns to the previous Mode.

- 3.7 pb Left (NEXT) → Press as required to select desired Temperature Control Mode to Idle
- 3.8 pb Center (APPLY) \rightarrow Press (one time)
- 3.9 \checkmark Confirm New Control Mode = Idle
- 3.10 pb Left (APPLY) → Press (one time), following appears: 'Temp Control' 'Control Mode 2/18'
- 3.11 √Control Mode = Idle
- 3.12 pb Right (EXIT) → Press until 'HOME' appears
- 4. <u>SETPOINT TEMPERATURE</u>
 - 4.1 pb Left (MENU) → Press (one time), following appears:
 'MAIN MENU'
 'QUICK STATUS 1/5'
 - 4.2 pb Left (NEXT) → Press (three times), following appears:
 'MAIN MENU'
 'SETUP 4/5'
 - 4.3 pb Center (SELECT) → Press (one time), following appears: 'SETUP' 'Temp Control 1/3'
 - 4.4 pb Center (SELECT) → Press (one time), following appears: 'Temp Control' 'Set Point Temp 1/18'
 - 4.5 pb Center (SELECT) → Press (one time), following appears:
 'Set Point Temp'
 'XXXXX °C'
 '-160.0 to +004.0'

- 1. The left pushbutton (CURSOR) moves cursor between New Set Point Temp fields. The default cursor position will be blinking.
- 2. The center pushbutton (PLUS) increases New Set Point Temp selected digit field value by 1.
- 4.6 Enter desired Set Point Temperature per MCC-H
- 4.7 pb Right (DONE) \rightarrow Press (one time)
- 4.8 ✓Confirm New Set Point = desired Set Point
- 4.9 pb Left (APPLY) \rightarrow Press (one time), following appears: 'Temp Control' 'Set Point Temp 1/18'

- 4.10 √Set Point Temp = desired Set Point
- pb Right (EXIT) \rightarrow Press until '**HOME**' appears 4.11
- 5. **TEMPERATURE CONTROL SENSORS**
 - pb Left (MENU) \rightarrow Press (one time), following appears: 'MAIN MENU' 5.1 'QUICK STATUS 1/5'
 - 5.2 pb Left (NEXT) \rightarrow Press (three times), following appears: 'MAIN MENU' 'SETUP 4/5'
 - pb Center (SELECT) \rightarrow Press (one time), following appears: 'SETUP' 5.3 'Temp Control 1/3'
 - pb Center (SELECT) \rightarrow Press (one time), following appears: 5.4 Temp Control 'Set Point Temp 1/18'
 - pb Left (NEXT) \rightarrow Press (two times), following appears: 'Temp Control' 5.5 'Control Sensors 3/18'
 - 5.6 pb Center (SELECT) \rightarrow Press (one time), following appears: Control Sensors' 'INNER OUTLET INLET'

- 1. The left pushbutton (CURSOR) moves cursor between Control Sensor fields. The default cursor position will be blinking.
- 2. The center pushbutton (PLUS) changes the values of the Control Sensor fileds from 0 to 1 or vice versa.
- Enter desired combination of Control Sensors per MCC-H 5.7
- 5.8 pb Right (DONE) \rightarrow Press (one time)
- 5.9 ✓ Confirm New Control Sensors = desired Control Sensors
- pb Left (APPLY) \rightarrow Press (one time), following appears: 'Temp Control' 5.10 'Control Sensors 3/18'
- 5.11 √Control Sensors = desired Control Sensors
- 5.12 pb Right (EXIT) \rightarrow Press until '**HOME**' appears
- 6. AIR MANAGEMENT PROCEED MESSAGE
 - 6.1 pb Left (MENU) \rightarrow Press (one time), following appears: 'MAIN MENU'

(ASSY OPS/2JA/FIN)

'QUICK STATUS 1/5'

- 6.2 pb Left (NEXT) → Press (three times), following appears: 'MAIN MENU' 'SETUP 4/5'
- 6.3 pb Center (SELECT) → Press (one time), following appears: 'SETUP' 'Temp Control 1/3'
- 6.4 pb Center (SELECT) → Press (one time), following appears: 'Temp Control' 'Set Point Temp 1/18'
- 6.5 pb Left (NEXT) → Press (three times), following appears: 'Temp Control' 'AirMgmt Proceed 4/18'
- 6.6 pb Center (SELECT) → Press (one time), following appears: 'AirMgmt Proceed' 'PROCEED'
- 6.7 pb Center (APPLY) \rightarrow Press (one time)
- 6.8 ✓Display line 3 PROCEED
- 6.9 pb Right (EXIT) → Press until 'HOME' appears
- 7. TEMPERATURE CONTROL BANDWIDTH
 - 7.1 pb Left (MENU) → Press (one time), following appears: 'MAIN MENU' 'QUICK STATUS 1/5'
 - 7.2 pb Left (NEXT) \rightarrow Press (three times), following appears: 'MAIN MENU' 'SETUP 4/5'
 - 7.3 pb Center (SELECT) → Press (one time), following appears: 'SETUP' 'Temp Control 1/3'
 - 7.4 pb Center (SELECT) → Press (one time), following appears: 'Temp Control' 'Set Point Temp 1/18'
 - 7.5 pb Left (NEXT) → Press (four times), following appears:
 'Temp Control'
 'Bandwidth 5/18'
 'XX.X °C'
 - 7.6 pb Center (SELECT) → Press (one time), following appears:
 'Bandwidth'
 'XX.X °C'
 '00.1 to 25.5'

1. The left pushbutton (CURSOR) moves cursor between Bandwidth fields. The default cursor position will be blinking.

2. The center pushbutton (PLUS) increases Bandwidth selected digit field value by 1.

- 7.7 Enter desired Bandwidth per MCC-H
- 7.8 pb Right (DONE) \rightarrow Press (one time)
- 7.9 ✓Confirm New Bandwidth = desired Bandwidth
- 7.10 pb Left (APPLY) → Press (one time), following appears: 'Temp Control' 'Bandwidth 5/18'
- 7.11 \checkmark Bandwidth = desired Bandwidth
- 7.12 pb Right (EXIT) → Press until 'HOME' appears

8. PRIMARY COOLER

- 8.1 pb Left (MENU) → Press (one time), following appears:
 'MAIN MENU'
 'QUICK STATUS 1/5'
- 8.2 pb Left (NEXT) → Press (three times), following appears:
 'MAIN MENU'
 'SETUP 4/5'
- 8.3 pb Center (SELECT) → Press (one time), following appears:
 'SETUP'
 'Temp Control 1/3'
- 8.4 pb Center (SELECT) → Press (one time), following appears:
 'Temp Control'
 'Set Point Temp 1/18'
- 8.5 pb Left (NEXT) → Press (five times), following appears:
 'Temp Control'
 'Primary Cooler 6/18'
- 8.6 pb Center (SELECT) → Press (one time), following appears:
 'Primary Cooler'
 'COOLER X'

- 1. There are 2 options for Primary Cooler (COOLER 1 and COOLER 2).
- The left pushbutton (NEXT) changes the Primary Cooler, the center pushbutton (APPLY) selects the Primary Cooler, and the right pushbutton (CANCEL) returns to the previous display.

- 8.7 pb Left (NEXT) → Press as required to select desired Primary Cooler per MCC-H
- 8.8 pb Center (APPLY) \rightarrow Press (one time)
- 8.9 ✓Confirm New Primary Cooler = desired Cooler
- 8.10 pb Left (APPLY) → Press (one time), following appears: 'Temp Control' 'Primary Cooler 6/18'
- 8.11 √Primary Cooler = desired Cooler
- 8.12 pb Right (EXIT) → Press until 'HOME' appears
- 9. COOLER 1 STROKE
 - 9.1 pb Left (MENU) → Press (one time), following appears: 'MAIN MENU' 'QUICK STATUS 1/5'
 - 9.2 pb Left (NEXT) → Press (three times), following appears:
 'MAIN MENU'
 'SETUP 4/5'
 - 9.3 pb Center (SELECT) → Press (one time), following appears: 'SETUP' 'Temp Control 1/3'
 - 9.4 pb Center (SELECT) → Press (one time), following appears: 'Temp Control' 'Set Point Temp 1/18'
 - 9.5 pb Left (NEXT) → Press (six times), following appears: 'Temp Control' 'Cooler 1 Stroke 7/18'
 - 9.6 pb Center (SELECT) → Press (one time), following appears: 'Cooler 1 Stroke' 'XX' '03 to 63'

- 1. The left pushbutton (CURSOR) moves cursor between Stroke fields. The default cursor position will be blinking.
- 2. The center pushbutton (PLUS) increases Cooler Stroke selected digit field by 1.
- 9.7 Enter desired Cooler 1 Stroke value per MCC-H
- 9.8 pb Right (DONE) \rightarrow Press (one time)
- 9.9 ✓Confirm New Cooler 1 Stroke = desired Cooler 1 Stroke

- 9.10 pb Left (APPLY) → Press (one time), following appears: 'Temp Control' 'Cooler 1 Stroke 7/18'
- 9.11 ✓Cooler 1 Stroke = desired Cooler 1 Stroke
- 9.12 pb Right (EXIT) → Press until 'HOME' appears
- 10. COOLER 1 STATE
 - 10.1 pb Left (MENU) → Press (one time), following appears: 'MAIN MENU' 'QUICK STATUS 1/5'
 - 10.2 pb Left (NEXT) → Press (three times), following appears: 'MAIN MENU' 'SETUP 4/5'
 - 10.3 pb Center (SELECT) → Press (one time), following appears: 'SETUP' 'Temp Control 1/3'
 - 10.4 pb Center (SELECT) → Press (one time), following appears: 'Temp Control' 'Set Point Temp 1/18'
 - 10.5 pb Left (NEXT) → Press (seven times), following appears: 'Temp Control' 'Cooler 1 State 8/18'
 - 10.6 pb Center (SELECT) \rightarrow Press (one time), following appears: 'Cooler 1 State' 'XX'

- 1. There are 2 options for Cooler 1 State (ON and OFF).
- 2. The left pushbutton (NEXT) changes the Cooler 1 State, the center pushbutton (APPLY) selects the State, and the right pushbutton (CANCEL) returns to the previous display.
- 10.7 pb Left (NEXT) \rightarrow Press as required to select desired Cooler 1 State per MCC-H
- 10.8 pb Center (APPLY) \rightarrow Press (one time)
- 10.9 ✓Confirm New Cooler 1 State = desired State
- 10.10 pb Left (APPLY) → Press (one time), following appears: 'Temp Control' 'Cooler 1 State 8/18'
- 10.11 ✓ Cooler 1 State = desired Cooler 1 State
- 10.12 pb Right (EXIT) → Press until 'HOME' appears

11. COOLER 2 STROKE

- 11.1 pb Left (MENU) → Press (one time), following appears:
 'MAIN MENU'
 'QUICK STATUS 1/5'
- 11.2 pb Left (NEXT) → Press (three times), following appears:
 'MAIN MENU'
 'SETUP 4/5'
- 11.3 pb Center (SELECT) → Press (one time), following appears:
 'SETUP'
 'Temp Control 1/3'
- 11.4 pb Center (SELECT) → Press (one time), following appears:
 'Temp Control'
 'Set Point Temp 1/18'
- 11.5 pb Left (NEXT) → Press (eight times), following appears:
 'Temp Control'
 'Cooler 2 Stroke 9/18'
- 11.6 pb Center (SELECT) → Press (one time), following appears:
 'Cooler 2 Stroke'
 'XX'
 '03 to 63'

- 1. The left pushbutton (CURSOR) moves cursor between Stroke fields. The default cursor position will be blinking.
- The center pushbutton (PLUS) increases Cooler Stroke selected digit field by 1.
- 11.7 Enter desired Cooler 2 Stroke value per MCC-H
- 11.8 pb Right (DONE) \rightarrow Press (one time)
- 11.9 ✓Confirm New Cooler 2 Stroke = desired Cooler 2 Stroke
- 11.10 pb Left (APPLY) → Press (one time), following appears: 'Temp Control' 'Cooler 2 Stroke 9/18'
- 11.11 ✓ Cooler 2 Stroke = desired Cooler 2 Stroke
- 11.12 pb Right (EXIT) → Press until 'HOME' appears
- 12. COOLER 2 STATE
 - 12.1 pb Left (MENU) \rightarrow Press (one time), following appears: 'MAIN MENU' 'QUICK STATUS 1/5'
 - 12.2 pb Left (NEXT) \rightarrow Press (three times), following appears:

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'MAIN MENU' 'SETUP 4/5'

- 12.3 pb Center (SELECT) → Press (one time), following appears:
 'SETUP'
 'Temp Control 1/3'
- 12.4 pb Center (SELECT) → Press (one time), following appears: 'Temp Control' 'Set Point Temp 1/18'
- 12.5 pb Left (NEXT) → Press (nine times), following appears: 'Temp Control' 'Cooler 2 State 10/18'
- 12.6 pb Center (SELECT) → Press (one time), following appears: 'Cooler 2 State' 'XX'

- 1. There are 2 options for Cooler 2 State (ON and OFF).
- The left pushbutton (NEXT) changes the Cooler 2 State, the center pushbutton (APPLY) selects the State, and the right pushbutton (CANCEL) returns to the previous display.
- 12.7 pb Left (NEXT) → Press as required to select desired Cooler 2 State per MCC-H
- 12.8 pb Center (APPLY) \rightarrow Press (one time)
- 12.9 ✓Confirm New Cooler 2 State = desired State
- 12.10 pb Left (APPLY) → Press (one time), following appears: 'Temp Control' 'Cooler 2 State 10/18'
- 12.11 ✓ Cooler 2 State = desired Cooler 2 State
- 12.12 pb Right (EXIT) → Press until 'HOME' appears
- 13. MAXIMUM POWER DRAW
 - 13.1 pb Left (MENU) → Press (one time), following appears:
 'MAIN MENU'
 'QUICK STATUS 1/5'
 - pb Left (NEXT) → Press (three times), following appears:
 'MAIN MENU'
 'SETUP 4/5'
 - 13.3 pb Center (SELECT) → Press (one time), following appears: 'SETUP' 'Temp Control 1/3'

- 13.4 pb Center (SELECT) → Press (one time), following appears:
 'Temp Control'
 'Set Point Temp 1/18'
- 13.5 pb Left (NEXT) → Press (twelve times), following appears:
 'Temp Control'
 'Max Power Draw 13/18'
- 13.6 pb Center (SELECT) → Press (one time), following appears:
 'Max Power Draw'
 'XXX W'
 '000 to 420'

- 1. The left pushbutton (CURSOR) moves cursor between fields. The default cursor position will be blinking.
- 2. The center pushbutton (PLUS) increases selected digit field by 1.
- 13.7 Enter desired Max Power Draw value per MCC-H
- 13.8 pb Right (DONE) \rightarrow Press (one time)
- 13.9 ✓Confirm New Max Power = desired Max Power Draw
- 13.10 pb Left (APPLY) → Press (one time), following appears: 'Temp Control' 'Max Power Draw 13/18'
- 13.11 √Max Power Draw = desired Max Power Draw
- 13.12 pb Right (EXIT) → Press until 'HOME' appears
- 14. OVER CURRENT
 - 14.1 pb Left (MENU) → Press (one time), following appears:
 'MAIN MENU'
 'QUICK STATUS 1/5'
 - 14.2 pb Left (NEXT) → Press (three times), following appears:
 'MAIN MENU'
 'SETUP 4/5'
 - 14.3 pb Center (SELECT) → Press (one time), following appears: 'SETUP' 'Temp Control 1/3'
 - 14.4 pb Center (SELECT) → Press (one time), following appears: 'Temp Control' 'Set Point Temp 1/18'
 - 14.5 pb Left (NEXT) → Press (thirteen times), following appears:
 'Temp Control'
 'Over Current 14/18'

14.6 pb Center (SELECT) → Press (one time), following appears:
'Over Current'
'XX.X A'
'00.0 to 30.0'

NOTE

1. The left pushbutton (CURSOR) moves cursor between fields. The default cursor position will be blinking.

2. The center pushbutton (PLUS) increases selected digit field by 1.

- 14.7 Enter desired Over Current value per MCC-H
- 14.8 pb Right (DONE) \rightarrow Press (one time)
- 14.9 ✓Confirm New Over Current = desired Over Current
- 14.10 pb Left (APPLY) → Press (one time), following appears: 'Temp Control' 'Over Current 14/18'
- 14.11 ✓ Over Current = desired Over Current
- 14.12 pb Right (EXIT) → Press until 'HOME' appears

15. AIR MANAGEMENT MODE

- 15.1 pb Left (MENU) → Press (one time), following appears:
 'MAIN MENU'
 'QUICK STATUS 1/5'
- 15.2 pb Left (NEXT) → Press (three times), following appears:
 'MAIN MENU'
 'SETUP 4/5'
- 15.3 pb Center (SELECT) → Press (one time), following appears: 'SETUP' 'Temp Control 1/3'
- 15.4 pb Left (NEXT) → Press (one time), following appears:
 'SETUP'
 'Air Management 2/3'
- 15.5 pb Center (SELECT) → Press (one time), following appears: 'Air Management' 'Air Mgmt Mode 1/6'
- 15.6 pb Center (SELECT) → Press (one time), following appears: 'Air Mgmt Mode' 'XXXXX'

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<u>NOTE</u>

1. There are 2 options for Air Mgmt Mode (MANUAL and AUTOMATIC).

 The left pushbutton (NEXT) changes the Mode, the center pushbutton (APPLY) selects the Mode, and the right pushbutton (CANCEL) returns to the previous display.

- 15.7 pb Left (NEXT) → Press as required to select desired Air Mgmt Mode per MCC-H
- 15.8 pb Center (APPLY) \rightarrow Press (one time)
- 15.9 ✓Confirm New Air Mgmt Mode = desired Air Mgmt Mode
- 15.10 pb Left (APPLY) → Press (one time), following appears: 'Air Management' 'Air Mgmt Mode 1/6'
- $15.11 \checkmark$ Air Mgmt Mode = desired Air Mgmt Mode
- 15.12 pb Right (EXIT) → Press until 'HOME' appears

16. AIR MANAGEMENT HUMIDITY

- 16.1 pb Left (MENU) → Press (one time), following appears:
 'MAIN MENU'
 'QUICK STATUS 1/5'
- 16.2 pb Left (NEXT) → Press (three times), following appears: 'MAIN MENU' 'SETUP 4/5'
- 16.3 pb Center (SELECT) → Press (one time), following appears: 'SETUP' 'Temp Control 1/3'
- 16.4 pb Left (NEXT) → Press (one time), following appears:
 'SETUP'
 'Air Management 2/3'
- 16.5 pb Center (SELECT) → Press (one time), following appears: 'Air Management' 'Air Mgmt Mode 1/6'
- 16.6 pb Left (NEXT) → Press (one time), following appears:
 'Air Management'
 'Humidity Config 2/6'
- 16.7 pb Center (SELECT) → Press (one time), following appears:
 'Humidity Config'
 'Pump: 12 Valve: 1234'
 'XX XXXX'

1. The left pushbutton (CURSOR) moves cursor between fields. The default cursor position will be blinking.

2. The center pushbutton (PLUS) toggles the selected Pump (1 or 2) or Valve (1-4) between 0 and 1 (OFF/ON).

- 16.8 Enter desired Humidity Config per MCC-H
- 16.9 pb Right (DONE) \rightarrow Press (one time)
- 16.10 ✓ Confirm New Humidity Config = desired Humidity Config
- 16.11 pb Left (APPLY) → Press (one time), following appears: 'Air Management' 'Humidity Config 2/6'
- 16.12 √ Humidity Config = desired Humidity Config
- 16.13 pb Right (EXIT) \rightarrow Press until '**HOME**' appears
- 17. AIR MANAGEMENT PRESSURE CONFIGURATION
 - 17.1 pb Left (MENU) \rightarrow Press (one time), following appears: 'MAIN MENU' 'QUICK STATUS 1/5'
 - 17.2 pb Left (NEXT) → Press (three times), following appears: 'MAIN MENU' 'SETUP 4/5'
 - 17.3 pb Center (SELECT) → Press (one time), following appears: 'SETUP' 'Temp Control 1/3'
 - 17.4 pb Left (NEXT) → Press (one time), following appears:
 'SETUP'
 'Air Management 2/3'
 - 17.5 pb Center (SELECT) → Press (one time), following appears: 'Air Management' 'Air Mgmt Mode 1/6'
 - 17.6 pb Left (NEXT) → Press (two times), following appears: 'Air Management' 'Pressure Config 3/6'
 - 17.7 pb Center (SELECT) → Press (one time), following appears: 'Pressure Config' 'Pump: 12 Valve: 1234' 'XX XXXX'

- 1. The left pushbutton (CURSOR) moves cursor between fields. The default cursor position will be blinking.
- 2. The center pushbutton (PLUS) toggles the selected Pump (1 or 2) or Valve (1-4) between 0 and 1 (OFF/ON).
- 17.8 Enter desired Pressure Config per MCC-H
- 17.9 pb Right (DONE) \rightarrow Press (one time)
- 17.10 ✓ Confirm New Pressure Config = desired Pressure Config
- 17.11 pb Left (APPLY) → Press (one time), following appears: 'Air Management' 'Pressure Config 3/6'
- 17.12 √ Pressure Config = desired Pressure Config
- 17.13 pb Right (EXIT) \rightarrow Press until '**HOME**' appears
- 18. AIR MANAGEMENT MANUAL CONFIGURATION
 - 18.1 pb Left (MENU) → Press (one time), following appears:
 'MAIN MENU'
 'QUICK STATUS 1/5'
 - 18.2 pb Left (NEXT) → Press (three times), following appears:
 'MAIN MENU'
 'SETUP 4/5'
 - 18.3 pb Center (SELECT) → Press (one time), following appears:
 'SETUP'
 'Temp Control 1/3'
 - 18.4 pb Left (NEXT) → Press (one time), following appears:
 'SETUP'
 'Air Management 2/3'
 - 18.5 pb Center (SELECT) → Press (one time), following appears:
 'Air Management'
 'Air Mgmt Mode 1/6'
 - 18.6 pb Left (NEXT) → Press (three times), following appears:
 'Air Management'
 'Manual Config 4/6'
 - 18.7 pb Center (SELECT) → Press (one time), following appears:
 'Manual Config'
 'Pump: 12 Valve: 1234'
 'XX XXXX'

1. The left pushbutton (CURSOR) moves cursor between fields. The default cursor position will be blinking.

2. The center pushbutton (PLUS) toggles the selected Pump (1 or 2) or Valve (1-4) between 0 and 1 (OFF/ON).

- 18.8 Enter desired Manual Config per MCC-H
- 18.9 pb Right (DONE) \rightarrow Press (one time)
- 18.10 ✓ Confirm New Manual Config = desired Manual Config
- 18.11 pb Left (APPLY) → Press (one time), following appears:
 'Air Management'
 'Manual Config 4/6'
- 18.12 ✓ Manual Config = desired Manual Config
- 18.13 pb Right (EXIT) → Press until '**HOME**' appears
- 19. START HUMIDITY MONITORING TIME
 - 19.1 pb Left (MENU) → Press (one time), following appears:
 'MAIN MENU'
 'QUICK STATUS 1/5'
 - 19.2 pb Left (NEXT) → Press (three times), following appears:
 'MAIN MENU'
 'SETUP 4/5'
 - 19.3 pb Center (SELECT) → Press (one time), following appears:
 'SETUP'
 'Temp Control 1/3'
 - 19.4 pb Left (NEXT) → Press (one time), following appears:
 'SETUP'
 'Air Management 2/3'
 - 19.5 pb Center (SELECT) → Press (one time), following appears:
 'Air Management'
 'Air Mgmt Mode 1/6'
 - 19.6 pb Left (NEXT) → Press (four times), following appears:
 'Air Management'
 'Start Humidity 5/6'
 - 19.7 pb Center (SELECT) → Press (one time), following appears:
 'Start Humidity'
 'XXXXX seconds'
 '00000 to 65535'

- 1. The left pushbutton (CURSOR) moves cursor between fields. The default cursor position will be blinking.
- 2. The center pushbutton (PLUS) increases the selected digit field value by 1.
- 19.8 Enter desired Start Humidity per MCC-H
- 19.9 pb Right (DONE) \rightarrow Press (one time)
- 19.10 ✓ Confirm New Start Humidity = desired Start Humidity
- 19.11 pb Left (APPLY) → Press (one time), following appears: 'Air Management' 'Start Humidity 5/6'
- 19.12 ✓ Start Humidity = desired Start Humidity
- 19.13 pb Right (EXIT) → Press until '**HOME**' appears
- 20. START PRESSURE MONITORING TIME
 - 20.1 pb Left (MENU) → Press (one time), following appears: 'MAIN MENU' 'QUICK STATUS 1/5'
 - 20.2 pb Left (NEXT) \rightarrow Press (three times), following appears: 'MAIN MENU' 'SETUP 4/5'
 - 20.3 pb Center (SELECT) → Press (one time), following appears: 'SETUP' 'Temp Control 1/3'
 - 20.4 pb Left (NEXT) → Press (one time), following appears: 'SETUP' 'Air Management 2/3'
 - 20.5 pb Center (SELECT) → Press (one time), following appears: 'Air Management' 'Air Mgmt Mode 1/6'
 - 20.6 pb Left (NEXT) → Press (five times), following appears: 'Air Management' 'Start Pressure 6/6'
 - 20.7 pb Center (SELECT) → Press (one time), following appears: 'Start Pressure' 'XXXXX seconds' '00000 to 65535'

- 1. The left pushbutton (CURSOR) moves cursor between fields. The default cursor position will be blinking.
- The center pushbutton (PLUS) increases the selected digit field value by 1.
- 20.8 Enter desired Start Pressure per MCC-H
- 20.9 pb Right (DONE) \rightarrow Press (one time)
- 20.10 √ Confirm New Start Pressure = desired Start Pressure
- 20.11 pb Left (APPLY) → Press (one time), following appears: 'Air Management' 'Start Pressure 6/6'
- 20.12 ✓ Start Pressure = desired Start Pressure
- 20.13 pb Right (EXIT) → Press until 'HOME' appears
- 21. CIRCULATION FAN MODE
 - 21.1 pb Left (MENU) → Press (one time), following appears: 'MAIN MENU' 'QUICK STATUS 1/5'
 - 21.2 pb Left (NEXT) → Press (three times), following appears: 'MAIN MENU' 'SETUP 4/5'
 - 21.3 pb Center (SELECT) → Press (one time), following appears: 'SETUP' 'Temp Control 1/3'
 - 21.4 pb Left (NEXT) → Press (two times), following appears: 'SETUP' 'Auxiliary 3/3'
 - 21.5 pb Center (SELECT) → Press (one time), following appears: 'Auxiliary' 'Circ Fan Mode 1/7'
 - 21.6 pb Center (SELECT) → Press (one time), following appears: 'Circ Fan Mode' 'XXXXX'

- 1. There are 2 options for Circ Fan Mode (MANUAL and AUTOMATIC).
- The left pushbutton (NEXT) changes the Mode, the center pushbutton (APPLY) selects the Mode, and the right pushbutton (CANCEL) returns to the previous display.

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- 21.7 pb Left (NEXT) \rightarrow Press as required to select desired Circ Fan Mode per MCC-H
- 21.8 pb Center (APPLY) \rightarrow Press (one time)
- 21.9 ✓Confirm New Circ Fan Mode = desired Circ Fan Mode
- 21.10 pb Left (APPLY) → Press (one time), following appears: 'Auxiliary' 'Circ Fan Mode 1/7'
- 21.11 ✓ Circ Fan Mode = desired Circ Fan Mode
- 21.12 pb Right (EXIT) → Press until 'HOME' appears
- 22. CIRCULATION FAN POWER
 - 22.1 pb Left (MENU) → Press (one time), following appears: 'MAIN MENU' 'QUICK STATUS 1/5'
 - 22.2 pb Left (NEXT) → Press (three times), following appears: 'MAIN MENU' 'SETUP 4/5'
 - 22.3 pb Center (SELECT) → Press (one time), following appears: 'SETUP' 'Temp Control 1/3'
 - 22.4 pb Left (NEXT) → Press (two times), following appears: 'SETUP' 'Auxiliary 3/3'
 - 22.5 pb Center (SELECT) → Press (one time), following appears: 'Auxiliary' 'Circ Fan Mode 1/7'
 - 22.6 pb Left (NEXT) \rightarrow Press (one time), following appears: 'Auxiliary' 'Circ Fan Power 2/7'
 - 22.7 pb Center (SELECT) → Press (one time), following appears: 'Circ Fan Power' 'XXX %' '000 to 090'

- 1. The left pushbutton (CURSOR) moves cursor between fields. The default cursor position will be blinking.
- 2. The center pushbutton (PLUS) increases the selected digit field value by 1.
- 22.8 Enter desired Circ Fan Power per MCC-H

- 22.9 pb Right (DONE) \rightarrow Press (one time)
- 22.10 √ Confirm New Circ Fan Power = desired Circ Fan Power
- 22.11 pb Left (APPLY) → Press (one time), following appears: 'Auxiliary' 'Circ Fan Power 2/7'
- 22.12 ✓ Circ Fan Power = desired Circ Fan Power
- 22.13 pb Right (EXIT) → Press until 'HOME' appears
- 23. DATA STORAGE INTERVAL
 - 23.1 pb Left (MENU) → Press (one time), following appears: 'MAIN MENU' 'QUICK STATUS 1/5'
 - 23.2 pb Left (NEXT) → Press (three times), following appears:
 'MAIN MENU'
 'SETUP 4/5'
 - 23.3 pb Center (SELECT) → Press (one time), following appears: 'SETUP' 'Temp Control 1/3'
 - 23.4 pb Left (NEXT) → Press (two times), following appears: 'SETUP' 'Auxiliary 3/3'
 - 23.5 pb Center (SELECT) → Press (one time), following appears: 'Auxiliary' 'Circ Fan Mode 1/7'
 - 23.6 pb Left (NEXT) → Press (two times), following appears:
 'Auxiliary'
 'Data Storage 3/7'
 - 23.7 pb Center (SELECT) → Press (one time), following appears:
 'Data Storage'
 'XXXX seconds'
 '0000 to 3600'

1. The left pushbutton (CURSOR) moves cursor between fields. The default cursor position will be blinking.

The center pushbutton (PLUS) increases the selected digit field value by
 1.

- 23.8 Enter desired Data Storage per MCC-H
- 23.9 pb Right (DONE) \rightarrow Press (one time)
- 23.10 ✓ Confirm New Store Period = desired Store Period

- 23.11 pb Left (APPLY) → Press (one time), following appears: 'Auxiliary' 'Data Storage 3/7'
- 23.12 ✓ Data Storage = desired Data Storage
- 23.13 pb Right (EXIT) → Press until 'HOME' appears

24. TEMPERATURE CONTROL MODE

- 24.1 pb Left (MENU) → Press (one time), following appears: 'MAIN MENU' 'QUICK STATUS 1/5'
- 24.2 pb Left (NEXT) → Press (three times), following appears: 'MAIN MENU' 'SETUP 4/5'
- 24.3 pb Center (SELECT) → Press (one time), following appears: 'SETUP' 'Temp Control 1/3'
- 24.4 pb Center (SELECT) → Press (one time), following appears: 'Temp Control' 'Set Point Temp 1/18'
- 24.5 pb Left (NEXT) → Press (one time), following appears: 'Temp Control' 'Control Mode 2/18'
- 24.6 pb Center (SELECT) → Press (one time), following appears: 'Control Mode' 'XXXX'

- 1. There are 3 options for setting the Control Mode (IDLE, SET POINT, and MANUAL).
- The left pushbutton (NEXT) changes the Mode, the center pushbutton (APPLY) selects the Mode, and the right pushbutton (CANCEL) returns to the previous Mode.
- 24.7 pb Left (NEXT) \rightarrow Press as required to select desired Temperature Control Mode per **MCC-H**
- 24.8 pb Center (APPLY) \rightarrow Press (one time)
- 24.9 ✓Confirm New Control Mode = desired Control Mode
- 24.10 pb Left (APPLY) → Press (one time), following appears: 'Temp Control' 'Control Mode 2/18'
- 24.11 ✓ Control Mode = desired Control Mode

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24.12 pb Right (EXIT) \rightarrow Press until '**HOME**' appears

25. Notify **MCC-H** GLACIER MANUAL RECONFIGURATION is complete.

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GLACIER POWER CYCLE

(ASSY OPS/2JA/FIN)

OBJECTIVE:

The following steps will perform a power cycle of the Glacier System.

On MCC-H GO

| | | \$************************************* |
|---------|----|---------------------------------------------------------------------------------------------------------------------------------------------------------------|
| | | * If Display - ' **Error Pending** ' |
| | | * Perform GLACIER ERROR MESSAGE, then: |
| | | *************************************** |
| Glacier | 1. | ✓Display 'HOME' * * * * * * * * * * * * * * * * * * * |
| | | $\stackrel{\circ}{}_{*} \qquad \qquad$ |
| | 2. | pb Left (MENU) → Press (one time), following appears: 'MAIN MENU' 'QUICK STATUS 1/5' |
| | 3. | pb Left (NEXT) → Press (four times), following appears: 'MAIN MENU' 'SHUTDOWN 5/5' |
| | 4. | pb Center (SELECT) → Press (one time), following appears 'SHUTDOWN' 'SHUTDOWN 1/2' |
| | 5. | pb Center (SELECT) → Press (one time), following appears: 'Confirm Shutdown' 'SHUTDOWN' |
| | 6. | pb Left (APPLY) → Press (one time), following appears: 'Glacier' 'System' 'Shutting Down' 'Please wait' |
| | 7. | Verify – 'Glacier' 'Shutdown Complete' 'TURN POWER OFF' |
| | 8. | Wait 5 seconds. |

Power light can take up to 2 minutes to fully extinguish. Once main power has been removed, the battery light will start to flash.

- 9. ✓BATTERY ON (It on)
- 10. cb POWER → Open (It off)
- 11. Wait 1 minute. (No need to wait for POWER light to extinguish)
- 12. cb POWER \rightarrow Close (It on)

| NOTE |
|----------------------------------------------------------------------------------------------------------------------------------|
| System Initialization may take up to 3 minutes. Initialization complete once ine 1 of front panel display reads ' HOME '. |

- 13. ✓Display 'HOME'
 - If 'HOME' not shown, Perform GLACIER FAIL TO REPOWER, then; If Display —'**Error Pending**' Perform GLACIER ERROR MESSAGE, then;
- 14. Log from Glacier front panel:
 - CURR TEMP: _____. °C
 - GPS: _____/___:____:
- 15. Notify MCC-H of Power Cycle completion and data recorded in Step 14.

GLACIER RECORD CRYOGENIC DIAGNOSTIC DATA

(ASSY OPS/2JA/FIN)

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OBJECTIVE:

The following steps allow the recording of some Glacier data for diagnostic purposes.

| *************************************** | | | |
|----------------------------------------------|--|--|--|
| * If Display – ' **Error Pending** ': | | | |
| * Perform GLACIER ERROR MESSAGE, then: | | | |
| *************************************** | | | |

1. RECORDING DATA

1.1 **✓MCC-H** for parameters to record in Table 3, GLACIER DIAGNOSTIC LOG FILE

Glacier 1.2 \checkmark DISPLAY – 'HOME' * If 'HOME' not shown: * | pb Right (EXIT) \rightarrow push until 'HOME' appears 2. <u>RECORDING CRYOGENIC STATUS</u>

- 2.1 Record from front panel 'CURR TEMP', 'SET POINT', and 'GPS' in Table 3, GLACIER DIAGNOSTIC LOG FILE.
- 2.2 pb Left (MENU) \rightarrow push (one time), following appears:

'MAIN MENU' 'QUICK STATUS 1/5'

2.3 pb Left (NEXT) \rightarrow push (one time), following appears:

'MAIN MENU' 'STATUS 2/5'

2.4 pb Center (SELECT) \rightarrow push (one time), following appears:

'STATUS' 'Cryogenic 1/3'

2.5 pb Center (SELECT) \rightarrow push (one time), following appears:

'Cryogenic' 'Cooler 1 Stroke 1/21' 'XX'

<u>NOTE</u>

1. The center pushbutton (NEXT) moves to next status display.

2. The left pushbutton (PREV) moves to previous status display.

- 2.6 Record Cryogenic data per **MCC-H** direction in Table 3, GLACIER DIAGNOSTIC LOG FILE
- 2.7 pb Center (NEXT) → press until all Cryogenic Status data has been recorded per MCC-H direction
- 2.8 pb Right (EXIT) \rightarrow push until 'HOME'
- 2.9 Notify **MCC-H** to report log values from Table 3, GLACIER DIAGNOSTIC LOG FILE.

GLACIER RECORD QUICK DIAGNOSTIC DATA

(ASSY OPS/2JA/FIN)

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OBJECTIVE:

The following steps allow the recording of some Glacier data for diagnostic purposes.

| ************************************** | | | |
|----------------------------------------------|--|--|--|
| * If Display – ' **Error Pending** ': | | | |
| * Perform GLACIER ERROR MESSAGE, then: | | | |
| *************************************** | | | |

1. RECORDING DATA

1.1 ✓**MCC-H** for parameters to record in Table 3, GLACIER DIAGNOSTIC LOG FILE

Glacier 1.2 ✓Display – 'HOME' * If 'HOME' not shown: * | pb Right (EXIT) → push until 'HOME' appears

2. <u>RECORDING QUICK STATUS</u>

- 2.1 Record from front panel 'CURR TEMP', 'SET POINT', and 'GPS'in Table 3, GLACIER DIAGNOSTIC LOG FILE.
- 2.2 pb Left (MENU) \rightarrow push (one time), following appears:

'MAIN MENU' 'QUICK STATUS 1/5'

2.3 pb Center (SELECT) \rightarrow push (one time), following appears:

'QUICK STATUS' 'Cold Head 1A 1/16'

- 1. The center pushbutton (NEXT) moves to next status display.
- 2. The left pushbutton (PREV) moves to previous status display.
- 2.4 Record Quick Status data per **MCC-H** direction in Table 3, GLACIER DIAGNOSTIC LOG FILE
- 2.5 pb Center (NEXT) → push until all Quick Status data has been recorded per **MCC-H** direction.
- 2.6 pb Right (EXIT) → push until 'HOME'

2.7 Notify **MCC-H** to report log values from Table 3, GLACIER DIAGNOSTIC LOG FILE.
GLACIER RECORD RESOURCES DIAGNOSTIC DATA

(ASSY OPS/2JA/FIN)

Page 1 of 2 pages

OBJECTIVE:

The following steps allow the recording of some Glacier data for diagnostic purposes.

| ************************************** | | | |
|----------------------------------------------|--|--|--|
| * If Display – ' **Error Pending** ': | | | |
| * Perform GLACIER ERROR MESSAGE, then: | | | |
| *************************************** | | | |

1. RECORDING DATA

1.1 **✓MCC-H** for parameters to record in Table 3, GLACIER DIAGNOSTIC LOG FILE

Glacier 1.2 \checkmark DISPLAY – 'HOME' * If 'HOME' not shown: * | pb Right (EXIT) \rightarrow push until 'HOME' appears 2. RECORDING RESOURCES STATUS

- 2.1 Record from front panel 'CURR TEMP', 'SET POINT', and 'GPS' in Table 3, GLACIER DIAGNOSTIC LOG FILE.
- 2.2 pb Left (MENU) \rightarrow push (one time), following appears:

'MAIN MENU' 'QUICK STATUS 1/5'

2.3 pb Left (NEXT) \rightarrow push (one time), following appears:

'MAIN MENU' 'STATUS 2/5'

2.4 pb Center (SELECT) \rightarrow push (one time), following appears:

'STATUS' 'Cryogenic 1/3'

2.5 pb Left (NEXT) \rightarrow push (one time), following appears:

'STATUS' ' Resources 2/3'

2.6 pb Center (SELECT) \rightarrow push (one time), following appears:

'Resources' 'AAA Outlet 1/8' (ASSY OPS/2JA/FIN)

Page 2 of 2 pages

'XX.X° C'

<u>NOTE</u>

1. The center pushbutton (NEXT) moves to next status display.

2. The left pushbutton (PREV) moves to previous status display.

- 2.7 Record Resource data per **MCC-H** direction in Table 3, GLACIER DIAGNOSTIC LOG FILE.
- 2.8 pb Center (NEXT) → push until all Resource data has been recorded per MCC-H direction.
- 2.9 pb Right (EXIT) \rightarrow push until 'HOME'
- 2.10 Notify **MCC-H** to report log values from Table 3, DIAGNOSTIC LOG FILE.

GLACIER RECORD SYSTEM DIAGNOSTIC DATA

(ASSY OPS/2JA/FIN)

Page 1 of 2 pages

OBJECTIVE:

The following steps allow the recording of some Glacier data for diagnostic purposes.

| ************************************** | | | |
|----------------------------------------------|--|--|--|
| * If Display – ' **Error Pending** ': | | | |
| * Perform GLACIER ERROR MESSAGE, then: | | | |
| ***** | | | |

1. RECORDING DATA

1.1 ✓**MCC-H** for parameters to record in Table 3, GLACIER DIAGNOSTIC LOG FILE

Glacier 1.2 \checkmark DISPLAY – 'HOME' * If 'HOME' not shown: * | pb Right (EXIT) \rightarrow push until 'HOME' appears 2. <u>RECORDING SYSTEM STATUS</u>

- 2.1 Record from front panel 'CURR TEMP', 'SET POINT', and 'GPS' in Table 3, GLACIER DIAGNOSTIC LOG FILE.
- 2.2 Left (MENU) $pb \rightarrow push$ (one time), following appears:

'MAIN MENU'

'QUICK STATUS 1/5'

2.3 Left (NEXT) $pb \rightarrow push$ (one time), following appears: 'MAIN MENU'

'STATUS 2/5'

2.4 Center (SELECT) $pb \rightarrow push$ (one time), following appears: 'STATUS'

'Cryogenic 1/3'

2.5 Left (NEXT) $pb \rightarrow push$ (two times), following appears: 'STATUS'

'System 3/3'

2.6 Center (SELECT) pb → push (one time), following appears:
 'System'
 'CPU 1/9'

'XX.X° C'

NOTE

- 1. The center pushbutton (NEXT) moves to next status display.
- 2. The left pushbutton (PREV) moves to previous status display.
- 2.7 Record System Status data per **MCC-H** direction in Table 3, GLACIER DIAGNOSTIC LOG FILE.
- 2.8 Center (NEXT) $pb \rightarrow push$ until all System Status data has been recorded per **MCC-H** direction.
- 2.9 Right (EXIT) $pb \rightarrow push until 'HOME'$
- 2.10 Notify **MCC-H** to report log values from Table 3, GLACIER DIAGNOSTIC LOG FILE.

TABLE 1 GLACIER ERROR MESSAGE LOG

(ASSY OPS/2JA/FIN) Page 1 of 3 pages

| GMT | Error Message | Error Event | Error Status |
|----------------------------|---------------|----------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------|
| Hours: Minutes: Seconds | Text | X of Total Number | (IP) INACTIVE / PENDING (AP) ACTIVE / PENDING (IA) INACTIVE / ACK (AA) ACTIVE / ACK (R) RESET |
| :: | | / | |
| :: | | / | |
| :: | | / | |
| :: | | / | |
| :: | | / | |
| :: | | / | |
| :: | | / | |
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| :: | | / | |
| :: | | / | |
| :: | | / | |
| :: | | / | |
| :: | | / | |

Table 1-1 Glacier Error Log File

TABLE 1 GLACIER ERROR MESSAGE LOG

(ASSY OPS/2JA/FIN) Page 2 of 3 pages

Possible Glacier Error Messages:

- (1) '**N/A**' (Ground Message Only)
- (2) 'Water Flow Range'
- (3) 'Water Temp Range'
- (4) 'AAA Air Temp'
- (5) 'Voltage Range'
- (6) 'Current Range'
- (7) 'RIC Comm Loss'
- (8) 'Over Temp'
- (9) 'Hardware Error'
- (10) 'Bandwidth'

| | č () | |
|--------------|--------------|-------|
| Sensor | Value | Units |
| Outlet Water | | °C |
| Inlet Water | | °C |
| Flow Rate | | kg/h |

Table 1-2 (002) Water Flow Range/(003) Water Temp Range Error Data

Table 1-3 (004) AAA Air Temp Error Data

| Sensor | Value | Units |
|-------------|-------|-------|
| AAA Outlet | | °C |
| AAA Inlet 1 | | °C |
| AAA Inlet 2 | | °C |

| Table 1-4 (005 |) Voltage | Range/(006) | Current Rang | e Error Data |
|----------------|-----------|-------------|--------------|--------------|
|----------------|-----------|-------------|--------------|--------------|

| Sensor | Value | Units |
|--------------|-------|---------|
| Main Current | | Amperes |
| Main Voltage | | Volts |
| Over Current | | Amperes |

TABLE 1 GLACIER ERROR MESSAGE LOG

(ASSY OPS/2JA/FIN) Page 3 of 3 pages

Table 1-5 (008) Over Temp Error Data

| Sensor | Value | Units |
|--------------|-------|-------|
| CPU | | °C |
| Capacitors A | | °C |
| Capacitors B | | °C |
| Data Logger | | °C |

Table 1-6 Bandwidth Error Data

| Parameter | Value | Units |
|----------------|-------|----------|
| CURR TEMP | | °C |
| SET POINT | | °C |
| GPS | | HH:MM:SS |
| Cold Head 1A | | °C |
| Cold Head 1B | | °C |
| Cold Head 2A | | °C |
| Cold Head 2B | | °C |
| Circ Fan Speed | | RPM |

(ASSY OPS/2JA/FIN) Page 1 of 5 pages

| | Parameter | Event 1 | Event 2 | Definition or Options | |
|------|-----------------------------------------------------------|--------------------------|--------------------------|------------------------------------------------------------------------------------|--|
| 1 | CURR TEMP | Start °C End °C | Start °C End °C | GLACIER Current Temperature XXXX.XX °C | |
| 2 | SET POINT | Start °C End °C | Start °C End °C | -160.0 to +4.0° C | |
| 3 | GPS | Start:: GPS End:: GPS | Start:: GPS End:: GPS | Hours: Min: Sec | |
| 4 | Expected CURR TEMP | °C | °C | Expected Glacier Current Temperature per MCC-H (-160.0 to +4.0° C) | |
| 5 | Expected SET POINT | °C | °C | Expected Set Point Temperature per MCC-H (-160.0 to + 4.0° C) | |
| Valu | Values for Reconfiguration of Setup: Temperature Control: | | | | |
| 6 | Set Point Temp | °C | °C | -160.0 to +4.0° C | |

(ASSY OPS/2JA/FIN) Page 2 of 5 pages

| | Parameter | Event 1 | Event 2 | Definition or Options |
|----|-----------------|----------|----------|-----------------------|
| 7 | Control Mode | | | |
| | | | | |
| 8 | Control Sensors | INNER | INNER | |
| 9 | AirMgmt Proceed | PROCEED | PROCEED | |
| 10 | Bandwidth | °C | °C | 00.1 to 25.5° C |
| 11 | Primary Cooler | COOLER 1 | COOLER 1 | |
| 12 | Cooler 1 Stroke | | | 03 to 63 |

(ASSY OPS/2JA/FIN) Page 3 of 5 pages

| | Parameter | Event 1 | Event 2 | Definition or Options |
|----|-----------------|-----------|-----------|-----------------------|
| 13 | Cooler 1 State | ON CFF | ON | |
| 14 | Cooler 2 Stroke | | | 03 to 63 |
| 15 | Cooler 2 State | ON OFF | ON OFF | |
| 16 | Heater 1 Duty | % | % | Percent Duty Cycle |
| 17 | Heater 2 Duty | % | % | Percent Duty Cycle |
| 18 | Max Power Draw | W | W | Max Watts |
| 19 | Over Current | A | A | Over Current Ampere |
| 20 | AAA Fan Mode | AUTOMATIC | AUTOMATIC | |

(ASSY OPS/2JA/FIN) Page 4 of 5 pages

| Parameter | | Event 1 | Event 2 | Definition or Options |
|-----------|-------------------------|-----------------------------|--------------------------|-----------------------|
| 21 | AAA Fan State | LOW | LOW | |
| 22 | Heat Rejection | AIR | AIR | |
| Valu | ues for Reconfiguration | on of Setup: Air Management | | |
| 23 | Air Mgmt Mode | AUTOMATIC | AUTOMATIC | |
| 24 | Humidity Config | Pump: 1 2 Valve: 1 2 3 4 | Pump: 1 2 Valve: 1 2 3 4 | |
| 25 | Pressure Config | Pump: 1 2 Valve: 1 2 3 4 | Pump: 1 2 Valve: 1 2 3 4 | |
| 26 | Manual Config | Pump: 1 2 Valve: 1 2 3 4 | Pump: 1 2 Valve: 1 2 3 4 | |

(ASSY OPS/2JA/FIN) Page 5 of 5 pages

| Parameter | | Event 1 | Event 2 | Definition or Options |
|-----------|----------------|-----------|-----------|-------------------------------|
| 27 | Start Humidity | Seconds | Seconds | 00000 to 65535 Seconds |
| 28 | Start Pressure | Seconds | Seconds | 00000 to 65535 Seconds |
| 29 | Circ Fan Mode | AUTOMATIC | AUTOMATIC | |
| 30 | Circ Fan Power | % | % | 000 to 100 % |
| 31 | Data Storage | Seconds | Seconds | 0 to 3600 seconds |
| 32 | Ethernet Addr | ·· | ··· | TCP IP Address |
| 33 | Function Code | Hex Value | Hex Value | 0x000A to 0xFFFE Hex Value |
| 34 | RIC Port | | | 6212 to 6999 |
| 35 | Remote Command | ENABLE | ENABLE | |

Note: These items may need to be entered for multiple events.

TABLE 3 GLACIER DIAGNOSTIC LOG FILE

(ASSY OPS/2JA/FIN) Page 1 of 3 pages

| Parameter | | Definition | Event 1 | Event 2 | Event 3 | Event 4 |
|-----------|-----------------------|---------------------------|---------|---------|---------|---------|
| HO | ME MENU (Front panel) | | | | | |
| 1 | CURR TEMP | Current Temperature °C | Start: | Start: | Start: | Start: |
| | | · | End: | End: | End: | End: |
| | | Cat Daint %C | Start: | Start: | Start: | Start: |
| 2 | SETPOINT | Set Point °C | End: | End: | End: | End: |
| | | | Start: | Start: | Start: | Start: |
| | | | :: | :: | | :: |
| 3 | GPS | Hours: Minutes: Seconds | End: | End: | End: | End: |
| | | | :: | :: | | :: |
| 011 | CK STATUS | | | | | |
| 40 | | Temperature %C | | 1 | | |
| 1 | | | | | | |
| 2 | | | | | | |
| 3 | Cold Head 2A | | | | | |
| 4 | Cold Head 2B | Temperature °C | | | | |
| 5 | Cold Vol Outlet | Temperature °C | | | | |
| 6 | Cold Vol Inlet | Temperature °C | | | | |
| 7 | Cold Vol Inner | Temperature °C | | | | |
| 8 | Cold Vol DeltaP | psi | | | | |
| 9 | Outlet Water | Temperature °C | | | | |
| 10 | Inlet Water | Temperature °C | | | | |
| 11 | Humidity 1 | % Humidity | | | | |
| 12 | Humidity 2 | % Humidity | | | | |
| 13 | Circ Fan Speed | RPM | | | | |
| 14 | Battery | 0 to greater than 9 Volts | | | | |
| 15 | Main Current | 0 to 20 Amps | | | | |
| 16 | Total Run Time | Hours: Minutes: Seconds | | | | |

TABLE 3 GLACIER DIAGNOSTIC LOG FILE

(ASSY OPS/2JA/FIN) Page 2 of 3 pages

| | Parameter | Definition | Event 1 | Event 2 | Event 3 | Event 4 |
|-------------------|-----------------|-------------------------------|---------|---------|---------|----------|
| STATUS: Cryogenic | | | | | | |
| 1 | Cooler 1 Stroke | | | | | |
| 2 | Cooler 2 Stroke | | | | | |
| 3 | HX 1 | Heat Exchanger Temperature °C | | | | |
| 4 | HX 2 | Heat Exchanger Temperature °C | | | | |
| 5 | Cold Head 1A | Temperature °C | | | | |
| 6 | Cold Head 1B | Temperature °C | | | | |
| 7 | Cold Head 2A | Temperature °C | | | | |
| 8 | Cold Head 2B | Temperature °C | | | | |
| 9 | Cold Vol Outlet | Temperature °C | | | | |
| 10 | Cold Vol Inlet | Temperature °C | | | | |
| 11 | Cold Vol Outer | Temperature °C | | | | <u> </u> |
| 12 | Cold Vol Inner | Temperature °C | | | | |
| 13 | Vac Jacket 1 | Torr | | | | |
| 14 | Vac Jacket 2 | Torr | | | | |
| 15 | Heat Sink | Temperature °C | | | | |
| 16 | Col Vol Vac 1 | Torr | | | | |
| 17 | Col Vol Vac 2 | Torr | | | | |
| 18 | Circ Fan Speed | RPM | | | | |
| 19 | Heater 1 Power | % | | | | |
| 20 | Heater 2 Power | % | | | | |
| 21 | Circ Fan Power | % | | | | Í |

TABLE 3 GLACIER DIAGNOSTIC LOG FILE

(ASSY OPS/2JA/FIN) Page 3 of 3 pages

| | Parameter | Definition | Event 1 | Event 2 | Event 3 | Event 4 |
|------|------------------|----------------------------|---------|---------|---------|---------|
| STAT | TUS: Resources | | | | | |
| 1 | AAA Outlet | Temperature °C | | | | |
| 2 | AAA Inlet 1 | Temperature °C | | | | |
| 3 | AAA Inlet 2 | Temperature °C | | | | |
| 4 | Outlet Water | Temperature °C | | | | |
| 5 | Inlet Water | Temperature °C | | | | |
| 6 | Water Flow | kg/h | | | | |
| 7 | Main Current | Amps | | | | |
| 8 | Main Voltage | Volts | | | | |
| STAT | TUS: System | | | | | |
| 1 | CPU | Temperature °C | | | | |
| 2 | Capacitors A | Temperature °C | | | | |
| 3 | Capacitors B | Temperature °C | | | | |
| 4 | Data Logger | Temperature °C | | | | |
| 5 | Battery | Volts | | | | |
| 6 | Total Run Time | Hours: Minutes: Seconds | | | | |
| 7 | Glacier Version | ##.## Day/Month/Year Hour: | | | | |
| | | Minutes | | | | |
| 8 | Logger Version | ##.## Day/Month/Year Hour: | | | | |
| | | Minutes | | | | |
| 9 | Circ Fan Version | ##.## Day/Month/Year Hour: | | | | |
| | | Minutes | | | | |

ICU-ANDE2 DEPLOY

(ASSY OPS/2JA/FIN 1/MULTI P) Page 1 of 3 pages

- 1. <u>DEPLOYING PAD</u> DEPLOY WINDOW OPEN MET = ___/___:___: DEPLOY WINDOW CLOSE MET = ___/___:___: (Set up countdown timer if desired)
- <u>CONFIGURING PHOTO/TV</u> Check complete or in work prior to deploy window open: Perform P/TV10 DEPLOYABLE PAYLOADS – DRAGONSAT, ANDE2 (PHOTO/TV, SCENES)

-25:00

R1

SSP1

3. ANDE2 INITIAL CONFIGURATION

- $\sqrt{PL AFT MN B} ON$ $\sqrt{ANDE2 PWR} - OFF$ $\sqrt{PRE-ARM/SAFE} - SAFE (tb-bp)$ $\sqrt{ARM/SAFE} - SAFE (tb-bp)$ $\sqrt{DEPLOY/SAFE} - SAFE (ctr)$ $\sqrt{NEA GOOD tb} - bp$
- 4. VERIFYING DEPLOY PATH CLEAR $\sqrt{OBSS/MPM}$ clear of deploy path \sqrt{RMS} clear of deploy path
 - * √MCC if ANDE2 deploy path not clear *

-06:00

5. START RECORDERS

- L10 (VTR) REC pb push, hold PLAY – push simo RED DOT displayed
- V10's
- (MON 1,2) REC pb's push $\sqrt{\text{RED DOT displayed}}$
- FD G1

-05:00

- 6. <u>CONFIGURE FOR DEPLOY</u> O14:F, $\sqrt{\text{Pri RJD LOGIC,DRIVER (sixteen)} - \text{ON}}$ O15:F, O16:F, O14:E, $\sqrt{\text{cb DDU (six)} - \text{cl}}$
- O15:E, O16:E

GNC 20 DAP CONFIG

√DAP: A1/B1 loaded

If VERN available: √DAP: A/AUTO/VERN ITEM 44 + <u>0.5</u> EXEC

ICU-ANDE2 DEPLOY

(ASSY OPS/2JA/FIN 1/MULTI P) Page 2 of 3 pages

If using ALT: √DAP: A/AUTO/ALT ITEM 31 + <u>1.0</u> EXEC ITEM 38 + <u>0.1 0</u> EXEC ITEM 40 + <u>1</u> EXEC

GNC 201 UNIV PTG

 \sqrt{In} Attitude per flight plan

DAP: B/AUTO/VERN(ALT) √Vehicle Rates

| | VERN | ALT |
|--------------------------|----------|----------|
| Pitch Rate (deg/sec) | ≤ Rate ≤ | ≤ Rate ≤ |
| Roll, Yaw Rate (deg/sec) | ≤ | ≤ |

 \sqrt{MCC} if deadband collapse complete or wait 60 sec

7. <u>DEPLOY PREP</u>

-02:00 A6U SSP1

-00:00

DAP: FREE

| ANDE2 | PWR – | ON |
|-------|-------|----|
| | | |

| | <u>CAUTION</u> To prevent solenoid overheating, the ANDE2 PRE-ARM/SAFE switch is limited to 120 sec in the PRE-ARM position. The ANDE2 PRE-ARM/SAFE switch must be in the SAFE pos for at least 120 sec before returning to the PRE-ARM position | | | |
|------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------------|--|--|
| 8 SSP1 | 3. <u>DEPLOY/SAFE</u> ANDE2 PRE-ARM/SAFE – PRE-ARM (tb- √D/S NEA GOOD tb – gray | gray) | | |
| R1 SSP1 | If PRE-ARM tb or NEA GOOD tb not gra continue deploy. If both tb not gray ANDE2 PRE-ARM/SAFE – SAFE PWR – OFF √PL AFT MN B – ON √MCC if available; if not ANDE2 PWR – ON Repeat step 8 | ay, * * * * * * * * | | |
| | ANDE2 ARM/SAFE – ARM (tb-gray) | | | |
| | If ARM tb not gray, continue deploy DEPLOY/SAFE – DEPLOY | * | | |

-00:00

ICU-ANDE2 DEPLOY

When deployment visually verified or after 5 sec: DEPLOY/SAFE – SAFE (ctr) Record deploy time: MET _____ :___:___:

SSP1

- * If ANDE2 not deployed:
- Record ANDE2 D/S NEA GOOD tb status: *
- ANDE2 PRE-ARM/SAFE SAFE (tb-bp) ARM/SAFE SAFE (tb-bp) *

*

*

- * Record D/S NEA GOOD tb status: *
- *
- Report D/S NEA GOOD tb statuses to MCC

| ANDE2 PRE-ARM/SAFE | – SAFE (tb-bp) |
|--------------------|------------------------------------|
| ARM/SAFE | - SAFE (tb-bp) |
| PWR | – OFF |

Notify MCC of Deploy MET Visually track and videotape ICU/ANDE2 for up to 4 min or until out of sight

- +02:00 A6U DAP: A/LVLH
 - 9. POWERDOWN

| O14:E, | cb DDU (six) – op |
|--------|-------------------|
| O15:E, | |
| O16:E, | |

O14:F, Pri RJD LOGIC, DRIVER (sixteen) - OFF O15:F, RJDA 1A L2/R2 MANF DRIVER - ON O16:F

> 10. DAP CLEANUP GNC 20 DAP CONFIG

> > ITEM 2 + <u>1</u> EXEC

A6U DAP: as regd

DRAGONSAT DEPLOY

(ASSY OPS/2JA/FIN 1/MULTI P) Page 1 of 3 pages

- 1. DEPLOY PAD DEPLOY WINDOW OPEN MET = DEPLOY WINDOW CLOSE MET = (Set up countdown timer if desired)
- 2. CONFIGURATION FOR PHOTO/TV Check complete or in work prior to deploy window open: Perform P/TV10 DEPLOYABLE PAYLOADS – DRAGONSAT, ANDE2 (PHOTO/TV, SCENES), then:
- -25:00

3. DRAGONSAT INITIAL CONFIGURATION

| R1 | √PL CAB | – MNA(MNB) |
|------|--------------------------|---------------|
| | √AFT MN B | – ON |
| SSP1 | \sqrt{cb} SW PWR 2 | – ор |
| | √D/S PRE-ARM | - SAFE (down) |
| | √PICO 2 HERE tb | – bp |
| | $\sqrt{D/S}$ NEA GOOD tb | – bp |
| | VARM | - SAFE (down) |

SAFE (down) VARIVI **√DEPLOY** - SAFE (ctr)

NOTE

SSP2 PDIP 2 PWR1 cb provides power to SSP1 D/S DEPLOY sw. This cb is expected to be in the cl position prior to DRAGONSAT deploy as it supplies power to the PDIP 2 pnl, which may be in use by a PGSC or other item

- SSP2 \sqrt{cb} PDIP 2 PWR 1 – cl
 - 4. VERIFY DEPLOY PATH CLEAR

 \sqrt{OBSS} clear of deploy path \sqrt{RMS} clear of deploy path

* √MCC If DRAGONSAT deploy path not clear *

| -06:00 | 5. | START RECORDERS | | |
|--------|-------------------------------------------|----------------------------------------|-------------------------------------------|--|
| | L10 (VTR) | REC pb | – press, hold | |
| | V/40'- | PLAY | – press simo | |
| | (MON 1,2) | REC pb's | – press | |
| | FD G1 (PAO) | START/STOP p | b – press | |
| -05:00 | 6. 014:F | <u>CONFIGURE F(</u> √Pri RJD LOGIC, | <u>DR DEPLOY</u> DRIVER (sixteen) – ON | |
| | 015:F 016:F 014:E 015:E 016:F | √cb DDU (six) – c | Ι | |

Page 2 of 3 pages

GNC 20 DAP CONFIG

√DAP: A1/B1 loaded

If VERN available: √DAP: A/VERN ITEM 44 + <u>0.5</u> EXEC

If using ALT: √DAP: A/ALT ITEM 31 + <u>1.0</u> EXEC ITEM 38 + <u>0.1 0</u> EXEC ITEM 40 + <u>1</u> EXEC

GNC 201 UNIV PTG

 \sqrt{In} Attitude per flight plan

DAP: B/VERN (ALT)

√Vehicle Rates

| | VERN | ALT |
|--------------------------|----------|----------|
| Pitch Rate (deg/sec) | ≤ Rate ≤ | ≤ Rate ≤ |
| Roll, Yaw Rate (deg/sec) | \leq | \leq |

 \sqrt{MCC} if deadband collapse complete or wait 60 sec

- 7. DEPLOY PREP
- -02:00 A6U DAP: FREE

SSP1 cb SW PWR 2 – cl

<u>CAUTION</u>

To prevent solenoid overheating, the D/S PRE-ARM switch is limited to 120 sec in the PRE-ARM position. The D/S PRE-ARM switch must be in the SAFE position for at least 120 sec before returning to the PRE-ARM position

<u>NOTE</u>

Two tbs, PICO 2 HERE and D/S NEA GOOD, will transition from bp to gray when the D/S PRE-ARM switch is thrown

8. <u>DEPLOY/SAFE</u>

-00:30 SSP1

 $\sqrt{PICO 2 HERE tb} - gray$ $\sqrt{D/S NEA GOOD tb} - gray$ DRAGONSAT DEPLOY (ASSY OPS/2JA/FIN 1/MULTI P

|)) | Page | 3 | of 3 | 3 | pages | |
|------------|-------|---|------|---|-------|--|
| / | - 0 - | - | - | - | | |

| | * If at least one tb gray, continue deploy * * If all tbs are bp: * D/S PRE-ARM – SAFE * Do not deploy * √MCC for instructions |
|------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| | D/S ARM – ARM |
| -00:00 | D/S DEPLOY – DEPLOY |
| | When deployment visually verified, or after 5 sec: D/S DEPLOY – SAFE Record deploy time: MET/:: |
| | $\sqrt{PICO 2 HERE tb}$ – bp $\sqrt{D/S NEA GOOD tb}$ – bp |
| | * If DRAGONSAT not deployed: * Record D/S NEA GOOD tb status: * D/S ARM - SAFE * PRE-ARM - SAFE * √D/S PICO 2 HERE tb - bp * Record D/S NEA GOOD tb status: * Report D/S NEA GOOD tb statuses to MCC |
| | D/S PRE-ARM – SAFE ARM – SAFE cb SW PWR 2 – op |
| | Notify MCC that deploy and switch reconfig is complete; report MET of deploy. |
| | <u>VISUAL TRACKING</u> Visually track DRAGONSAT for up to 4 min or until out of view |
| +02:00 A6U | DAP: A/AUTO/VERN (ALT) |
| | 10. DAP CLEANUP |

GNC 020 DAP CONFIG

ITEM 2 + <u>1</u> EXEC

CONTINGENCY EVA PL CONFIG

PRE-EVA PL CONFIGURATION

(ASSY OPS/2JA/FIN) Page 1 of 1 pages

N/A

POST EVA PL CONFIGURATION

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N/A

MALFUNCTION

20 MAY 09

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4850201_127.SCH:1










26 MAR 09







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PL/DPS RECONFIGURATION

| SS | Y OPS/2JA/FIN) Page 1 of 2 pages | | | |
|----|----------------------------------------------------------------------------------------|------------------|--------------------|------|
| | PROCEDURE | SECURE ACTION | RECOVERY ACTION | INFO |
| | PL 1(2) MDM I/O ERROR; PL 1(2) MDM OUTPUT (ORB PKT, <u>DPS</u>) | N/A | N/A | А |
| | 5.3c I/O ERROR PL 1(2); MDM OUTPUT PL 1(2) (MAL, <u>DPS</u>) | N/A* | N/A | A |
| | PASS SM GPC FAIL (ORB PKT, <u>DPS</u>) | N/A | D | В |
| | GNC RECOVERY VIA G2FD (ORB PKT, DPS) | N/A | C,D | В |
| | 5.1a CS SPLIT(MAL, <u>DPS</u>) | N/A | C,D,E** | В |
| | 5.3g BCE BYP PL1(2) (MAL, <u>DPS</u>) | N/A* | N/A | А |
| | GPC FRP-4 PASS RECOVERY AFTER BFS ENGAGE (ASCENT/ORBIT/ENTRY) (MAL, <u>DPS</u>) | N/A* | C,D | В |
| | GPC FRP-7 DPS RECONFIG FOR LOSS OF AV BAY COOLING (MAL, <u>DPS</u>) | N/A* | C,D | В |
| | DPS SSR-3 GNC REASSIGNMENT (MAL, <u>DPS</u>) | N/A* | N/A | В |
| | DPS SSR-4 SM REASSIGNMENT (MAL, <u>DPS</u>) | N/A | C,D | В |
| | ECLSS SSR-10 H2O PUMP OPS VIA GPC | N/A | C,D,E** | В |

(AS

*NOTE: Procedure does not call out PL/DPS RECONFIG, Secure

**NOTE: Procedure does not call out PL/DPS RECONFIG, Recovery

ACTION A

(MAL, <u>ECLSS</u>)

If 'I/O ERROR PL1' message:

Loss of ground and orbiter MCDS command interface to ISS via PSP 1/OIU 1 For additional impacts, refer to ORBITER MDM LOSS IMPACTS (SODF: ASSY OPS: MALFUNCTION: CRITICAL EQUIPMENT LOSS)

If failure at IOP XMTR/RCVR at SM GPC:

If PL2 interface with SM GPC failed:

√MCC for SM GPC reassignment

PF1 interface can be recovered by port moding PL 1/2 buses

If 'I/O ERROR PL2' message:

Loss of ground and orbiter MCDS command interface to ISS via PSP 2/OIU 2 For additional impacts, refer to ORBITER MDM LOSS IMPACTS (SODF: ASSY OPS: MALFUNCTION: CRITICAL EQUIPMENT LOSS) If failure at IOP XMTR/RCVR at SM GPC:

If PL1 interface with SM GPC failed:

√MCC for SM GPC reassignment

PF2 interface can be recovered by port moding PL 1/2 buses

ACTION B

If SM GPC affected:

Note PL/ISS commanding via SM GPC (ground and orbiter MCDS) not possible until SM machine is restored and PL 1(2) MDM I/F is restored

If GNC GPC affected:

Ground commanding not possible until GNC machine is restored

PL/DPS RECONFIGURATION

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ACTION C

If PSP I/O reset not previously performed SM 62 PCMMU/PL COMM I/O RESET PSP 1(2) – ITEM 6(7) EXEC

Notify MCC when complete

ACTION D

Reload PDI DECOM FORMAT (ORB OPS FS, <u>COMM/INST</u>) As required, reenable PDI DECOM FDA Resume SPEC 62

ACTION E

Reload PCMMU TFLs, load PCMMU FORMAT (ORB OPS, COMM/INST)

ORBITER ELECTRICAL BUS LOSS MATRIX

(ASSY OPS/2JA/FIN 1)

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| ORBITER EPS BUSES | F | C1 | | FC2 | | FC3 | | | | | | MNA | A DA1 | | | | | | | | | | MNB DA2 FC3 | | | | | | | | MNC | MNC DA3 | | | | | |
|-----------------------------------------------------------------|-------------------------------|------------------------------|-----------------|------------|--------------|--------------|--------------|--------------|-----------|-----------|------------|---------|--------------|--------|--------|-----------|------|----------|-----|-----------|------|--------|-------------|------|----------|------|------|---------|-----------|-------------|-----|---------|----|---------|---------------|---------|----------------|
| | ESS | 1BC | | ESS 2C | A | ESS | | | | | | | | | FPC1 | ſ | MPC1 | | MPC | C2 | | | APC5 | I | FPC2 | | | | | | (1 | R) (R) | Р | | APC 6 | FPC3 | |
| | PNL 0128 | ESS | | ESS | PNL | 3AB | CNTL C | CNTL C | NTL F | PNL R14 | PNL O14 | МС | A1 MCA3 | PNL | | 1 — | | D (D | | | MCA3 | PNL | APC2 | | AC2 | CNTL | CNTL | PNL 015 | 5 PNL R14 | MAR1 MA | R2 | , , , | | PNL O16 | PNL R14 APC 3 | AC3 | CNTL CNTL CNTL |
| | R14 11 | BC FD | 20 | CA FD | R14 | PNL O13 | BCT | D02 L | 505 | | | | | AUGAIH | AC1 3ø | A | UX — | CAB | - A | UX PLB | | 700714 | AFT PLE | В 3ф | фА | | CAZ | | | WILCOD WILC | 300 | PRI F | L | | AFT PLC | PNL A15 | |
| ORBITER EQUIPMENT | | | | | | | | | | | | | | | | | PI | L1 PL2 F | PL3 | | | | / | υψ | ψ | | | | | | | | | | | φC | |
| PTU1 APCU1 Conv / Output (JEE) | XRC | | | | | | | | | | | ¥ | | | | | | | | | | | | | - | | | XRC | | | | | | | | | XC |
| OPCU1 | | | | | | | | | | | | X | | | | | | | | | | | | | | | | | | | | | | | | | XC |
| PTU2 APCU2 Conv / Output (LCS) | | | | | XRC | | | | | | | | | | | | | | | | x | | | | | XC | | | | | | | | XRC | | | |
| OPCU2 | | | | | | | | | | | | | | | | | | | | | Х | | | | | XC | | | | | | | | | | | |
| PRLA PL Sel 1/2/3 | | | | | | | R | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | R |
| Sys 1 Relays Mech Pwr Ena 1 | | | | | | | | | | | | > | < | | x | | | | | | | | | | | YRC | | | | | | | | | | | XC |
| Mech Pwr Ena 2 | | | | | | | | | | | | | | | X | | | | | | | | | | | XIXO | XRC | | | | | | | | | | XRC |
| Logic Pwr Svs 2 Relavs | | | | | | | | | хс | | | | x | Х | | | | + | | | x | | | | - | | | | - | | | _ | | | | | XC |
| Mech Pwr Ena 1 / 2 | | | | | | | XC | XC | | | | | | | | | | | | | | ~ | | Х | | | | | | | | | | | | | |
| Logic Pwr ROEU Latch / Mate / Relax (JLE) | | | | | | | | | | | | > | < | | | | | | | | x | X | | _ | | | | | | | | _ | | | | | |
| OIU1 | | | | | | | | | | | | | | | | | | | Х | ~ | | | | | | | | | - | | | | | | | | |
| ODS X1 Connector Mate TIm/Pwr | | | | | | | | | | | | | | | | | | | | ^ | | | | | | R | R | | | | | | | | | | K K |
| ODS X2 Connector Mate TIm/Pwr | | | | | | | | | | | | _ | | | | | | | | × | | | | | | | | | | | | | | | | | |
| Primary C/L Camera | | | | | | | | | | | | | | | | | | | X | ~ | | | | | | | | | | | | | | | | | |
| Secondary C/L Camera PDIP 1 (Ku-Band relay / PCS-to-OIU I/F) | | | | | | | | | | | | | | | | | , | x x | | | | | | | - | | | | - | | | _ | | | | | |
| PDIP 2 (TCS / SSV) | | | | | | | | | | | | | | | | | | Х | | | | | | | | | | | | | | | | | | | |
| Video Processing Unit (VPU) Payload Timing Buffer | | | | | | | | | | | | | | | | | | + | х | | | | | | | | | | X | | | | | | | | |
| Orbiter PCS | | | | | | | | | | | | | | | | | | X | | | | | | | | | | | | | | | | | | | |
| CARGO EQUIPMENT | | | | | | | | | | | | | | | | | | ^ | | | | | | | | | | | | | | | | | | | |
| DRAGONEYE PPSU1 (JLE) | | | | | | | | | | | | _ | | | | + | X | C | | | | | | _ | | | | | | | | _ | x | | X | | |
| HTR 1-2 Ena | | | | | | | | | | | | | | | | | | | XC | | | | | | | | | | | | | | | | | | |
| ICS-EF HTR #2 | | | | | | | | | | | | | | | | | | | XC | | | | | | | | | | | | | | X | | | | |
| HTR 3-4 Ena | | | | | | | | | | | | | | | | | X | C | | | | | | | | | | | - | | | | | | | | |
| SEDA-AP HTR #3 MAXI HTR #4 | | | | | | | | | | | | _ | | | | | X | C | | | | | | | | | | | - | | | | x | | | | |
| PPSU2 (ICC-VLD) | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | X | | | | |
| PFRAM HTR | | | | | | | | | | | | | | | | | X | .0 | хс | | | | | | | | | | | | | | X | | | | |
| PPSU 1/2 HTR A Ena | | | | | | | | | | | | | | | | | × | с I | XC | | | | | | | | | | | | | | | | | | |
| KEEL CAM1 (ICC) | | | | | | | | | | | | | | | | | ^ | .0 | | | | | | | | | | | | | | | | | | | |
| Heater Power Illuminator Power | | | | | | | | | | | | | | | | | | x | | | | | | | - | | | | - | | | _ | | | | | |
| KEEL CAM2 (JLE) | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Heater Power Illuminator Power | | | | | | | | | | | | | | | | | | X | | | | | | | | | | | | | | | | | | | |
| | | | | | | | | | | | | | | | | | | | | | | | X | | | | | | | | | | | | | | |
| DRAGONSAT (Heaters) | | | | | | | | | | | | | | | | | | | | | | | X | | | | | | | | | | | | | | |
| DEPLOY PRE-ARM / ARM | $\left - \right ^{-}$ | | + + - | |] | | | | | | | | | | | + $+$ $-$ | | XC | хс | | | | | | <u> </u> | + | | | | + | | | ┢┤ | | | | |
| Glacier (descent) | | | | | | | | | | | | | | | | | | | | | | | | | 1 | | | | | Х | | | | | | | |
| PCDF-PU (descent) | (1) The heate | er circuit has | been isol | lated from | n orbiter bu | us power by | / de-pinning | the assoc | iated co | onnector. | | | | 1 | 1 | | | | | | | | | | 1 | 1 | 1 | 1 | 1 | | (| | | | | | |
| | (2) Redunda | nt LCS pwr is | available | e from AF | PCU1 throu | ugh the inte | erconnect ca | able (the po | ower stil | I must go | through AP | CU2's d | output relay | l. | | | | | | | | | | | | | | | | | | | | | | | |
| | XR - Loss of | Redundant F | Power | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | XC - Total Lo XRC - Loss o | ss or Contro of Redundant | Control | Power | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | XRM - Loss (P - Primary F | of Redundant Power Source | t tb Monit e | tor Power | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | (R) - Redund | ant Power Se | ource (re | quires cre | ew action t | o use) | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |

ORBITER ELECTRICAL BUS LOSS MATRIX

(ASSY OPS/2JA/FIN 1)

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| ORBITER EPS BUSES | FC1 | | FC2 | | FC3 | | | | MNA DA1 | | | | | | | | | | | N | INB DA2 | | | | | | FC3 | | | MNC DA3 | | |
|-----------------------------------------------|------------|---|--------|-----|--------------------|------|------|-----------------|---------|-----|--------|-----|------------------|---------------|------------|---|------|-----|--------------|---------|-----------|------|---------------------|---------|--------|-----|--------|--------|-----------|---------------|----|------|
| | PNL ESS | | ESS 20 | PNL | ESS 3AB CNTI | CNTL | CNTL | PNL R14 PNL O14 | MCA1 M | CA3 | PNL | | MPC1 | (P) | MPC2 | | MCA3 | PNL | APC5 APC2 | FF A | PC2 C2 | CNTL | CNTL CA2 PNL 015 | PNL R14 | MAR2 | (R) | (R) P | -PNL O | 16 PNL R1 | APC 6 FPC3 | | ITL |
| | R14 1BC FD | | 2CA FD | R14 | PNL O13 | 002 | DOJ | | | r | AC1 36 | | AUX (PLA PL1 | CAB PL2 PL | AUX PLB | | | | AFT PLB | 3ф | φA | UA1 | UNZ | WEOOD | WILCOD | F | PRI PL | | | AFT PLC PNL A | 15 | |
| ISS EQUIPMENT | | | | | | | | | | | | | | | | | | | | | | 1 | | | | | 1 | | | | | |
| PMA 2 Hooks - Group 1, 2 - Sys A | XRC | | | | | | | | | | Х | Х | | | | | | | | | | | XRC | | | | | | | | | |
| PMA 2 Hooks - Group 1, 2 - Sys B | | | | XRC | | | | | | | | | | | Х | | | Х | | | | | | | | | | XRC | | | | _ |
| OBSS | | - | 1 | | | - | 1 | | | - 1 | | 1 1 | | - | | - | | | 1 1 | | | 1 1 | | 1 | - | | | 4 | - | | | |
| LCS (+124 VDC via APCU 2) ² | | | | | | | | | | | | | | | | Х | | | | | | | | | | | | | | | | |
| LDRI / ITVC / PTU / SPEE (on SRMS) | | | | | | | | | | | | Х | | X | | | | | | | | | | | | | | | | | | |
| LDRI / ITVC / PTU / SPEE / LCS Htrs (in MPMs) | | | | | | | | | | | | XR | | | XF | २ | | | | | | | | | | | | | | | | |
| RSC Cam | | | | | | | | | | | | | | Х | | | | | | | | | | | | | | | | | | |
| DTV MUX / VTR | | | | | | | | | | | | Х | | | | | | | | | | | | | | | | | | | | |
| PAYLOAD BUS CONTROL POWER | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Cabin PL - MNA Cntl Pwr (nom src) | XC | | | | | | | | | | | | | | | | | | | | | | | | T T | | | | | | | _ |
| Cabin PL - MNB Cntl Pwr (b/u src) | | | XC | | | | | | | | | | | | | | | | | | | | | | | | | 1 | | | | |
| Aux PLA Cntl Pwr | XC | | | | | | | | | | | | | | | | | | | | | | | | | | | 1 | | | | |
| Aux PLB Cntl Pwr | | | XC | | | | | | | | | | | | | | | | | | | | | | | | | 1 | | | | |
| PL PRI - MNC DA3 Cntl Pwr (nom src) | | | | | XRC | | | XRC | | | | | | | | | | | | | | | | | | | | 1 | | | | |
| PL PRI - MNB DA2 Cntl Pwr (b/u src) | | | | XRC | | | | | | | | | | | | | | | | | | | | | | | | XRC | | | | - |
| PL PRI - FC3 Cntl Pwr (b/u src) | | | | | XRC | | | XRC | | | | | - 1 1 | | | | | | | | | | | | | | | 1 | | 1 | | |
| AFT PLB Cntl Pwr | | | | XRC | | | | | | | | | | | | | | | | | | | | | | | | XRC | | | | |
| AFT PLC Cntl Pwr | | | | | XRC | | | XRC | | | | | | | | | | | | | | | | | | | | | | | | |

 (1) The heater circuit has been isolated from orbiter bus power by de-pinning the associated connector.
 (2) Redundant LCS pwr is available from APCU1 through the interconnect cable (the power still must go through APCU2's output relay).

 X - Total Loss of Operational Power
 XR - Loss of Redundant Power

 XC - Total Loss of Control Power
 XRC - Loss of Redundant to Monitor Power

 XRC - Loss of Redundant to Monitor Power
 Primary Power Source

 (R) - Redundant Power Source
 (R) - Redundant Power Source

ORBITER MDM LOSS IMPACTS

(ASSY OPS/2JA/FIN 1) Page 1 of 3 pages

- FF1 Uplink through NSP 1 (secondary)
- FF3 Uplink through NSP 2 (primary) FRCS Vernier RJD command path (loss of verns)
- FA1 LRCS Vernier RJD command path (loss of verns)
- FA2 RRCS Vernier RJD command path (loss of verns)
- PF1 ISS Primary command path (via PSP 1 UMB 1/OIU 1) OIU 1 tlm (PDI TELEMETRY 1) Ku-Band command and tlm JEM-EF (JEF) LAT 4 RFL tlm (Sys 1) 3 RFL tlm (Sys 1) ELM-ES (JLE) LAT 4 RFL tlm (Sys 1)
 - 3 RFL tlm (Sys 1)
- PF2 ISS Redundant command path (via PSP 2 UMB 1/OIU 2) OIU 2 tlm (PDI TELEMETRY 2) CCTV Command Path from MCC (crew still has control from PNL A7) C/W Annunciation (PL Caution, B/U C/W Alarm) JEM-EF (JEF) LAT 1 RFL tlm (Sys 2) 2 RFL tlm (Sys 2) ELM-ES (JLE) LAT 1 RFL tlm (Sys 2)
 - 2 RFL tlm (Sys 2)
- OF1 PCMMU 1 – mode select tlm 1,2 – ON/OFF power tlm – RPC A tlm PL AUX A - RPC ON/OFF tlm MID MCA 1 OP STATUS 1, 2, 3, 4 tlm 3 OP STATUS 1, 2, 3, 4 tlm PL BAY MECH PWR SYS 1. 2 tlm RETEN LOGIC PWR SYS 1, 2 tlm ROEU MATE/DEMATE tlm (Sys 2) LAT, REL tlm (Sys 2) ELM-ES (JLE) KEEL RFL, LAT, REL, tlm (Sys 2) ICC-VLD LAT 1 RFL, LAT, REL tlm (Svs 2) 2 RFL, LAT, REL tlm (Sys 2) 3 RFL, LAT, REL tlm (Sys 2) 4 RFL, LAT, REL tlm (Sys 2) KEEL RFL, LAT, REL tlm (Sys 2)
- OF2 PSP 1,2 bit and frame sync PCMMU 2 – mode select tim PCMMU 2 RPC B tim PL AUX B – RPC ON/OFF tim MID MCA 1 OP STATUS 5, 6 tim 3 OP STATUS 5, 6, 7, 8 tim

ORBITER MDM LOSS IMPACTS

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JEM-EF (JEF) LAT 4 RFL, LAT, REL tlm (Sys 2) 1 LAT, REL tlm (Sys 2) 3 RFL, LAT, REL tlm (Sys 2) 2 LAT, REL tlm (Sys 2) KEEL RFL, LAT, REL tlm (Sys 2) ELM-ES (JLE) LAT 4 RFL, LAT, REL tlm (Sys 2) 1 LAT, REL tlm (Sys 2) 3 RFL, LAT, REL tlm (Sys 2) 2 LAT, REL tlm (Sys 2) ROEU RELAX tlm (Sys 2) ELM-ES (JLE) KEEL RFL, LAT, REL, tlm (Sys 1) ICC-VLD LAT 1 RFL, LAT, REL tlm (Sys 1) 2 RFL, LAT, REL tlm (Sys 1) 3 RFL, LAT, REL tlm (Sys 1) 4 RFL, LAT, REL tlm (Sys 1) KEEL RFL, LAT, REL tlm (Sys 1) DSC OF2 FRCS Vernier Inj Temps (loss of verns) OF3 Orbiter Comm system tlm (refer to OI MDM/DSC Failure Impacts) PL PRI MNC, MNB, FC3 – ON/OFF tlm PCMMU 1 RPC B tlm OF4 Ku-Band – RADAR mode and output power S-Band, Ku-Band – PNL/CMD switch position PSP, GCIL – ON/OFF tlm Orbiter Comm system tlm (refer to OI MDM/DSC Failure Impacts) CAB PL (MNA, MNB), PL AUX - ON/OFF tlm APCU 1 and 2 Converters/Outputs switch position tlm PTU1 and 2 OPCU Converter switch position tlm ROEU MATE/DEMATE tlm (Sys 1) LAT, REL tlm (Sys 1) OA1 ODS X4/PMA X3 connector mate tlm PMA 2/3 GRP 1 passive hooks (1,3,5,7,9,11), Close tlm PTU 1/APCU 1 voltage/trip status/temperature tlm ODS X1 Connector mate A/B tlm DSC OA1 ODS X4/PMA X3 connector mate tlm PMA 2/3 GRP 1 passive hooks (1,3,5,7,9,11), Close tlm OA2 AFT PL MNB PWR ON tlm amps ODS X3/PMA X4 connector mate tlm PMA 2/3 GRP 2 passive hooks (2,4,6,8,10,12), Close tlm PTU 2/APCU 2 voltage/trip status/temperature tlm ODS X2 Connector mate A/B tlm DSC OA2 ODS X3/PMA X4 connector mate tlm PMA 2/3 GRP 2 passive hooks (2,4,6,8,10,12), Close tlm Vernier R5D Inj Temps (loss of verns)

ORBITER MDM LOSS IMPACTS

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- OA3 AFT PL MNC PWR ON tim amps JEM-EF (JEF) LAT 1 RFL, LAT, REL tim (Sys 1) 4 LAT, REL tim (Sys 1) 2 RFL, LAT, REL tim (Sys 1) 3 LAT, REL tim (Sys 1) KEEL RFL, LAT, REL tim (Sys 1) ELM-ES (JLE) LAT 1 RFL, LAT, REL tim (Sys 1) 4 LAT, REL tim (Sys 1) 2 RFL, LAT, REL tim (Sys 1) 3 LAT, REL tim (Sys 1) ROEU RELAX tim (Sys 1)
- DSC OL1 LRCS Vernier Inj Temps (loss of verns)
- DSC OR1 RRCS Vernier Inj Temps (loss of verns)

DEORBIT PREP

PAYLOAD DEACTIVATION

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L12U 1. cb SW PWR 1 – op (SSP1) PDIP 1 PWR 2/KuBAND RLY – op PDIP 1 PWR 1 – op

| L12L (SSP2) | 2. KE Pl ct | EEL 1 ILL PWR (ICC) 2 ILL PWR (JLE) PSU 1/2 HTR B 0 CB2 PDIP 2 PWR 2 | – OFF – OFF – DSBL – op – op |
|----------------|-------------------|----------------------------------------------------------------------------------|------------------------------------------|
| | PI ct | PSU 1/2 HTR A 0 CB4 PDIP 2 PWR 1 | – DSBL – op – op |
| L12 (PDIP1) | 3. Kı) | BAND RATE | – OFF |
| 54 | | 0.45 | 0.55 |

R1 4. PL CAB – OFF AFT MNC – OFF

PAYLOAD REACTIVATION

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- R1 1. PL CAB MNA AFT MNC – ON
- L12L 2. cb CB2 cl (SSP2) PDIP 2 PWR 2 - cl KEEL 1 ILL PWR (ICC) - ON 2 ILL PWR (JLE) - ON PPSU 1/2 HTR B - ENA cb CB4 - cl
 - PPSU 1/2 HTR A ENA

PAYLOAD ENTRY SWITCH LIST/VERIFICATION

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TIG-1:55

| L12U (SSP1) | √cb SW PWR 1 √cb PDIP 1 PWR 2/KuBA √ANDE2 PWR √PRE-ARM/SAFE √ARM/SAFE √DEPLOY/SAFE √NEA GOOD tb √cb SW PWR 2 √PDIP 1 PWR 1 √D/S ARM √PICO 2 HERE tb √OIU PWR √TCS PWR √TCS PWR √D/S DEPLOY √PRE-ARM √D/S NEA GOOD tb √PICO 1 HERE tb | ND RLY | - op - op - OFF - SAFE (tb-bp) - SAFE (tb-bp) - SAFE - bp - op - op - op - SAFE - bp - OFF (tb-bp) - (ctr) - SAFE - bp - oFF (tb-bp) - oFF (tb-bp) |
|--------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| L12L (SSP2) | 8. $\sqrt{\text{KEEL 1 PWR (ICC)}}$ $\sqrt{\text{ILL PWR (ICC)}}$ $\sqrt{\text{KEEL 2 PWR (JLE)}}$ $\sqrt{\text{ILL PWR (JLE)}}$ 9. $\sqrt{\text{cb CB2}}$ $\sqrt{\text{PDIP 2 PWR 2}}$ 10. $\sqrt{\text{DRGNEYE PWR}}$ 11. $\sqrt{\text{C/L CAM PWR}}$ 12. $\sqrt{\text{cb CB4}}$ 13. $\sqrt{\text{PDIP 2 PWR 1}}$ 14. $\sqrt{\text{PPSU 1/2 HTR B}}$ $\sqrt{\text{ICC BATT HTRS}}$ $\sqrt{\text{JLE SEDA-AP HTR #3}}$ $\sqrt{\text{MAXI HTR #4}}$ $\sqrt{\text{JLE HTR 1-2}}$ $\sqrt{3-4}$ $\sqrt{#1}}$ $\sqrt{\text{ICS-EF HTR #2}}$ $\sqrt{\text{ICC PFRAM HTRS}}$ $\sqrt{\text{PPSU 1/2 HTR A}}$ | OFF OFF OFF OF OP OP OFF (tb-t) OFF OP OF OF Ctr) (tb-b) OFF (tb-t) (Ctr) (tb-b) (Ctr) (tb-b) OFF (tb-t) | p) p) p) p) p) p) p) p) p) p) |
| L12 (PDIP1) | 15. \sqrt{Ku} BAND RATE – OFF \sqrt{DC} POWER 1 – OFF $\sqrt{2}$ – OFF | | |
| L11 (PDIP2) | 16. √DC POWER 1 – OFF √2 – OFF | | |
| MF28E/G (GLACIE | i17.√cb POWER – cl (lt on) R) √BATTERY – ON (lt on) | | |
| MA16F (PCDF-F | 18. √sw POWER – ON PU)√POWER ON It – on | | |

REFERENCE

STANDARD SWITCH PANEL 1 LAYOUT

(ASSY OPS/2JA/FIN)

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STANDARD SWITCH PANEL 1 LAYOUT(ASSY OPS/2JA/FIN)Page 2 of 4 pages

| | Device Type | Function |
|---------------------------|----------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------|
| CB1 | Circuit breaker, 5 amp | closed (in) – Applies orbiter CAB PL2 power to the Keel Camera, PDIP DC PWR 2 switch outlet, and |
| PDIP 1 PWR2/ | | open (out) – Removes power from PDIP DC PWR 2 |
| | | outlet and KuBAND RATE switch. |
| | Circuit breaker, 5 amp | closed (in) – Applies orbiter CAB PL1 power to SSP1 S3 and S4, and SSP2 S12. |
| SW F WIX 1 | | open (out) – Removes power from SSP1 S3 and S4, and SSP2 S12. |
| S8 | Two-position toggle switch: | ON (up) – Closes ANDE 2 PWR relay. |
| ANDE2 PWR | Maintained – Maintained | OFF (dn) – Opens ANDE 2 PWR relay. |
| S10 | Two-position toggle switch: | PRE-ARM (up) – Closes PRE-ARM relay in ANDE 2 deploy circuit (enables ground path for high current mode to allow NEA fuse wire ablation). |
| ANDE2 PRE-ARM/ SAFE | Maintained – Maintained | SAFE (dn) – Opens PRE-ARM relay in ANDE 2 deploy circuit. |
| DS10 | Talkback, two-position | gray – Indicates PRE-ARM relay is closed. |
| PRE-ARM | gray bp (barberpole) | bp (default) – Indicates PRE-ARM relay is open. |
| S11 | Two-position toggle switch: | ARM (up) – Closes ARM relay in ANDE 2 deploy circuit (enables 2nd ground path for high current mode to allow NEA fuse wire ablation). |
| ANDE2 ARM/ SAFE | Maintained – Maintained | SAFE (down) – Opens ARM relay in ANDE 2 deploy circuit. |
| DS11 | Talkback, two-position | gray – Indicates ARM relay is closed. |
| ARM | gray bp | bp (default) – Indicates ARM relay is open. |
| S12 | Three-position toggle switch: | DEPLOY (up) – Closes DEPLOY relay in ANDE 2 deploy circuit (enables high current mode to NEA). |
| ANDE2 DEPLOY/ SAFE | Maintained (up) Default (center) Maintained (down) | SAFE (dn, ctr) – Opens DEPLOY relay in ANDE 2 deploy circuit. |
| DS12 | Talkback, two-position | gray – Indicates bus power to NEA. |
| NEA GOOD | gray bp | bp (default) – Indicates no power to NEA. |

STANDARD SWITCH PANEL 1 LAYOUT

(ASSY OPS/2JA/FIN) Page 3 of 4 pages

| | Device Type | Function |
|--------------------|------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------|
| DS13 | Event indicator, three-position | UP – Indicates that CAB PL3 power is being supplied to OIU 1. |
| | | bp – Indicates power is removed from OIU 1 and OIU 2. |
| | | DN – Indicates that AUX PLB power is being supplied to OIU 2. |
| S15 | Toggle switch, two-position | ON (up) – Applies power to TCS. |
| TCS | • | OFF (dn) – Removes power from TCS. |
| PWR | Maintained – Maintained | |
| DS15 | Event indicator, Two-position | gray – Indicates TCS is powered. |
| TCS PWR | | bp – Indicates TCS is not powered. |
| S17 | Three-position momentary switch: | DEPLOY (up) – Closes deploy relay in DRAGONSAT deploy circuit (enables high current mode to NEA). |
| D/S Deploy | Momentary – Maintained – Momentary | SAFE (dn, ctr) – Opens deploy relay in the DRAGONSAT deploy circuit. |
| DS17 | Talkback, two-position: | gray – Indicates D/S PREARM relay is closed and current is flowing to NEA device. |
| D/S NEA GOOD | gray bp | Barberpole – Indicates D/S PREARM is open. |
| S18 | Two-position toggle switch: | PREARM (up) – Closes PREARM relay in DRAGONSAT deploy circuit. Supplies power to SSPL 5510 safing latch solenoid, rotating to ARM position. |
| D/S PREARM | Maintained – Maintained | SAFE (down) – Opens PREARM relay and removes power from SSPL 5510 safing latch solenoid, rotating to safe position. |
| DS18 | Talkback, two-position: | gray – Indicates PREARM relay is closed and Pico-sat 1 is present. |
| D/S PICO 1 HERE | gray bp | bp – Indicates PREARM relay is open. |
| CB4 SW PWR 2 | Circuit breaker, 5 amp | closed (in) – Applies orbiter CAB PL 3 to SSP1 switches S16-S20, S22, and S23. Only S18 and S23 are wired. |
| | | open (out) – Removes power from SSP1 switches S16-S20, S22, and S23. |

STANDARD SWITCH PANEL 1 LAYOUT

| | Device Type | Function |
|---------------------|----------------------------------|--------------------------------------------------------------------------------------------------------|
| CB 3 PDIP1 PWR 1 | Circuit breaker, 5 amp | closed (in) – Applies orbiter CAB PL2 to PDIP DC PWR 1 outlet and redundant power to SSP1 S20 and S22. |
| | | open (out) – Removes power from PDIP DC PWR 1 outlet and redundant power from SSP1 S20 and S22. |
| S23 | Two-position toggle switch: | ARM (up) – Closes ground leg inhibit of SSPL 5510 firing circuit. |
| D/S ARM | Maintained – Maintained | SAFE (dn) – Opens ground leg inhibit of the firing circuit. |
| DS23 D/S PICO 2 | Talkback, two-position: | Gray – Indicates PREARM relay is closed and Pico-sat 2 is present. |
| HERE | gray bp | bp – Indicates PREARM relay is open. |
| S24 | Toggle switch, three-position | OIU 1 ON (up) – Provides CAB PL3 power to OIU 1. |
| | | OFF (ctr) – Removes power from OIU 1 and OIU 2. |
| OIU PWR | Maintained – | |
| | Maintained – Maintained | OIU 2 ON (dn) – Provides AUX PLB power to OIU 2. |

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STANDARD SWITCH PANEL 2 LAYOUT (ASSY OPS/2JA/FIN 1) Page 1 of 5 pages



(ASSY OPS/2JA/FIN 1)

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| | Device Type | Function |
|-------------------------------|--------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------|
| CB1 PDIP 2 PWR 2 | Circuit breaker, 5 amp | closed (in) – Applies orbiter power to PDIP DC PWR 2. |
| | | open (out) – Removes orbiter power from PDIP DC PWR 2. |
| CB2 | Circuit breaker, 5 amp: | closed (in) – Applies orbiter power to SSP2 switches S10, S14, S20, S21, S23, S24 and talkbacks DS10, DS14, DS21, DS23, DS24. |
| | | open (out) – Removes orbiter power from SSP2 switches S10, S14, S20, S21, S23, S24 and talkbacks DS10, DS14, DS21, DS23, DS24. |
| S3 KEEL 1 PWR (ICC) | Two-position toggle switch: Maintained – Maintained | up (ON) – Indicates power applied to Keel Camera 1. down (default) (OFF) – Indicates power removed from Keel Camera 1. |
| S4 KEEL 1 ILL PWR (ICC) | Two-position toggle switch: Maintained – | up (ON) – Indicates power applied to Keel Camera 1 illuminator. down (default) (OFF) – Indicates power removed from |
| | Maintained | Keel Camera 1 illuminator. |
| S6 KEEL 2 PWR (JLE) | Two-position toggle switch: | up (ON) – Indicates power applied to Keel Camera 2. down (default) (OFF) – Indicates power removed from |
| | Maintained – Maintained | Keel Camera 2. |
| S7 KEEL 2 ILL PWR (JLE) | Two-position toggle switch: | up (ON) – Indicates power applied to Keel Camera 2 illuminator. |
| | Maintained – Maintained | down (default) (OFF) – Indicates power removed from Keel Camera 2 illuminator. |
| S10 DRGNEYE PWR | Two-position | up (ON) – Indicates power applied to DRAGONEYE. |
| | Maintained – Maintained | down (default) (OFF) – Indicates power removed from DRAGONEYE. |
| DS10 DRGNEYE PWR | Talkback two-position: | gray – Indicates DRAGONEYE is powered. |
| | gray bp | |

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| | Device Type | Function |
|----------------------------|--------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| S12 C/L CAM PWR | Three-position toggle switch: Maintained – Maintained – Maintained | PRI ON – Applies CAB PL3 power to PRI C/L CAM. center – Removes power from PRI/SEC C/L CAM SEC ON – Applies CAB PL1 power to SEC C/L CAM. |
| S13 JLE HTR 1-2 ENA | Three-position toggle switch: Momentary – Maintained – Momentary | ENA (up) – Enables power from PL PRI MN C to PPSU 1 relays for JLE heaters 1 and 2. center – default switch position DSBL (dn) – Removes power from PPSU 1 relays for JLE heaters 1 and 2. |
| DS13 JLE HTR 1-2 ENA | Talkback three-position: UP bp DN | UP – Indicates PPSU 1 K8 (Sys A) relay is closed and power applied to downstream heater relays. bp (default) – Indicates PPSU 1 K8 (Sys A) relay is open and power removed from downstream power relays. DN – not wired |
| S14 JLE HTR 3-4 ENA | Three-position toggle switch: Momentary – Maintained – Momentary | ENA (up) – Enables power from PL PRI MN C to PPSU 1 relays for JLE heaters 3 and 4. center – default switch position DSBL (dn) – Removes power from PPSU 1 relays for JLE heaters 3 and 4. |
| DS14 JLE HTR 3-4 ENA | Talkback three-position: UP bp DN | UP – Indicates PPSU 1 K7 (Sys B) relay is closed and power applied to downstream heater relays. bp (default) – Indicates PPSU 1 K7 (Sys B) relay is open and power removed from downstream power relays. DN – not wired |
| S15 JLE HTR (#1) | Two-position toggle switch: Maintained – Maintained | ON (up) – Once heater power enabled, applies PL PRI MN C power to JLE heater 1 (for JLE). OFF (dn) – Default position. Removes power to JLE heater 1 (for JLE). |
| DS15 JLE HTR (#1) | Talkback two-position: gray bp | gray – Indicates PPSU 1 K1 relay is closed and power applied to JLE heater 1 (for JLE). bp (default) – Indicates PPSU 1 K1 relay is open and power removed from JLE heater 1 (for JLE). |

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| | Device Type | Function |
|----------------------------|-------------------------------|------------------------------------------------------------------------------------------------------------------------------|
| S16 | Two-position toggle switch: | ON (up) – Once heater power enabled, applies PL PRI MN C power to JLE heater 2 (for ICS-EF). |
| ICS-EF HTR (#2) | Maintained – Maintained | OFF (dn) – Default position. Removes power to JLE heater 2 (for ICS-EF). |
| DS16 ICS-EF HTR (#2) | Talkback two-position: | gray – Indicates PPSU 1 K2 relay is closed and power applied to JLE heater 2 (for ICS-EF). |
| | gray bp | bp (default) – Indicates PPSU 1 K2 relay is open and power removed from JLE heater 2 (for ICS-EF). |
| S17 | Three-position toggle switch: | ON (up) – Applies PL PRI MN C power to ICC-VLD PFRAM heaters. |
| ICC PFRAM | Momentary – | center (default) – default position |
| HTRS | Maintained – Momentary | OFF (dn) – Removes power from ICC-VLD PFRAM heaters. |
| DS17 | Talkback two-position: | gray – Indicates PPSU 2 K8 (Sys A) relay is closed and power applied to PFRAM heaters. |
| ICC PFRAM HTRS | gray bp | bp (default) – Indicates PPSU 2 K8 (Sys A) relay is open and power removed from PFRAM heaters. |
| S19 | Two-position toggle switch: | ENA (up) – Applies CAB PL 3 power to PPSU 1 and 2 A heaters |
| PPSU 1/2 HTR A | Maintained – Maintained | DSBL (dn) – Default position. Removes power from PPSU 1 and 2 A heaters. |
| CB3 | Circuit breaker, 5 amp: | closed (in) – Applies orbiter power to PDIP DC PWR 1 and powers the DRAGONSAT Deploy switch S17 on panel SSP 1. |
| PDIP 2 PWR 1 | | open (out) – Removes orbiter power from PDIP DC PWR 1 and removes power to DRAGONSAT Deploy switch S17 on panel SSP 1. |
| CB4 | Circuit breaker, 5 amp: | closed (in) – Applies orbiter power to SSP2 switches S13, S15 to S17, S19 and talkbacks DS13, DS15 to DS17. |
| | | open (out) – Removes orbiter power from SSP2 switches S13, S15 to S17, S19 and talkbacks DS13, DS15 to DS17. |
| S20 | Two-position toggle switch: | ENA (up) – Applies CAB PL 1 power to PPSU 1 and 2 B heaters. |
| PPSU 1/2 HTR B | Maintained – Maintained | DSBL (dn) – Default position. Removes power from PPSU 1 and 2 B heaters. |

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| | Device Type | Function |
|-------------------------|--------------------------------------------|-----------------------------------------------------------------------------------------------------|
| S21 | Three-position toggle switch: | ON (up) – Applies PL PRI MN C power to ICC-VLD P6 Battery heaters. |
| ICC BATT HTRS | Momentary – Maintained – Momentary | center (default) – default position |
| | | OFF (dn) – Removes power from ICC-VLD P6 Battery heaters. |
| DS21 | Talkback two-position: | gray – Indicates PPSU 2 K7 (Sys B) relay is closed and power applied to P6 Battery heaters. |
| ICC BATT HTRS | gray bp | bp (default) – Indicates PPSU 2 K7 (Sys B) relay is open and power removed from P6 Battery heaters. |
| S23 | Two-position toggle switch: | ON (up) – Once heater power enabled, applies PL PRI MN C power to JLE heater 3 (for SEDA-AP). |
| JLE SEDA-AP HTR (#3) | Maintained – Maintained | OFF (dn) – Default position. Removes power to JLE heater 3 (for SEDA-AP). |
| DS23 | Talkback two-position: | gray – Indicates PPSU 1 K4 relay is closed and power applied to JLE heater 3 (for SEDA-AP). |
| JLE SEDA-AP HTR (#3) | gray bp | bp (default) – Indicates PPSU 1 K4 relay is open and power removed from JLE heater 3 (for SEDA-AP). |
| S24 | Three-position toggle switch: | ON (up) – Once heater power enabled, applies PL PRI MN C power to JLE heater 4 (for MAXI). |
| JLE MAXI HTR (#4) | Maintained – Maintained – Maintained | center (default) – Removes power to JLE heater 4 (for MAXI). |
| | | OFF (dn) – Removes power to JLE heater 4 (for MAXI). |
| DS24 | Talkback two-position: | gray – Indicates power applied to JLE heater 4 (for MAXI). |
| JLE MAXI HTR (#4) | gray bp | bp (default) – Indicates power removed from JLE heater 4 (for MAXI). |

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MUS (LOW BACK PAIN – MUSCLE) QUESTIONNAIRE – _____ GMT

(ASSY OPS/2JA/FIN)

Page 1 of 1 page

Question 1 Did you experience pain today in the lower back? □ No □ Yes

If your answer is no, continue with question 8.

Question 2 Can you point out on the drawing where the pain was present?

Question 3

How serious was this pain? Mark the number.

2 3 4 5 6 7 8 9 10 1 unbearable no pain pain

Question 4

Is your back painful almost all the time? 🗆 No **Q** Yes

Question 5

What provokes your low back pain? Unknown Known If known, please give brief details

Question 6

Are you able to do something to relieve your low back pain? **No** □ Yes If yes, please give brief details

Question 7

Do you suffer from any of the following symptoms? Pins and needles □ No □ Yes If yes, where Numbness 🛛 No **Q** Yes If yes, where Change in bladder or bowel function during painful period? 🗆 No □ Yes If yes, what Other

Question 8

Have you been taking any pain medication? □ Yes



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ASSEMBLY OPERATIONS

Return on STS-121